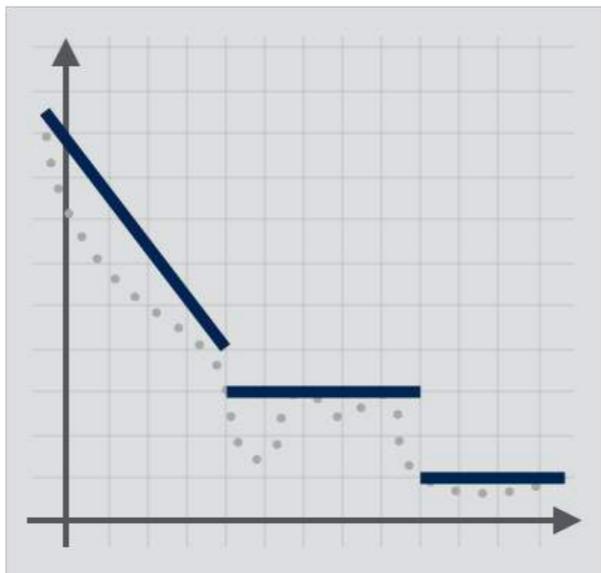


Abstract Interpretation for Liveness Properties

MPRI 2-6: Abstract Interpretation,
Application to Verification and Static Analysis



So far, we have focused on **using static analysis to avoid software failures**

The cost of software failure

- **Patriot MIM-104** failure, 25 February 1991
(death of 28 soldiers¹)
- **Ariane 5** failure, 4 June 1996
(cost estimated at more than 370 000 000 US\$²)
- **Toyota** electronic throttle control system failure, 2005
(at least 89 death³)
- **Heartbleed** bug in OpenSSL, April 2014
- the economic cost of software bugs is tremendous⁴
- ...

¹R. Skeel. "Roundoff Error and the Patriot Missile". SIAM News, volume 25, nr 4.

²M. Dowson. "The Ariane 5 Software Failure". Software Engineering Notes 22 (2): 84, March 1997.

³CBSNews. Toyota "Unintended Acceleration" Has Killed 89. 20 March 2014.

⁴NIST. Software errors cost U.S. economy \$59.5 billion annually. Tech. report, NIST Planning Report, 2002.

How can we avoid such failures?

- Choose a safe programming language.
C (low level) / Ada, Java, OCaml (high level)
yet, Ariane 5 software is written in Ada
- Carefully design the software.
many software development methods exist
yet, critical embedded software follow strict development processes
- Test the software extensively.
yet, the erroneous code was well tested. . . on Ariane 4
⇒ not sufficient!

We should use **formal methods**.

provide rigorous, mathematical insurance of correctness
may not prove everything, but give a precise notion of what is proved

This case triggered the first large scale static code analysis
(PolySpace Verifier, using abstract interpretation)

that is, for **proving Safety Properties**

Safety vs Liveness Properties

Trace properties

Safety properties for traces

- Idea:** a safety property P models that “nothing bad ever occurs”
- P is provable by exhaustive testing;
(observe the prefix trace semantics: $\mathcal{T}_P(\mathcal{I}) \subseteq P$)
 - P is disprovable by finding a single finite execution not in P .

Examples:

- any state property
- ordering: $P \stackrel{\text{def}}{=} \{ \text{no } b \text{ can appear w... but we can have c... (not a state property) \}$
- but termination: disproving requires...

Course 02

Liveness properties

Idea: liveness property $P \in \mathcal{P}(\Sigma^\infty)$

Liveness properties model that “something good eventually occurs”

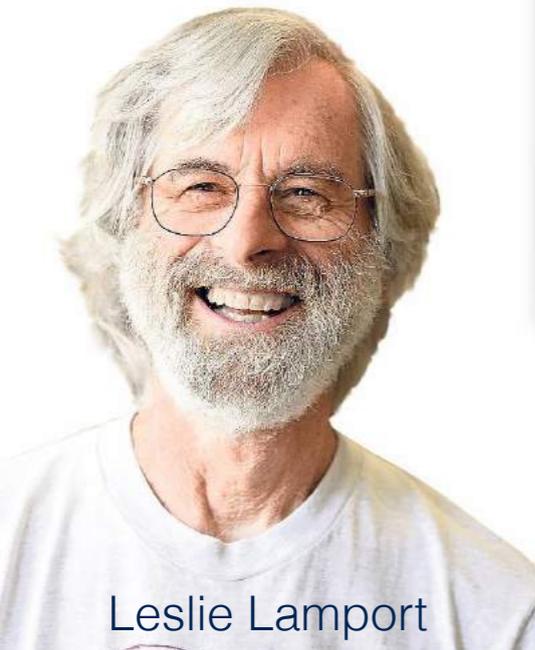
- P cannot be proved by testing
(if nothing good happens in a prefix execution, it can still happen in the rest of the execution)
- disproving P requires exhibiting an infinite execution not in P

Safety Properties

“something bad never happens”

“something good eventually happens”

Liveness Properties



Leslie Lamport

Liveness Properties

- **Guarantee Properties**

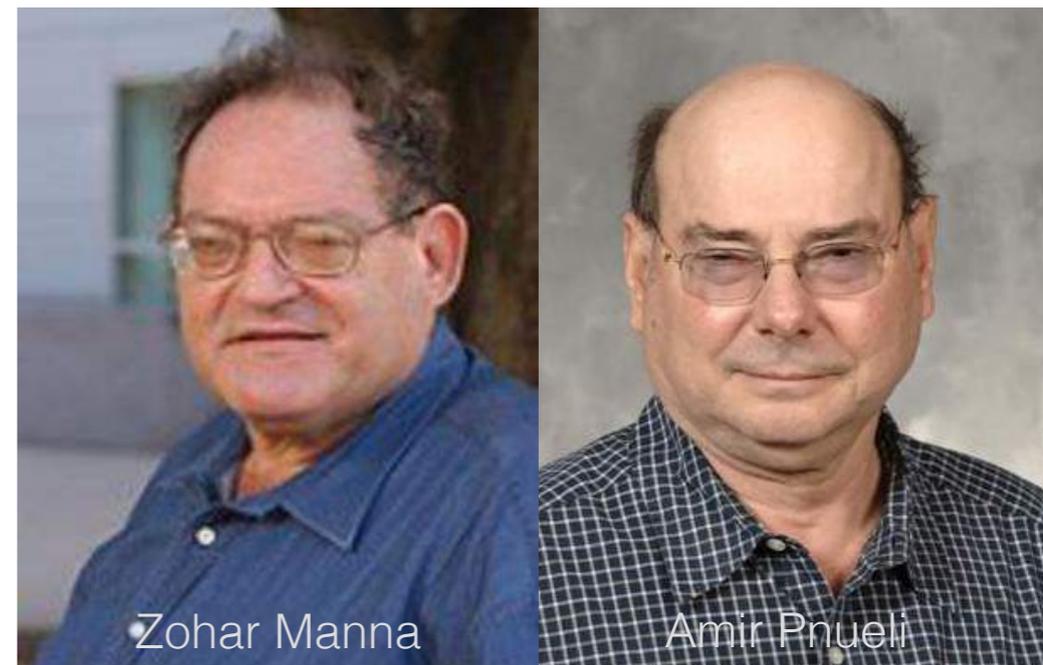
“something good eventually happens at least once”

- Example: Program Termination

- **Recurrence Properties**

“something good eventually happens infinitely often”

- Example: Starvation Freedom



Zohar Manna

Amir Pnueli

Program Termination

The Zune Bug

31 December 2008

unresponsive
systems

The screenshot shows a web browser window with the URL `techcrunch.com/2008/12/31/all-zune-30s-crapping-out/`. The page features the TechCrunch logo and navigation links for News, TCTV, and Events. A search bar is visible on the right. Below the navigation, there are links for Gadgets, Headline, Zune, and Feature. The main article title is "30GB Zunes all over the world fail en masse", posted by Matt Burns (@mjburnsy) on Dec 31, 2008. The article text describes a bug affecting 30GB Zunes, where they reset on their own at 2:00 AM and do not fully reboot. An update states that the solution is to let the Zune run out of battery and charge it.

30GB Zunes all over the world fail en masse

Posted Dec 31, 2008 by [Matt Burns \(@mjburnsy\)](#)

It seems that a random bug is affecting a bunch, if not every, 30GB Zunes. Real early this morning, a bunch of Zune 30s just stopped working. No official word from Redmond on this one yet but we might have a gadget Y2K going on here. [Fan boards](#) and [support forums](#) all have the same mantra saying that at 2:00 AM this morning, the Zune 30s reset on their own and doesn't fully reboot. We're sure Microsoft will get flooded with angry Zune owners as soon as the phone lines open up for the last time in 2008. More as we get it.

Update 2: [The solution](#) is ... kind of weak: let your Zune run out of battery and it'll be fixed when you wake up tomorrow and charge it.

The Zune Bug

31 December 2008

unresponsive systems

30GB Zunes all over the world

techcrunch.com/2008/12/31/all-zune

News TCTV Events

DISRUPT Register Now to Save £300 on Disrupt Europe: London

Gadgets | **Headline** | Zune | Feature

30GB Zunes all over the world

Posted Dec 31, 2008 by [Matt Burns \(@mjburnsy\)](#)

It seems that a random bug is affecting a bunch, a bunch of Zune 30s just stopped working. No one might have a gadget Y2K going on here. [Fan boards](#) have the same mantra saying that at 2:00 AM this morning the devices will fully reboot. We're sure Microsoft will get flooded with support lines open up for the last time in 2008. More as we learn.

Update 2: [The solution](#) is ... kind of weak: let your Zune wake up tomorrow and charge it.

Zune bug explained in detail

techcrunch.com/2008/12/31/zune-bug-explained-in-detail/

Zune bug explained in detail

Posted Dec 31, 2008 by [Devin Coldewey](#)

Share 10 | Share 0 | Tweet 2

Next Story

Earlier today, the sound of [thousands of Zune owners crying out in terror](#) made ripples across the blogosphere. The response from Microsoft is to [wait until tomorrow](#) and all will be well. You're probably wondering, what kind of bug fixes itself?

Well, I've got the code here and it's very simple, really; if you've taken an introductory programming class, you'll see the error right away.

```
year = ORIGINYEAR; /* = 1980 */
while (days > 365)
{
    if (IsLeapYear(year))
    {
        if (days > 366)
        {
            days -= 366;
            year += 1;
        }
    }
    else
    {
        days -= 365;
        year += 1;
    }
}
```

You can see the details [here](#), but the important bit is that today, the day count is 366. As you

Follow

Apache HTTP Server

Versions <2.3.3

denial-of-service
attacks

The screenshot shows a web browser window at cve.mitre.org. The page features the CVE logo and navigation links for 'CVE List', 'CNA's', 'Board', 'About', and 'News & Blog'. A search bar and navigation menu are visible, with a total of 97,475 CVE entries. The main content area displays the details for CVE-2009-1890, including a description of a denial-of-service vulnerability in the Apache HTTP Server and a link to the NVD for more information.

CVE-2009-1890 [Learn more at National Vulnerability Database \(NVD\)](#)
• CVSS Severity Rating • Fix Information • Vulnerable Software Versions • SCAP Mappings • CPE Information

Description

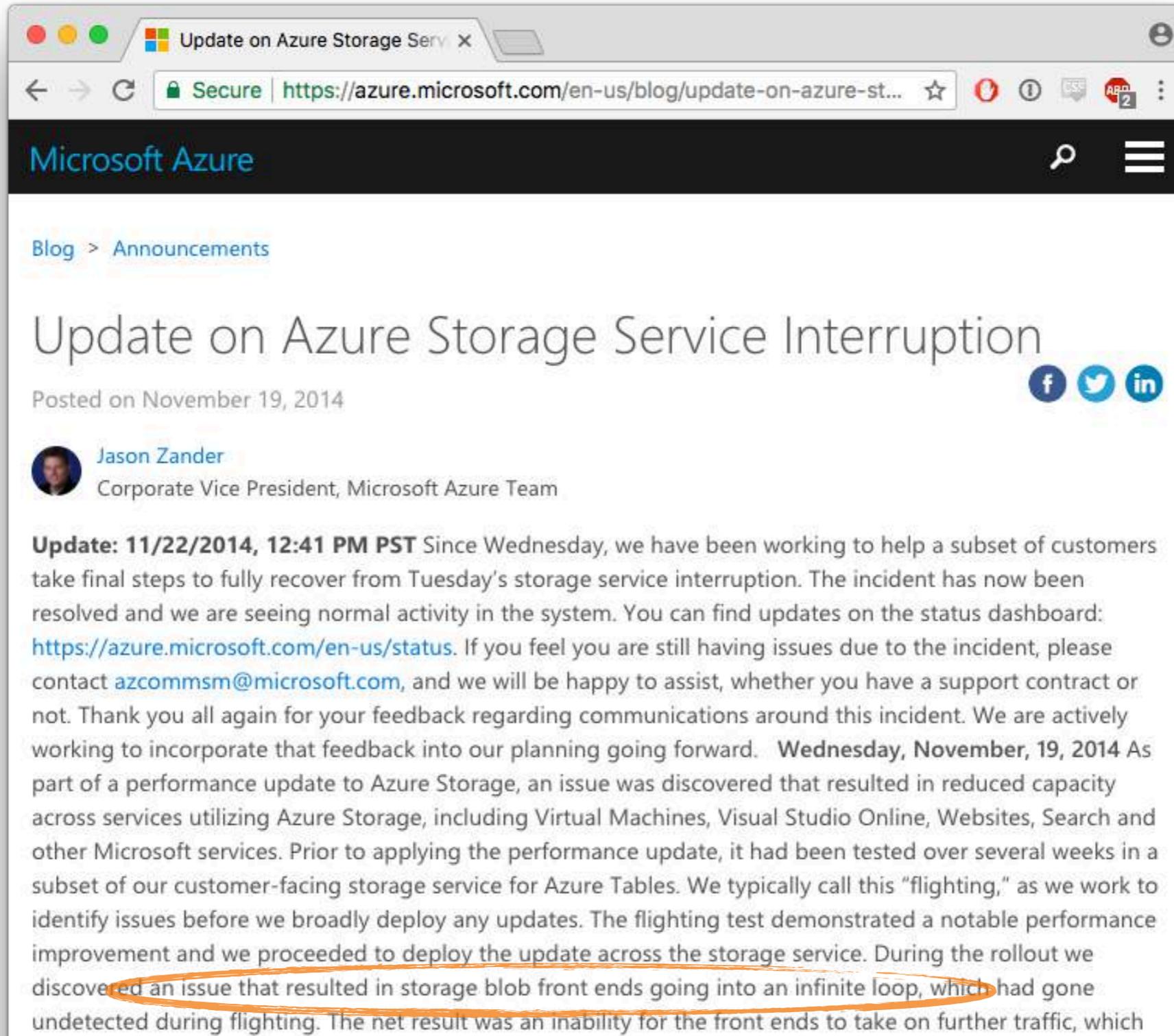
The stream_reqbody_cl function in mod_proxy_http.c in the mod_proxy module in the Apache HTTP Server before 2.3.3, when a reverse proxy is configured, does not properly handle an amount of streamed data that exceeds the Content-Length value, which allows remote attackers to cause a denial of service (CPU consumption) via crafted requests.

References

Azure Storage Service

19 November 2014

Service interruptions



The screenshot shows a web browser window displaying a blog post from Microsoft Azure. The browser's address bar shows the URL <https://azure.microsoft.com/en-us/blog/update-on-azure-st...>. The page header includes the Microsoft Azure logo and navigation icons. The main content area features the title "Update on Azure Storage Service Interruption" and the author "Jason Zander, Corporate Vice President, Microsoft Azure Team". The post text begins with an update on November 22, 2014, and describes a service interruption caused by a performance update. A specific sentence in the text is circled in orange: "an issue that resulted in storage blob front ends going into an infinite loop, which had gone undetected during flighting."

Update on Azure Storage Service Interruption

Posted on November 19, 2014

Jason Zander
Corporate Vice President, Microsoft Azure Team

Update: 11/22/2014, 12:41 PM PST Since Wednesday, we have been working to help a subset of customers take final steps to fully recover from Tuesday's storage service interruption. The incident has now been resolved and we are seeing normal activity in the system. You can find updates on the status dashboard: <https://azure.microsoft.com/en-us/status>. If you feel you are still having issues due to the incident, please contact azcommmsm@microsoft.com, and we will be happy to assist, whether you have a support contract or not. Thank you all again for your feedback regarding communications around this incident. We are actively working to incorporate that feedback into our planning going forward. **Wednesday, November 19, 2014** As part of a performance update to Azure Storage, an issue was discovered that resulted in reduced capacity across services utilizing Azure Storage, including Virtual Machines, Visual Studio Online, Websites, Search and other Microsoft services. Prior to applying the performance update, it had been tested over several weeks in a subset of our customer-facing storage service for Azure Tables. We typically call this "flighting," as we work to identify issues before we broadly deploy any updates. The flighting test demonstrated a notable performance improvement and we proceeded to deploy the update across the storage service. During the rollout we discovered an issue that resulted in storage blob front ends going into an infinite loop, which had gone undetected during flighting. The net result was an inability for the front ends to take on further traffic, which

Potential and Definite Termination

Definition

A program with trace semantics $\mathcal{M} \in \mathcal{P}(\Sigma^\infty)$ **may terminate** if and only if $\mathcal{M} \cap \Sigma^* \neq \emptyset$

Definition

A program with trace semantics $\mathcal{M} \in \mathcal{P}(\Sigma^\infty)$ **must terminate** if and only if $\mathcal{M} \subseteq \Sigma^*$

Finite trace semantics | Traces and trace operations

Traces

Trace: sequence of elements from Σ

- ϵ : empty trace (unique)
- σ : trace of length 1 (assimilated to a state)
- $\sigma_0, \dots, \sigma_{n-1}$: trace of length n
- Σ^n : the set of traces of length n
- $\Sigma^{\leq n} \stackrel{\text{def}}{=} \bigcup_{i \leq n} \Sigma^i$: the set of traces of length at most n
- $\Sigma^* \stackrel{\text{def}}{=} \bigcup_{i \in \mathbb{N}} \Sigma^i$: the set of finite traces
- state sets $\mathcal{I}, \mathcal{F} \subseteq \Sigma$ are also sets of traces, of length 1
- transition relation $\tau \subseteq \Sigma \times \Sigma$ is also a set of traces, of length 2

Course 02 | Program Semantics and Properties | Antoine Miné | p. 41 / 102

In *absence of non-determinism*, potential and definite termination coincide

Definite Termination

Ranking Functions



Alan Turing

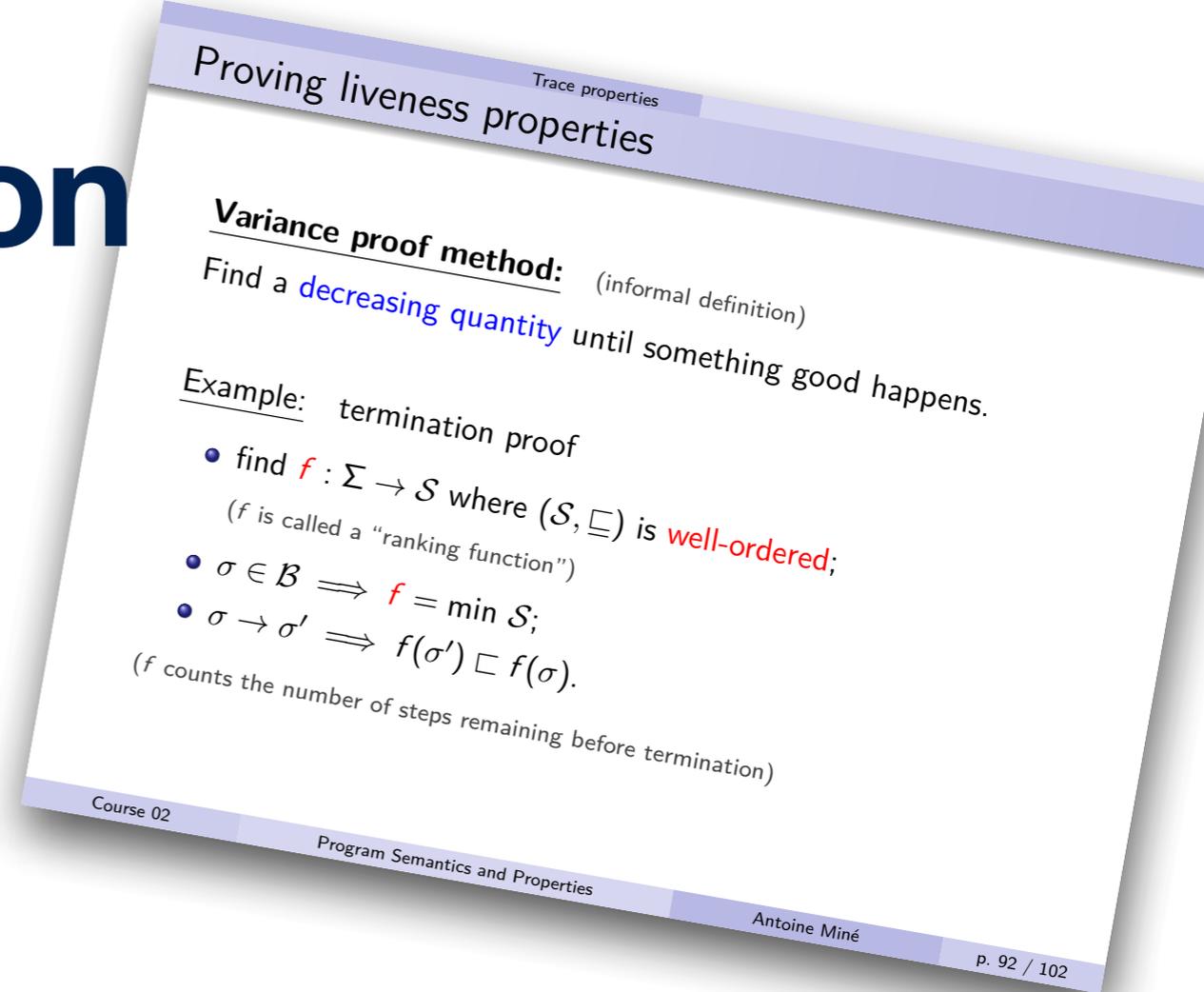


Robert W. Floyd

Definition

Given a transition system $\langle \Sigma, \tau \rangle$, a **ranking function** is a partial function $f: \Sigma \rightarrow \mathcal{W}$ from the set of program states Σ into a well-ordered set $\langle \mathcal{W}, \leq \rangle$ whose value *strictly decreases* through transitions between states, that is, $\forall \sigma, \sigma' \in \text{dom}(f): (\sigma, \sigma') \in \tau \Rightarrow f(\sigma') < f(\sigma)$

The best known *well-ordered sets* are **naturals** $\langle \mathbb{N}, \leq \rangle$ and **ordinals** $\langle \mathbb{O}, \leq \rangle$



Ranking Functions

Example

```
1  $x \leftarrow [-\infty, +\infty]$ 
  while 2  $(1 - x < 0)$  do
    3  $x \leftarrow x - 1$ 
  od4
```

Language syntax Introduction

```
 ${}^l\text{stat}^l ::= {}^lX \leftarrow \text{exp}^l$  (assignment)
          |  $\text{if } \text{exp} \bowtie 0 \text{ then } {}^l\text{stat}^l$  (conditional)
          |  $\text{while } \text{exp} \bowtie 0 \text{ do } {}^l\text{stat}^l \text{ done}^l$  (loop)
          |  $\text{stat}; {}^l\text{stat}^l$  (sequence)
 $\text{exp} ::= X$  (variable)
        |  $-\text{exp}$  (negation)
        |  $\text{exp} \diamond \text{exp}$  (binary operation)
        |  $c$  (constant  $c \in \mathbb{Z}$ )
        |  $[c, c']$  (random input,  $c, c' \in \mathbb{Z} \cup \{\pm\infty\}$ )
```

Simple structured, numeric language

- $X \in \mathbb{V}$, where \mathbb{V} is a finite set of **program variables**
- $\ell \in \mathcal{L}$, where \mathcal{L} is a finite set of **control points**
- numeric expressions: $\bowtie \in \{=, \leq, \dots\}$, $\diamond \in \{+, -, \times, /\}$
- **random inputs**: $X \leftarrow [c, c']$
model environment, parametric programs, unknown functions, ...

Course 02 Program Semantics and Properties Antoine Miné p. 3 / 102

Ranking Functions

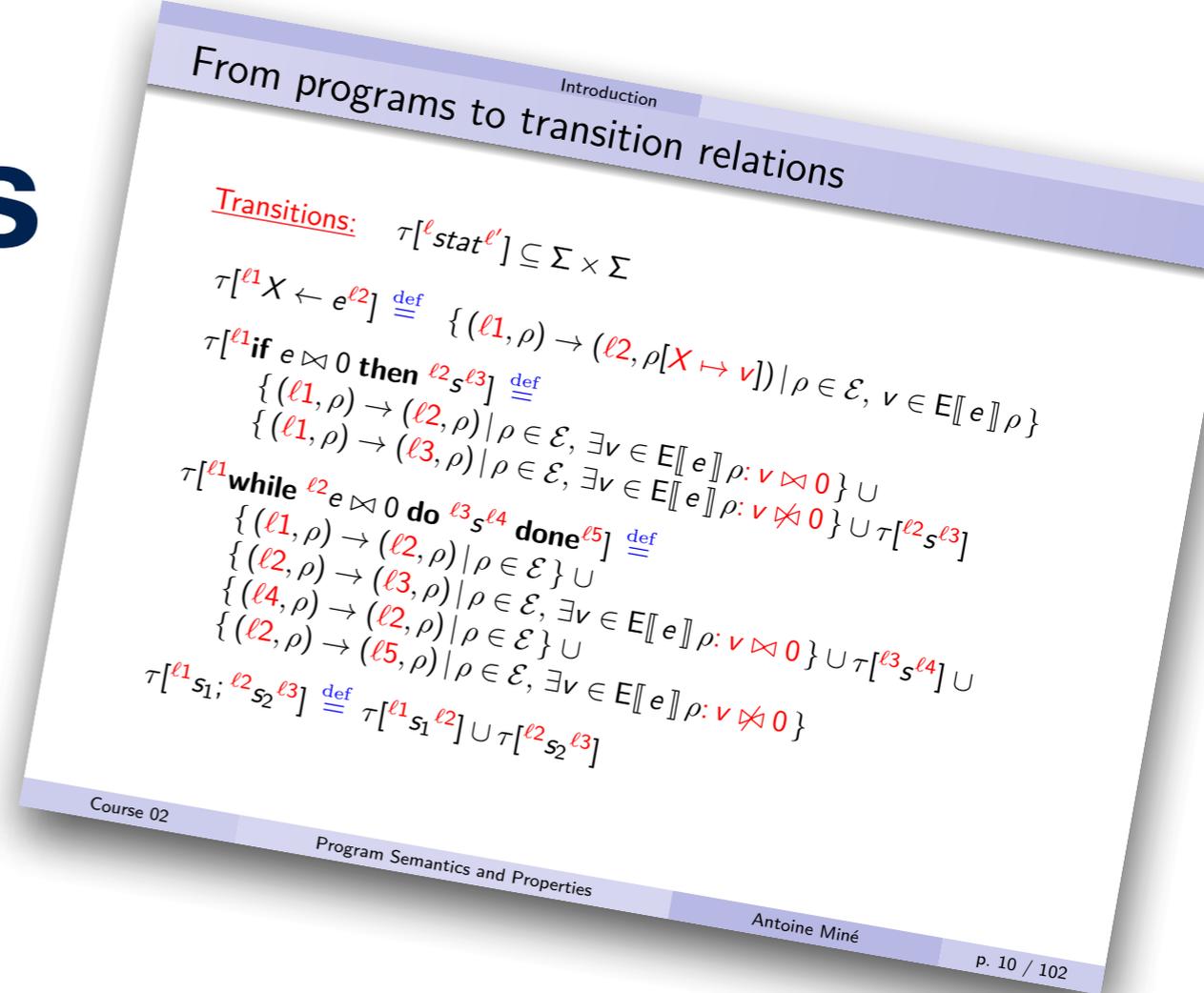
Example (continue)

```

1x ← [-∞, +∞]
while 2(1 - x < 0) do
    3x ← x - 1
od4
    
```

$$\Sigma \stackrel{\text{def}}{=} \{ \mathbf{1,2,3,4} \} \times \mathcal{E}$$

$$\begin{aligned} \tau \stackrel{\text{def}}{=} & \{ (\mathbf{1}, \rho) \rightarrow (\mathbf{2}, \rho[X \mapsto v]) \mid \rho \in \mathcal{E}, v \in \mathbb{Z} \} \\ & \cup \{ (\mathbf{2}, \rho) \rightarrow (\mathbf{3}, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[[1 - x]]\rho : v < 0 \} \\ & \cup \{ (\mathbf{3}, \rho) \rightarrow (\mathbf{2}, \rho[X \mapsto v]) \mid \rho \in \mathcal{E}, v \in E[[x - 1]]\rho \} \\ & \cup \{ (\mathbf{2}, \rho) \rightarrow (\mathbf{4}, \rho) \mid \rho \in \mathcal{E}, \exists v \in E[[1 - x]]\rho : v \neq 0 \} \end{aligned}$$



Ranking Functions

Example (continue)

```
1x ← [-∞, +∞]  
while 2(1 - x < 0) do  
    3x ← x - 1  
od4
```

Most obvious ranking function:

a mapping $f: \Sigma \rightarrow \mathbb{Q}$

from each program state

to

(a well-chosen upper bound on)

the number of steps until termination



Alan Turing



Robert W. Floyd

Ranking Functions

Example (continue)

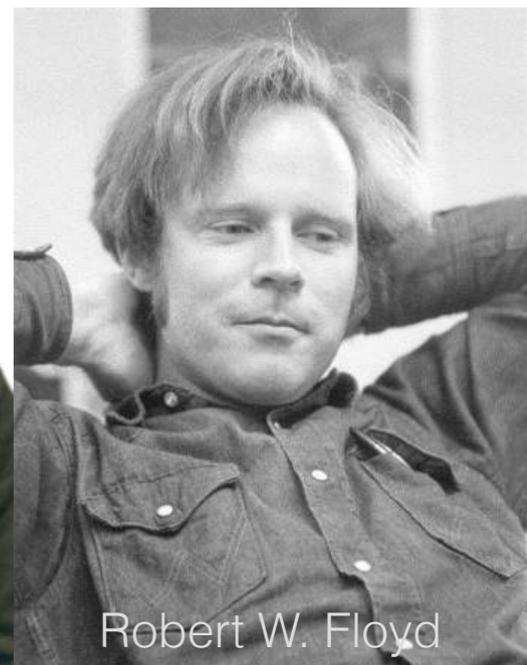
```
1x ← [-∞, +∞]
while 2(1 - x < 0) do
    3x ← x - 1
od4
```

We define the ranking function $f: \Sigma \rightarrow \mathbb{O}$ by partitioning with respect to the program control points, i.e., $f: \mathcal{L} \rightarrow (\mathcal{E} \rightarrow \mathbb{O})$

$$\begin{aligned} f(\mathbf{4}) &\stackrel{\text{def}}{=} \lambda\rho.0 \\ f(\mathbf{2}) &\stackrel{\text{def}}{=} \lambda\rho. \begin{cases} 1 & 1 - \rho(x) \not< 0 \\ 2\rho(x) - 1 & 1 - \rho(x) < 0 \end{cases} \\ f(\mathbf{3}) &\stackrel{\text{def}}{=} \lambda\rho. \begin{cases} 2 & 2 - \rho(x) \not< 0 \\ 2\rho(x) - 2 & 2 - \rho(x) < 0 \end{cases} \\ f(\mathbf{1}) &\stackrel{\text{def}}{=} \lambda\rho.\omega \end{aligned}$$



Alan Turing



Robert W. Floyd

Potential Termination

Potential Ranking Functions

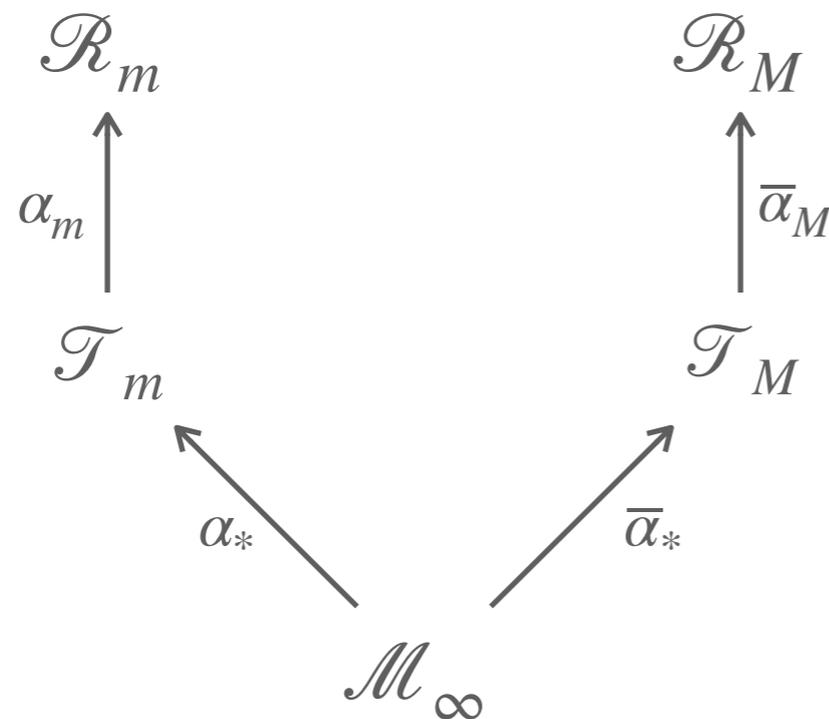
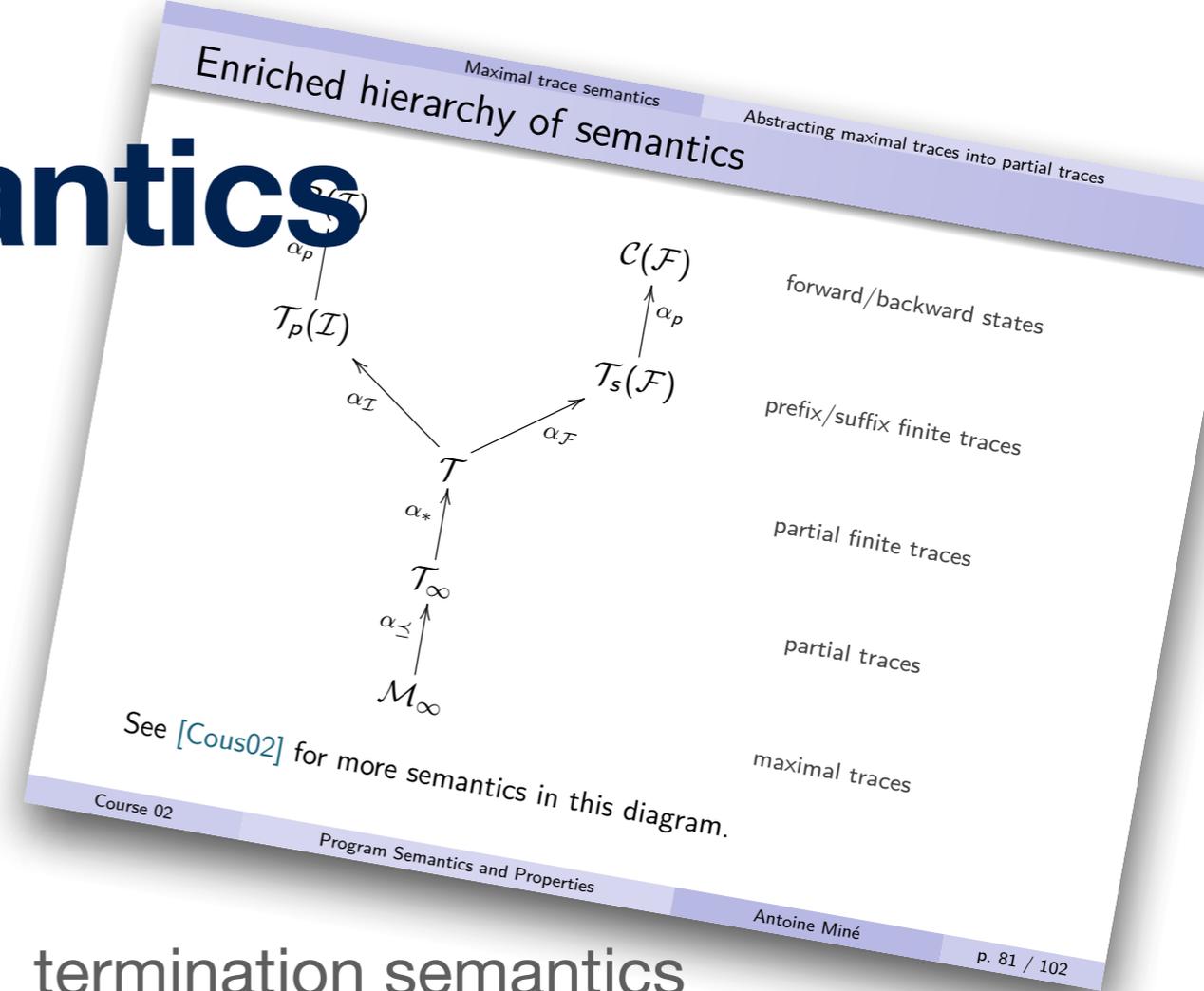
For proving potential termination, we use a *weaker* notion of ranking function, which *decreases along at least one transition* during program execution

Definition

Given a transition system $\langle \Sigma, \tau \rangle$, a **potential ranking function** is a partial function $f: \Sigma \rightarrow \mathcal{W}$ from the set of states Σ into a well-ordered set $\langle \mathcal{W}, \leq \rangle$ whose value *strictly decreases* through at least one transitions from each state, that is, $\forall \sigma \in \text{dom}(f): (\exists \bar{\sigma} \in \text{dom}(f): (\sigma, \bar{\sigma}) \in \tau) \Rightarrow \exists \sigma' \in \text{dom}(f): (\sigma, \sigma') \in \tau \wedge f(\sigma') < f(\sigma)$

Termination Semantics

Hierarchy of Semantics

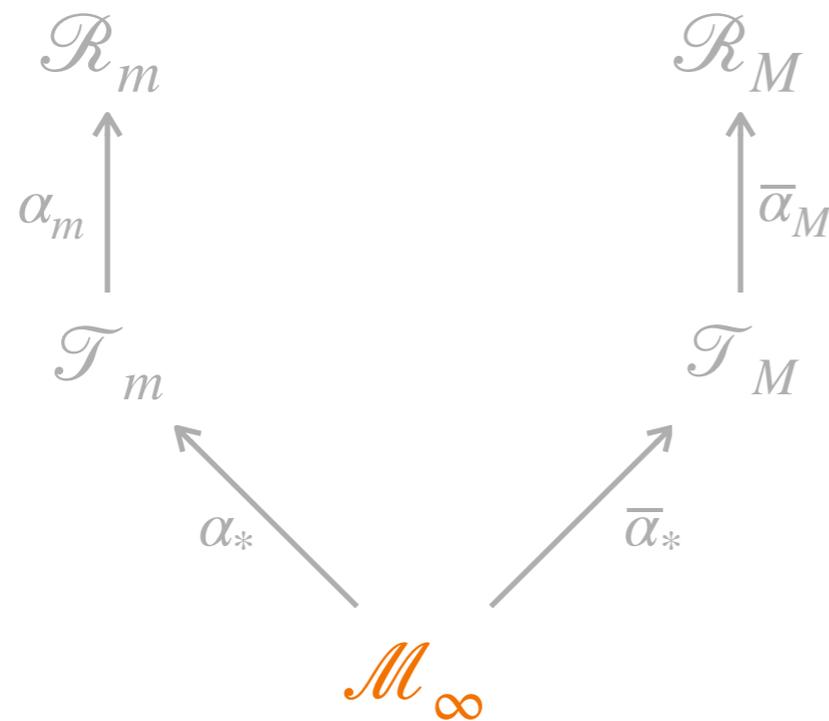
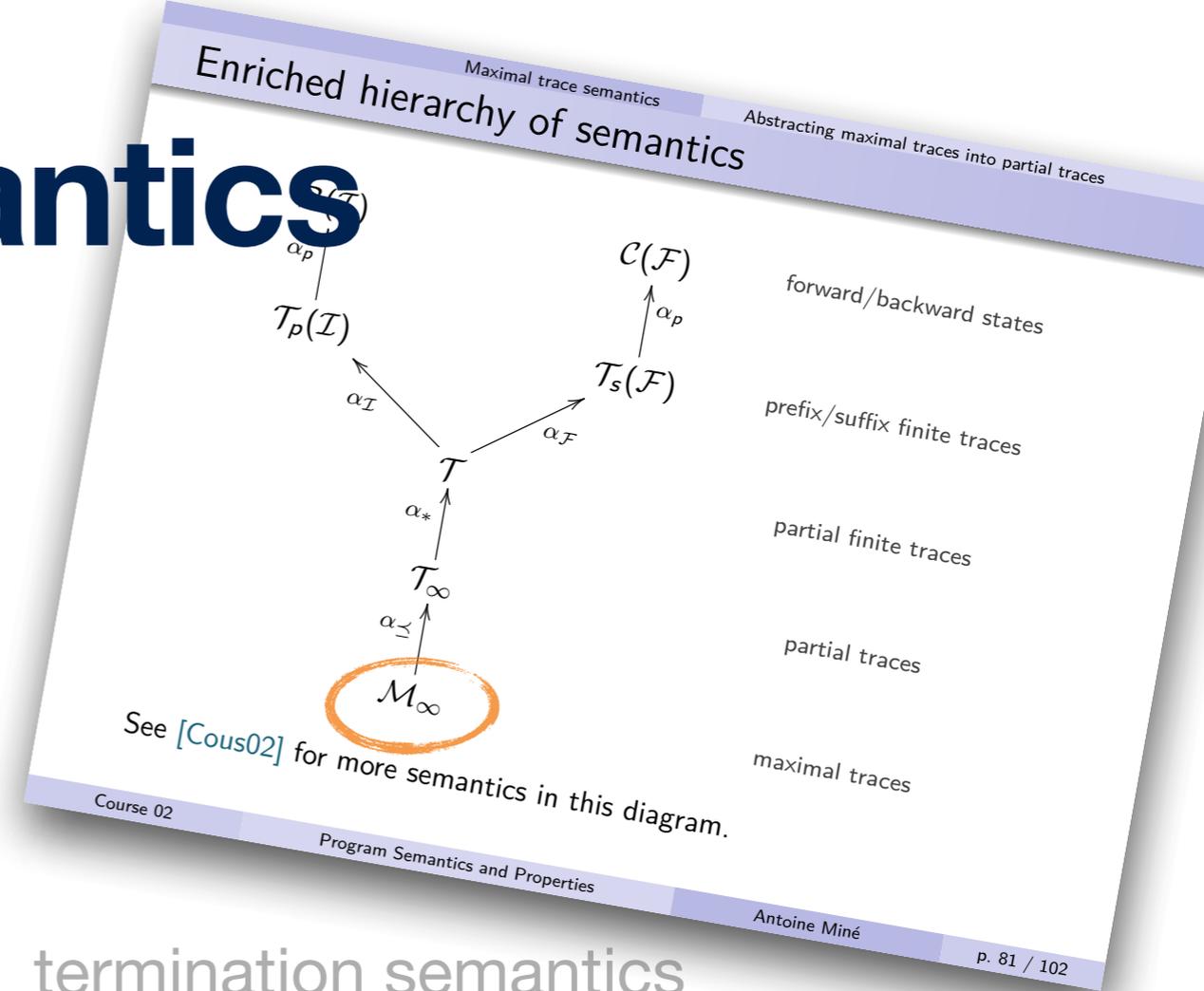


termination semantics

termination trace semantics

maximal trace semantics

Hierarchy of Semantics



termination semantics

termination trace semantics

maximal trace semantics

Maximal Trace Semantics

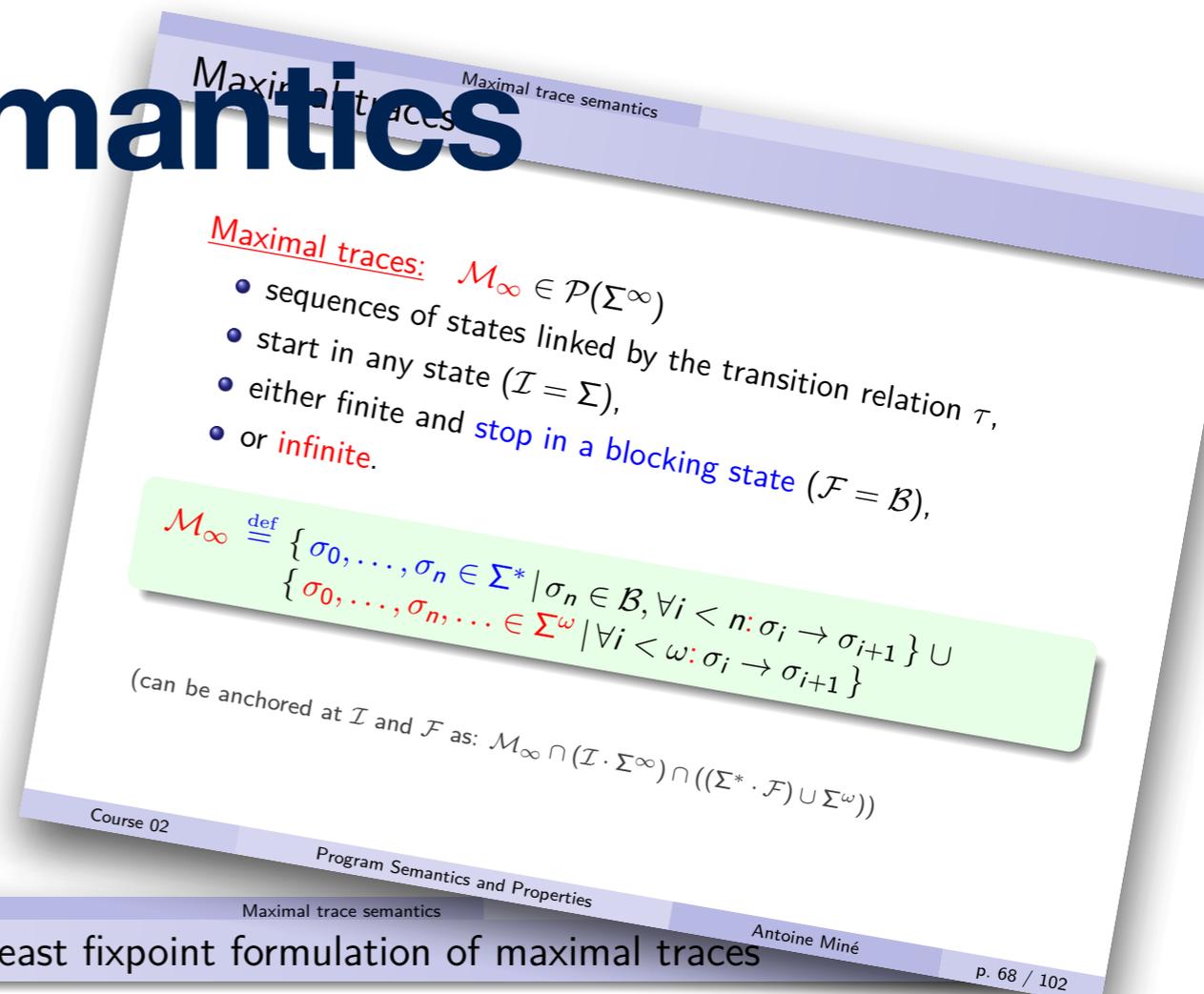
Example

```
while 1([-∞, +∞] ≠ 0) do
  2skip
od3
```

$$\Sigma \stackrel{\text{def}}{=} \{\mathbf{1}, \mathbf{2}, \mathbf{3}\} \times \mathcal{E}$$

$$\tau \stackrel{\text{def}}{=} \left\{ \begin{array}{l} (\mathbf{1}, \rho) \rightarrow (\mathbf{2}, \rho) \mid \rho \in \mathcal{E} \\ (\mathbf{2}, \rho) \rightarrow (\mathbf{1}, \rho) \mid \rho \in \mathcal{E} \\ (\mathbf{1}, \rho) \rightarrow (\mathbf{3}, \rho) \mid \rho \in \mathcal{E} \end{array} \right\}$$

$$\mathcal{M}_\infty \stackrel{\text{def}}{=} \left\{ \begin{array}{l} (\mathbf{1}, \rho)(\mathbf{2}, \rho)^*(\mathbf{3}, \rho) \mid \rho \in \mathcal{E} \\ (\mathbf{1}, \rho)(\mathbf{2}, \rho)^\omega \mid \rho \in \mathcal{E} \end{array} \right\}$$



Least fixpoint formulation of maximal traces

Idea: To get a **least fixpoint** formulation for whole \mathcal{M}_∞ , merge finite and infinite maximal trace least fixpoint forms.

Fixpoint fusion

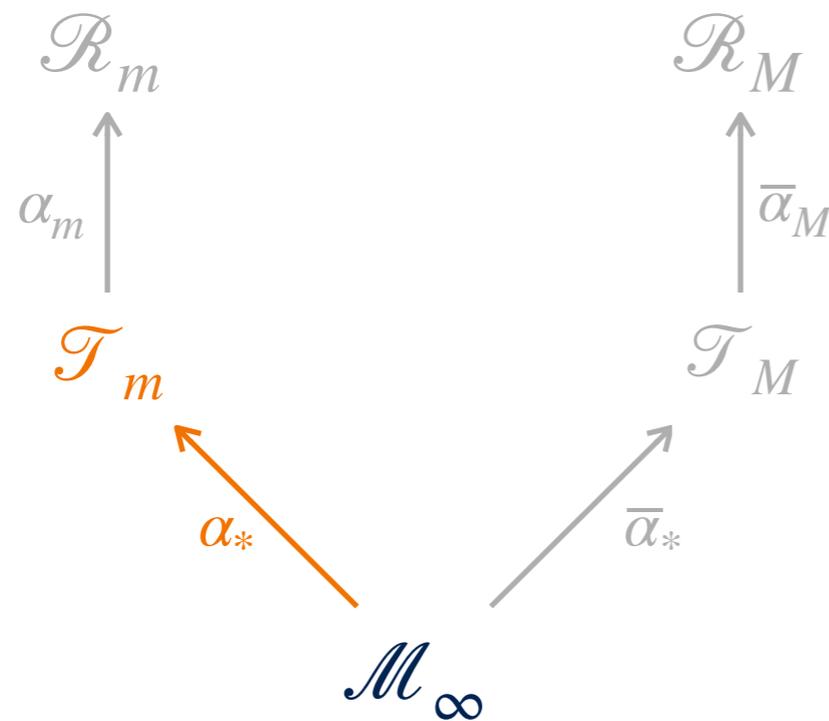
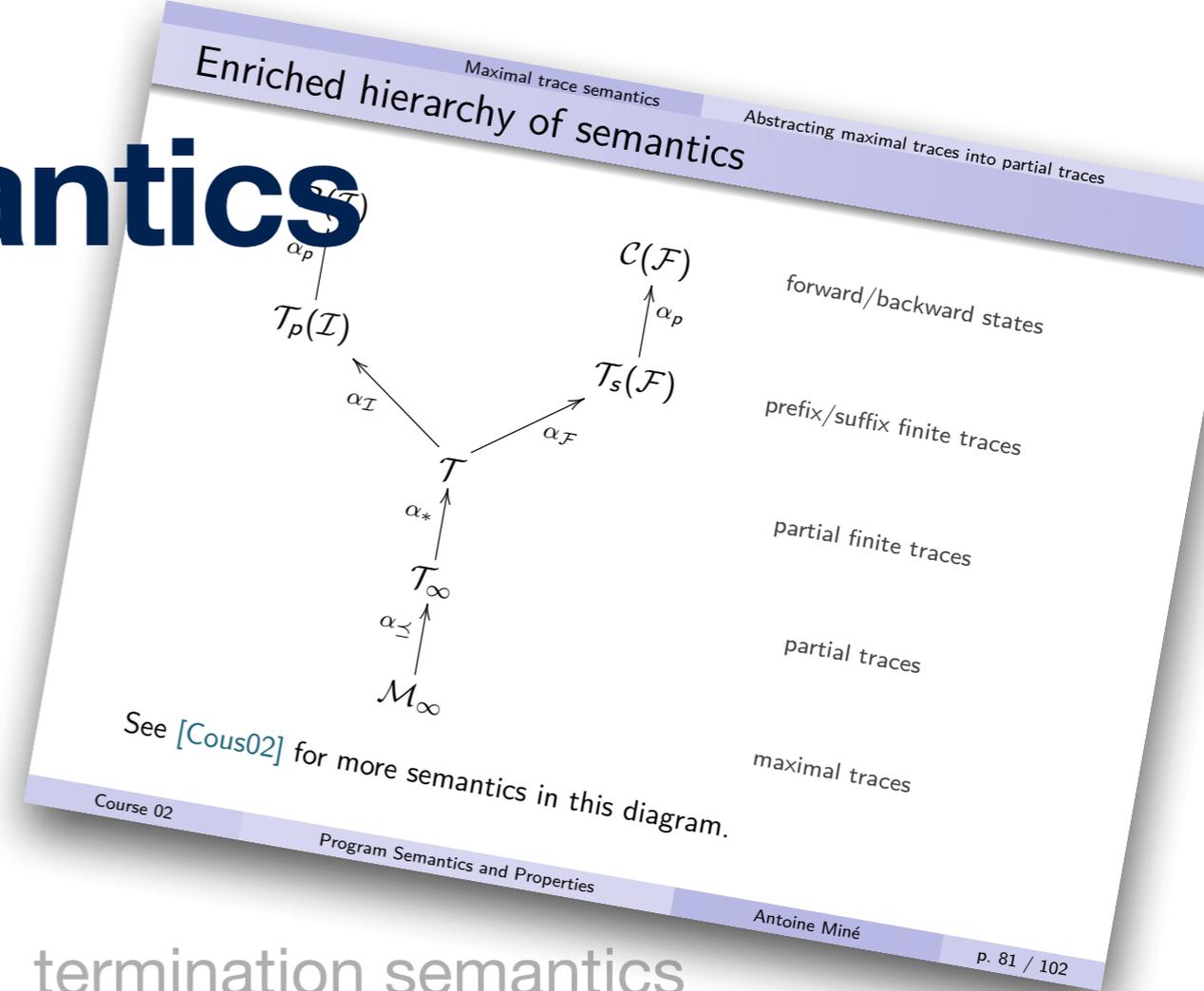
$\mathcal{M}_\infty \cap \Sigma^*$ is best defined on $(\mathcal{P}(\Sigma^*), \subseteq, \cup, \cap, \emptyset, \Sigma^*)$.
 $\mathcal{M}_\infty \cap \Sigma^\omega$ is best defined on $(\mathcal{P}(\Sigma^\omega), \supseteq, \cap, \cup, \Sigma^\omega, \emptyset)$, the **dual lattice** (we transform the greatest fixpoint into a least fixpoint!)

We mix them into a **new** complete lattice $(\mathcal{P}(\Sigma^\infty), \subseteq, \sqcup, \sqcap, \perp, \top)$:

- $A \sqsubseteq B \stackrel{\text{def}}{\iff} (A \cap \Sigma^*) \subseteq (B \cap \Sigma^*) \wedge (A \cap \Sigma^\omega) \supseteq (B \cap \Sigma^\omega)$
- $A \sqcup B \stackrel{\text{def}}{=} ((A \cap \Sigma^*) \cup (B \cap \Sigma^*)) \cup ((A \cap \Sigma^\omega) \cap (B \cap \Sigma^\omega))$
- $A \sqcap B \stackrel{\text{def}}{=} ((A \cap \Sigma^*) \cap (B \cap \Sigma^*)) \cup ((A \cap \Sigma^\omega) \cup (B \cap \Sigma^\omega))$
- $\perp \stackrel{\text{def}}{=} \Sigma^\omega$
- $\top \stackrel{\text{def}}{=} \Sigma^*$

In this lattice, $\mathcal{M}_\infty = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \cap T$.
 (proof on next slides)

Hierarchy of Semantics



termination semantics

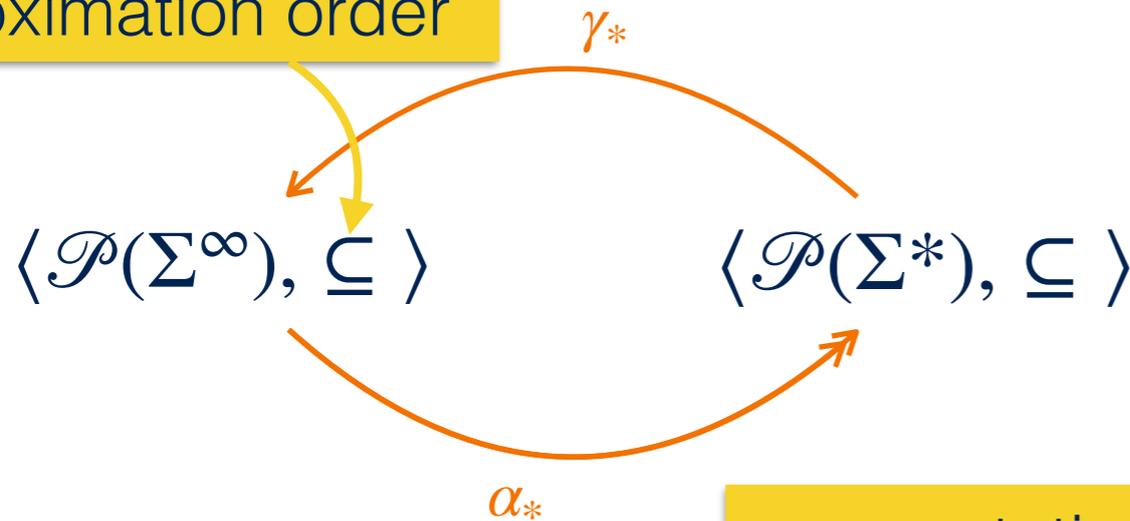
termination trace semantics

maximal trace semantics

Potential Termination Trace Semantics

Potential Termination Abstraction

approximation order



computational order

$$\alpha_*(T) \stackrel{\text{def}}{=} T \cap \Sigma^*$$

$$\gamma_*(T) \stackrel{\text{def}}{=} T \cup \Sigma^\omega$$

Example:

$$\alpha_*({ab, aba, bb, ba^\omega}) = \{ab, aba, bb\}$$

Galois connections

Given two posets (C, \leq) and (A, \sqsubseteq) , the pair $(\alpha : C \rightarrow A, \gamma : A \rightarrow C)$ is a **Galois connection** iff:

$$\forall a \in A, c \in C, \alpha(c) \sqsubseteq a \iff c \leq \gamma(a)$$

which is noted $(C, \leq) \xrightleftharpoons[\alpha]{\gamma} (A, \sqsubseteq)$.

- α is the **upper adjoint** or **abstraction**; A is the abstract domain.
- γ is the **lower adjoint** or **concretization**; C is the concrete domain.

Course 01 Order Theory Antoine Miné p. 48 / 69

Least fixpoint formulation of maximal traces

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Fixpoint fusion

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 $\mathcal{M}_\infty \cap \Sigma^\omega$ is best defined on $(\mathcal{P}(\Sigma^\omega), \supseteq, \cap, \cup, \Sigma^\omega, \emptyset)$, the **dual lattice**
 (we transform the greatest fixpoint into a least fixpoint!)

We mix them into a **new** complete lattice $(\mathcal{P}(\Sigma^\infty), \sqsubseteq, \cup, \cap, \perp, \top)$:

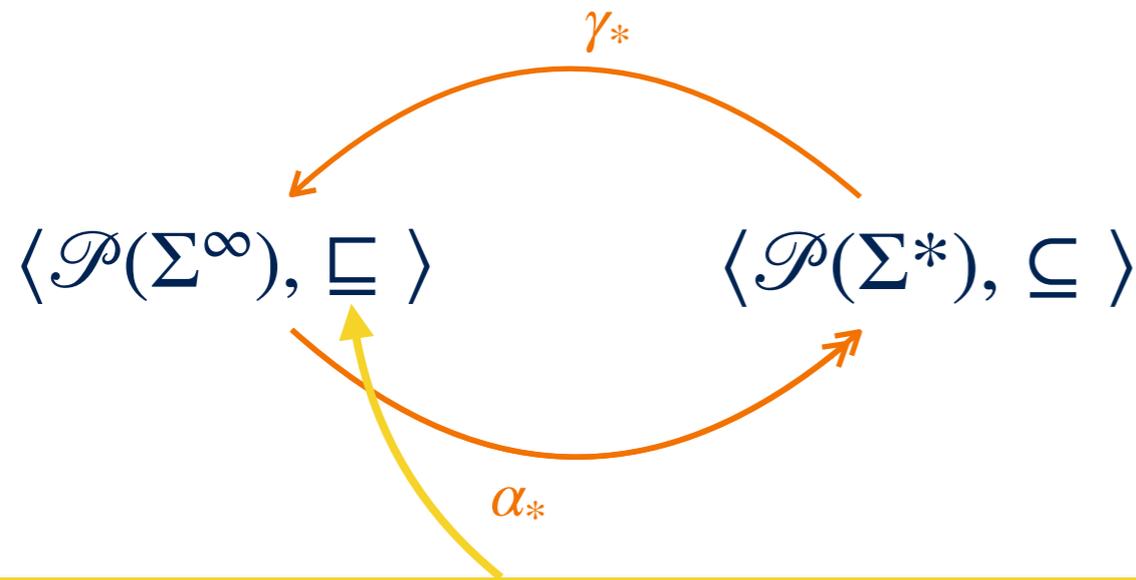
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- $A \cap B \stackrel{\text{def}}{=} ((A \cap \Sigma^*) \cap (B \cap \Sigma^*)) \cup ((A \cap \Sigma^\omega) \cup (B \cap \Sigma^\omega))$
- $\perp \stackrel{\text{def}}{=} \Sigma^\omega$
- $\top \stackrel{\text{def}}{=} \Sigma^*$

In this lattice, $\mathcal{M}_\infty = \text{lfp } F_s$ where $F_s(T) \stackrel{\text{def}}{=} B \cup T \cap T$.

(proof on next slides)

Potential Termination Trace Semantics

Finite Trace Abstraction



approximation and computational order coincide

$$\alpha_*(T) \stackrel{\text{def}}{=} T \cap \Sigma^*$$

$$\gamma_*(T) \stackrel{\text{def}}{=} T$$

Galois connections

Given two posets (C, \leq) and (A, \sqsubseteq) , the pair $(\alpha : C \rightarrow A, \gamma : A \rightarrow C)$ is a **Galois connection** iff:

$$\forall a \in A, c \in C, \alpha(c) \sqsubseteq a \iff c \leq \gamma(a)$$

which is noted $(C, \leq) \xleftrightarrow[\alpha]{\gamma} (A, \sqsubseteq)$.

- α is the **upper adjoint** or **abstraction**; A is the abstract domain.
- γ is the **lower adjoint** or **concretization**; C is the concrete domain.

Course 01 Order Theory Antoine Miné p. 48 / 69

Finite trace abstraction

Finite partial traces \mathcal{T} are an **abstraction** of all partial traces \mathcal{T}_∞ (forget about infinite executions)

We have a **Galois embedding**:

$$(\mathcal{P}(\Sigma^\infty), \sqsubseteq) \xleftrightarrow[\alpha_*]{\gamma_*} (\mathcal{P}(\Sigma^*), \sqsubseteq)$$

- \sqsubseteq is the fused ordering on $\Sigma^* \cup \Sigma^\omega$:
 $A \sqsubseteq B \stackrel{\text{def}}{\iff} (A \cap \Sigma^*) \subseteq (B \cap \Sigma^*) \wedge (A \cap \Sigma^\omega) \supseteq (B \cap \Sigma^\omega)$
- $\alpha_*(T) \stackrel{\text{def}}{=} T \cap \Sigma^*$
 (remove infinite traces)
- $\gamma_*(T) \stackrel{\text{def}}{=} T$
 (embedding)
- $\mathcal{T} = \alpha_*(\mathcal{T}_\infty)$

(proof on next slide)

Potential Termination Trace Semantics

Kleenean Fixpoint Transfer

- $\langle \mathcal{P}(\Sigma^\infty), \sqsubseteq \rangle$
- $\mathcal{M}_\infty \stackrel{\text{def}}{=} \text{lfp}^{\sqsubseteq} F_s$
 $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$
- $\langle \mathcal{P}(\Sigma^*), \subseteq \rangle$
- $\alpha_*: \mathcal{P}(\Sigma^\infty) \rightarrow \mathcal{P}(\Sigma^*)$
 $\alpha_*(T) \stackrel{\text{def}}{=} T \cap \Sigma^*$

$$\mathcal{T}_m \stackrel{\text{def}}{=} \alpha_*(\mathcal{M}_\infty) = \text{lfp}^{\subseteq} F_*$$

$$F_*(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$$

If we have:

- a Galois connection $(C, \leq) \xleftrightarrow[\alpha]{\gamma} (A, \sqsubseteq)$ between CPOs
 - monotonic concrete and abstract functions $f: C \rightarrow C, f^\#: A \rightarrow A$
 - a commutation condition $\alpha \circ f = f^\# \circ \alpha$
 - an element a and its abstraction $a^\# = \alpha(a)$
- then $\alpha(\text{lfp}_a f) = \text{lfp}_{a^\#} f^\#$.

Theorem

Let $\langle C, \leq \rangle$ and $\langle A, \sqsubseteq \rangle$ be complete partial orders, let $f: C \rightarrow C$ and $f^\#: A \rightarrow A$ be monotonic functions, and let $\alpha: C \rightarrow A$ be a continuous abstraction function such that $\alpha(a) = a^\#$, for $a \in C$ and $a^\# \in A$, and that satisfies the commutation condition $\alpha \circ f = f^\# \circ \alpha$. Then, we have the fixpoint abstraction $\alpha(\text{lfp}_a^{\leq} f) = \text{lfp}_{a^\#}^{\sqsubseteq} f^\#$.

Potential Termination Trace Semantics

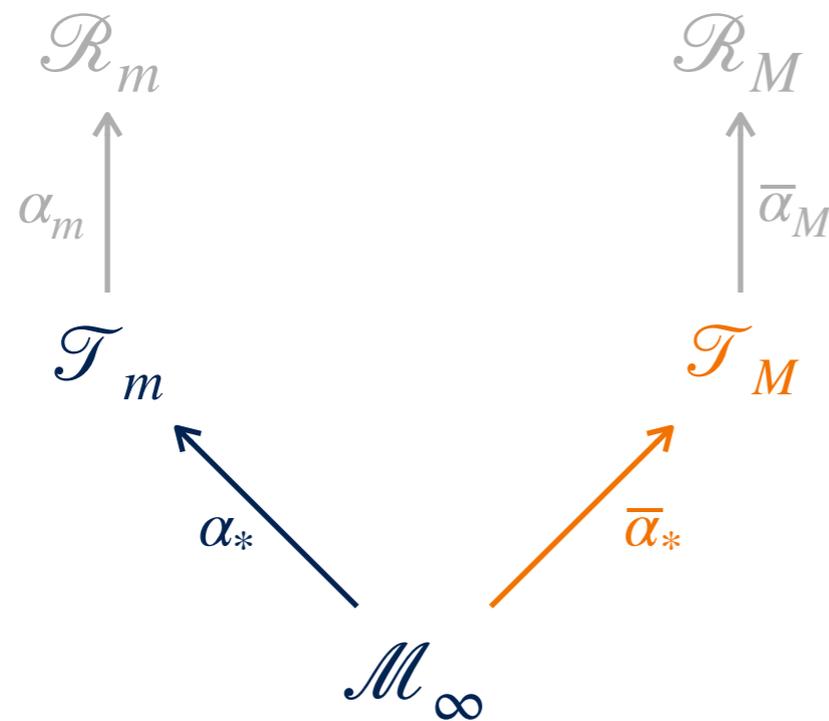
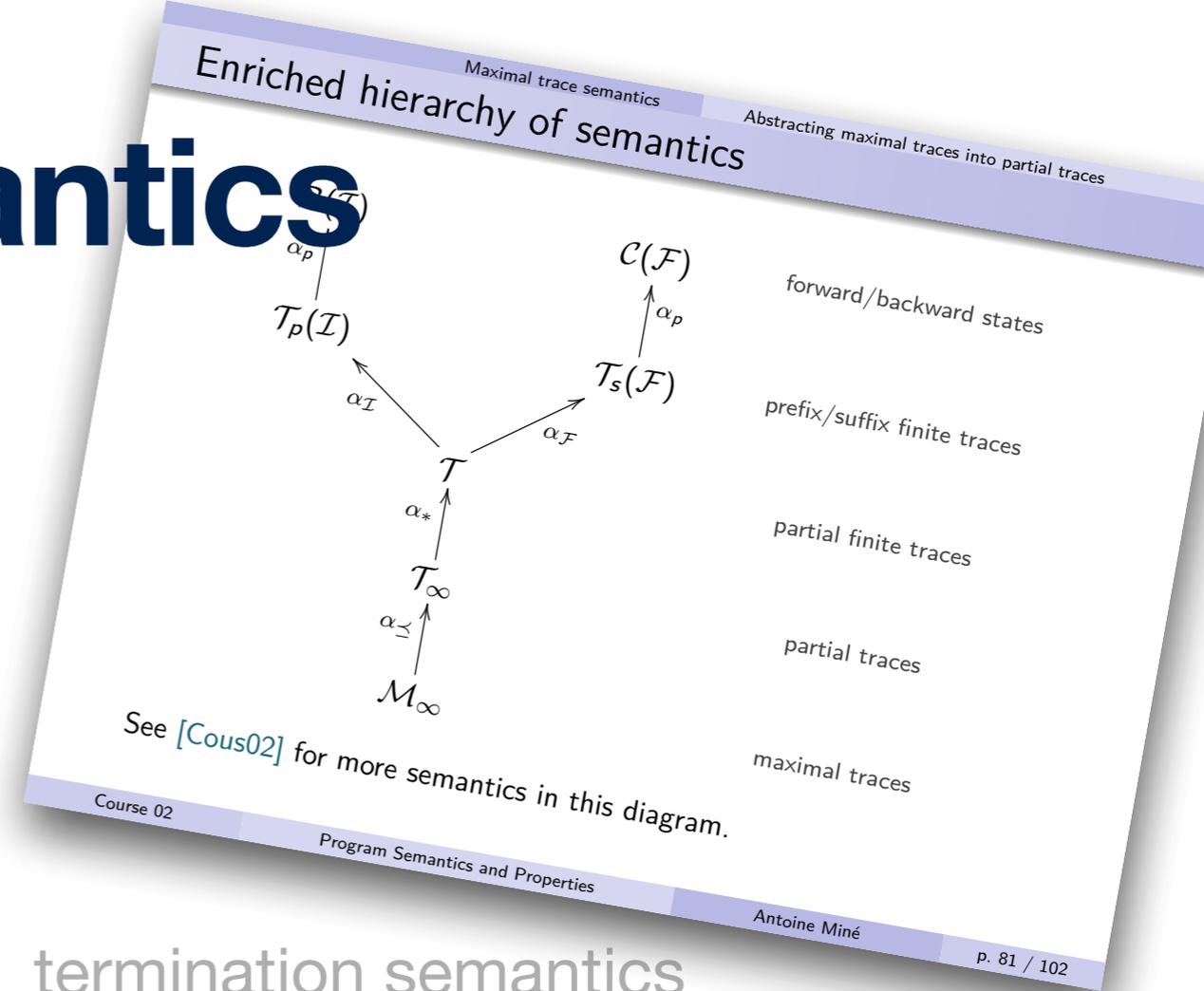
Example

```
while 1([-∞, +∞] ≠ 0) do  
  2skip  
od3
```

$$\mathcal{M}_\infty \stackrel{\text{def}}{=} \{(\mathbf{1}, \rho)(\mathbf{2}, \rho)^*(\mathbf{3}, \rho) \mid \rho \in \mathcal{E}\} \\ \cup \{(\mathbf{1}, \rho)(\mathbf{2}, \rho)^\omega \mid \rho \in \mathcal{E}\}$$

$$\mathcal{T}_m \stackrel{\text{def}}{=} \{(\mathbf{1}, \rho)(\mathbf{2}, \rho)^*(\mathbf{3}, \rho) \mid \rho \in \mathcal{E}\}$$

Hierarchy of Semantics



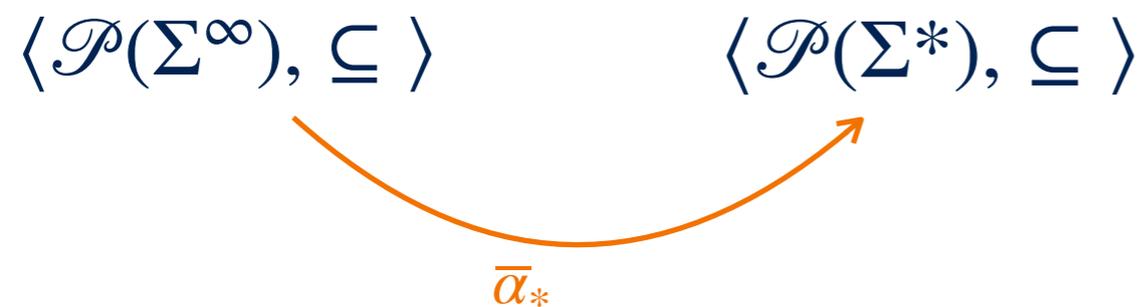
termination semantics

termination trace semantics

maximal trace semantics

Definite Termination Trace Semantics

Definite Termination Abstraction



$$\bar{\alpha}_*(T) \stackrel{\text{def}}{=} \{t \in T \cap \Sigma^* \mid \text{nhdb}(t, T \cap \Sigma^\omega) = \emptyset\}$$

$$\text{nhdb}(t, T) \stackrel{\text{def}}{=} \{t' \in T \mid \text{pf}(t) \cap \text{pf}(t') \neq \emptyset\}$$

$$\text{pf}(t) \stackrel{\text{def}}{=} \{t' \in \Sigma^\omega \setminus \{\epsilon\} \mid \exists t'' \in \Sigma^\omega : t = t' \cdot t''\}$$

Example:

$$\alpha_*({ab, aba, bb, ba^\omega}) = \{ab, aba\} \text{ since } \text{pf}(bb) \cap \text{pf}(ba^\omega) = \{b\} \neq \emptyset$$

Definite Termination Trace Semantics

Tarskian Fixpoint Transfer

- $\langle \mathcal{P}(\Sigma^\infty), \sqsubseteq, \sqcup, \sqcap, \Sigma^\omega, \Sigma^* \rangle$

- $\mathcal{M}_\infty \stackrel{\text{def}}{=} \text{lfp}^{\sqsubseteq} F_s$
 $F_s(T) \stackrel{\text{def}}{=} \mathcal{B} \cup \tau \frown T$

- $\langle \mathcal{P}(\Sigma^*), \subseteq, \cup, \cap, \emptyset, \Sigma^* \rangle$

- $\bar{\alpha}_*: \mathcal{P}(\Sigma^\infty) \rightarrow \mathcal{P}(\Sigma^*)$

$$\mathcal{T}_M \stackrel{\text{def}}{=} \bar{\alpha}_*(\mathcal{M}_\infty) = \text{lfp}^{\subseteq} \bar{F}_*$$

$$\bar{F}_*(T) \stackrel{\text{def}}{=} \mathcal{B} \cup ((\tau \frown T) \cap \neg(\tau \frown \neg T))$$

Theorem

Let $\langle C, \leq, \vee, \wedge, \perp, \top \rangle$ and $\langle A, \sqsubseteq, \sqcup, \sqcap, \perp^\#, \top^\# \rangle$ be complete lattices, let $f: C \rightarrow C$ and $f^\#: A \rightarrow A$ be monotonic functions, and let $\alpha: C \rightarrow A$ be an abstraction function that is a complete \wedge -morphism ($\forall S \subseteq C: f(\wedge S) = \sqcap \{f(s) \mid s \in S\}$) and that satisfies $f^\# \circ \alpha \sqsubseteq \alpha \circ f$ and the post-fixpoint correspondence $\forall a^\# \in A: f^\#(a^\#) \sqsubseteq a^\# \Rightarrow \exists a \in C: f(a) \leq a \wedge \alpha(a) = a^\#$ (i.e., each abstract post-fixpoint of $f^\#$ is the abstraction by α of some concrete post-fixpoint of f). Then, we have the fixpoint abstraction $\alpha(\text{lfp}^{\leq} f) = \text{lfp}^{\sqsubseteq} f^\#$.

(see proof in [Cousot02])

Definite Termination Trace Semantics

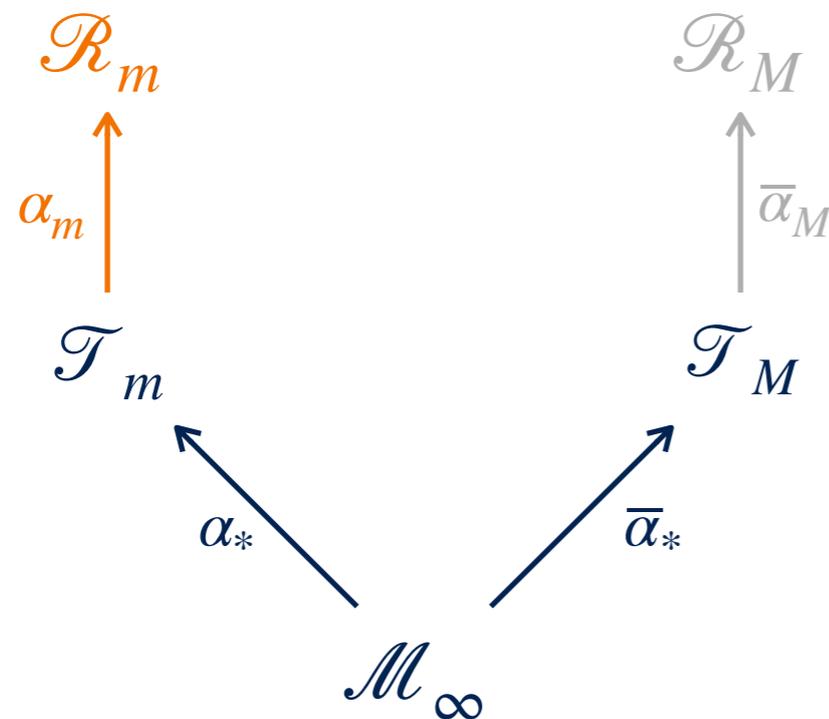
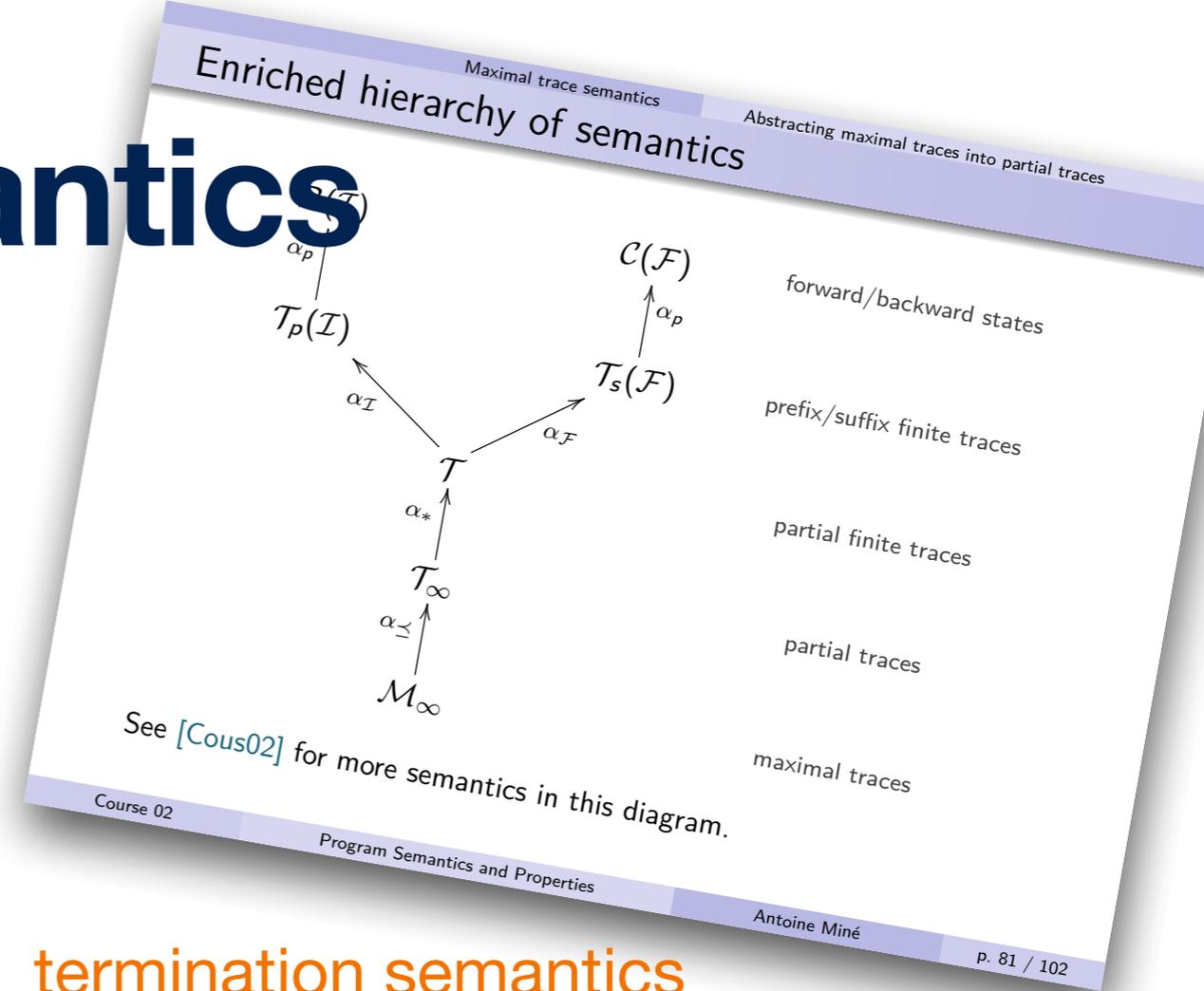
Example

```
while 1([-∞, +∞] ≠ 0) do  
  2skip  
od3
```

$$\mathcal{M}_\infty \stackrel{\text{def}}{=} \{(\mathbf{1}, \rho)(\mathbf{2}, \rho)^*(\mathbf{3}, \rho) \mid \rho \in \mathcal{E}\} \\ \cup \{(\mathbf{1}, \rho)(\mathbf{2}, \rho)^\omega \mid \rho \in \mathcal{E}\}$$

$$\mathcal{T}_M \stackrel{\text{def}}{=} \emptyset$$

Hierarchy of Semantics



termination semantics

termination trace semantics

maximal trace semantics

Potential Termination Semantics

Potential Ranking Abstraction



count execution steps backwards

$$\langle \mathcal{P}(\Sigma^*), \subseteq \rangle$$

$$\langle \Sigma \rightarrow \mathbb{O}, \leq \rangle$$

α_m

$$f_1 \leq f_2 \stackrel{\text{def}}{=} \text{dom}(f_1) \subseteq \text{dom}(f_2) \wedge \forall x \in \text{dom}(f_1): f_1(x) \leq f_2(x)$$

approximation order

$$\alpha_m(T) \stackrel{\text{def}}{=} \alpha_v(\vec{\alpha}(T))$$

$$\alpha_v(\emptyset) \stackrel{\text{def}}{=} \emptyset$$

$$\alpha_v(r)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \forall \sigma' \in \Sigma: (\sigma, \sigma') \notin r \\ \inf\{\alpha_v(r)\sigma' + 1 \mid \sigma' \in \text{dom}(\alpha_v(r)) \wedge (\sigma, \sigma') \in r\} & \text{otherwise} \end{cases}$$

$$\vec{\alpha}(T) \stackrel{\text{def}}{=} \{(\sigma, \sigma') \in \Sigma \times \Sigma \mid \exists t \in \Sigma^*, t' \in \Sigma^\infty: t\sigma\sigma't' \in T\}$$

Potential Termination Semantics

approximation and computational order coincide

$$\mathcal{R}_m \stackrel{\text{def}}{=} \alpha_m(\mathcal{T}_m) = \text{lfp}^{\preceq} F_m$$

$$F_m(f)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \sigma \in \mathcal{B} \\ \inf\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \in \text{pre}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$

State semantics and properties Backward semantics

Backward co-reachability

$\mathcal{C}(\mathcal{F})$: states **co-reachable** from \mathcal{F} in the transition system:

$$\mathcal{C}(\mathcal{F}) \stackrel{\text{def}}{=} \{ \sigma \mid \exists n \geq 0, \sigma_0, \dots, \sigma_n: \sigma = \sigma_0, \sigma_n \in \mathcal{F}, \forall i: \sigma_i \rightarrow \sigma_{i+1} \}$$

$$= \bigcup_{n \geq 0} \text{pre}_\tau^n(\mathcal{F})$$

where $\text{pre}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma \mid \exists \sigma' \in S: \sigma \rightarrow \sigma' \}$ ($\text{pre}_\tau = \text{post}_{\tau^{-1}}$)

$\mathcal{C}(\mathcal{F})$ can also be expressed in **fixpoint form**:

$$\mathcal{C}(\mathcal{F}) = \text{lfp } F_C \text{ where } F_C(S) \stackrel{\text{def}}{=} \mathcal{F} \cup \text{pre}_\tau(S)$$

Justification: $\mathcal{C}(\mathcal{F})$ in τ is exactly $\mathcal{R}(\mathcal{F})$ in τ^{-1} .

Alternate characterization: $\mathcal{C}(\mathcal{F}) = \text{lfp}_{\mathcal{F}} G_C$ where $G_C(S) = S \cup \text{pre}_\tau(S)$

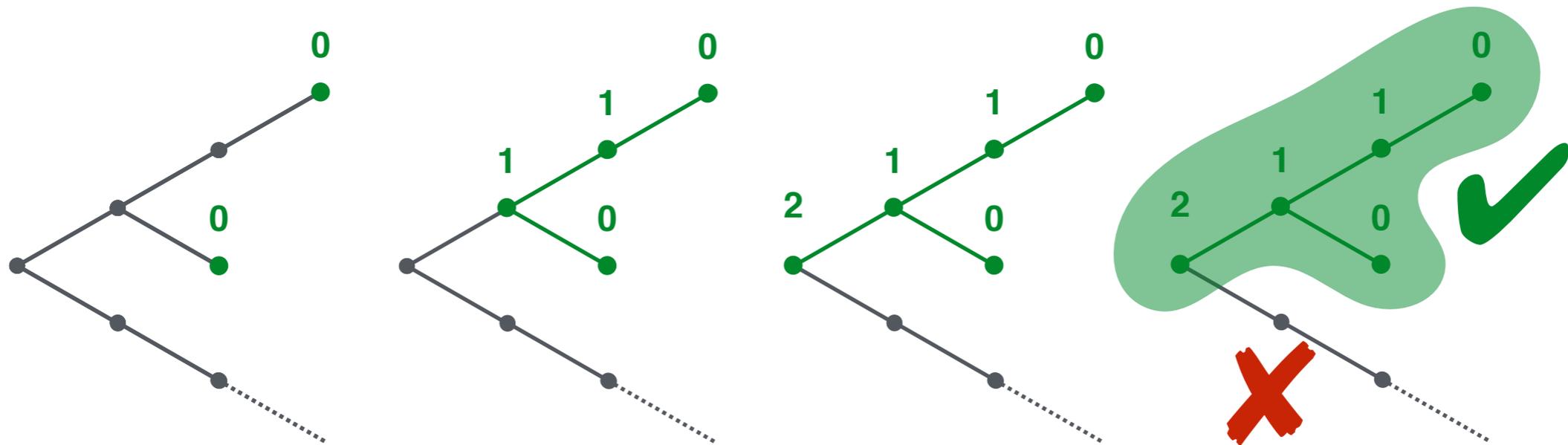
Course 02
Program Semantics and Properties
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Potential Termination Semantics

approximation and computational order coincide

$$\mathcal{R}_m \stackrel{\text{def}}{=} \alpha_m(\mathcal{T}_m) = \text{lfp}^{\preceq} F_m$$

$$F_m(f)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \sigma \in \mathcal{B} \\ \inf\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \in \text{pre}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$



Theorem

A program **may terminate** for traces starting from a set of initial state \mathcal{I} if and only if $\mathcal{I} \subseteq \text{dom}(\mathcal{R}_m)$

Potential Termination Semantics

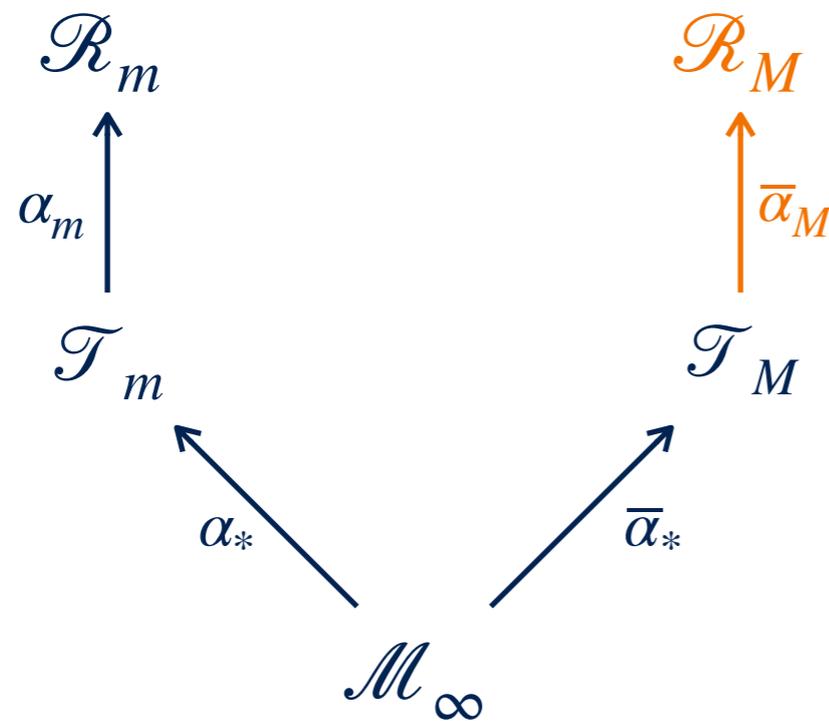
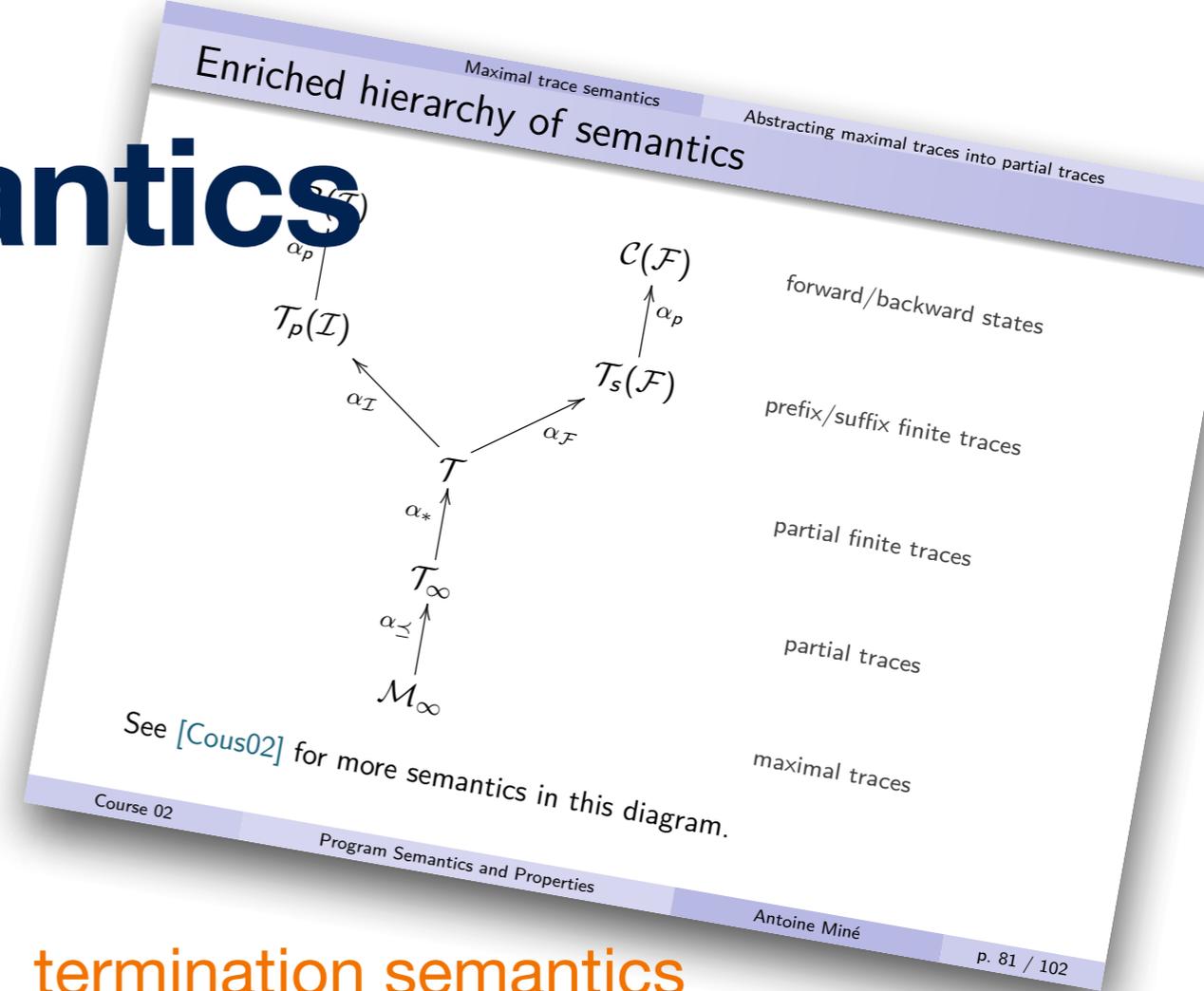
Exercise

Show that the following fixpoint definition of the potential termination semantics **does not guarantee the existence of a least fixpoint**:

$$\mathcal{R}_m \stackrel{\text{def}}{=} \alpha_m(\mathcal{T}_m) = \text{lfp}^{\preceq} F_m$$
$$F_m(f)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \sigma \in \mathcal{B} \\ \sup\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \in \text{pre}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$

Hint: find a program for which the values of the iterates of the potential termination semantics are always increasing

Hierarchy of Semantics



termination semantics

termination trace semantics

maximal trace semantics

Definite Termination Semantics

Ranking Abstraction



count execution steps backwards

$$\langle \mathcal{P}(\Sigma^*), \subseteq \rangle$$

$$\langle \Sigma \rightarrow \mathbb{O}, \preceq \rangle$$

α_m

$$f_1 \preceq f_2 \stackrel{\text{def}}{=} \text{dom}(f_1) \supseteq \text{dom}(f_2) \wedge \forall x \in \text{dom}(f_1): f_1(x) \leq f_2(x)$$

approximation order

$$\bar{\alpha}_M(T) \stackrel{\text{def}}{=} \bar{\alpha}_V(\vec{\alpha}(T))$$

$$\bar{\alpha}_V(\emptyset) \stackrel{\text{def}}{=} \emptyset$$

$$\bar{\alpha}_V(r)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \forall \sigma' \in \Sigma: (\sigma, \sigma') \notin r \\ \sup\{\bar{\alpha}_V(r)\sigma' + 1 \mid \sigma' \in \text{dom}(\bar{\alpha}_V(r)) \wedge (\sigma, \sigma') \in r\} & \text{otherwise} \end{cases}$$

$$\vec{\alpha}(T) \stackrel{\text{def}}{=} \{(\sigma, \sigma') \in \Sigma \times \Sigma \mid \exists t \in \Sigma^*, t' \in \Sigma^\infty: t\sigma\sigma't' \in T\}$$

Definite Termination Semantics

$$\mathcal{R}_M \stackrel{\text{def}}{=} \bar{\alpha}_M(\mathcal{T}_M) = \text{lfp}^{\preceq} \bar{F}_M$$

computational order

$$f_1 \preceq f_2 \stackrel{\text{def}}{=} \text{dom}(f_1) \subseteq \text{dom}(f_2) \wedge \forall x \in \text{dom}(f_1): f_1(x) \leq f_2(x)$$

$$\bar{F}_M(f)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \sigma \in \mathcal{B} \\ \sup\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \in \tilde{\text{pre}}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$

State semantics and properties Sufficient precondition semantics

Sufficient preconditions

$\mathcal{S}(\mathcal{Y})$: states with executions **staying in** \mathcal{Y} .

$$\mathcal{S}(\mathcal{Y}) \stackrel{\text{def}}{=} \{ \sigma \mid \forall n \geq 0, \sigma_0, \dots, \sigma_n: (\sigma = \sigma_0 \wedge \forall i: \sigma_i \rightarrow \sigma_{i+1}) \implies \sigma_n \in \mathcal{Y} \}$$

$$= \bigcap_{n \geq 0} \tilde{\text{pre}}_\tau^n(\mathcal{Y})$$

where $\tilde{\text{pre}}_\tau(S) \stackrel{\text{def}}{=} \{ \sigma \mid \forall \sigma': \sigma \rightarrow \sigma' \implies \sigma' \in S \}$
 (states such that all successors satisfy S , $\tilde{\text{pre}}$ is a complete \cap -morphism)

$\mathcal{S}(\mathcal{Y})$ can be expressed in **fixpoint form**:

$$\mathcal{S}(\mathcal{Y}) = \text{gfp } F_S \text{ where } F_S(S) \stackrel{\text{def}}{=} \mathcal{Y} \cap \tilde{\text{pre}}_\tau(S)$$

proof sketch: similar to that of $\mathcal{R}(\mathcal{I})$, in the dual.

F_S is continuous in the dual CPO $(\mathcal{P}(\Sigma), \supseteq)$, because $\tilde{\text{pre}}_\tau$ is:
 $F_S(\bigcap_{i \in I} A_i) = \bigcap_{i \in I} F_S(A_i)$.
 By Kleene's theorem in the dual, $\text{gfp } F_S = \bigcap_{n \in \mathbb{N}} F_S^n(\Sigma)$.
 We would prove by recurrence that $F_S^n(\Sigma) = \bigcap_{i < n} \tilde{\text{pre}}_\tau^i(\mathcal{Y})$.

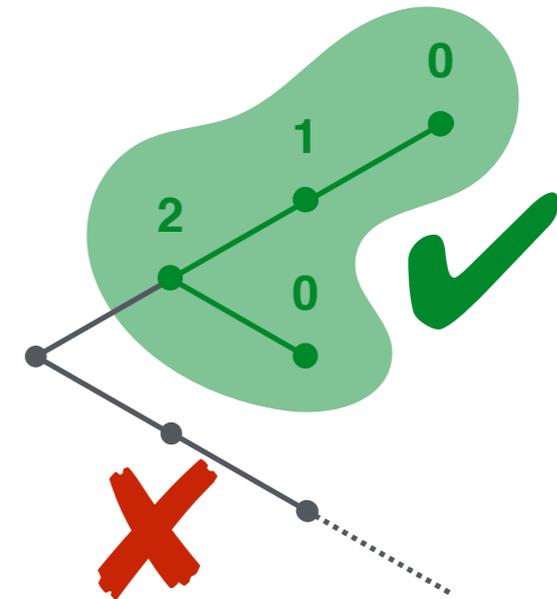
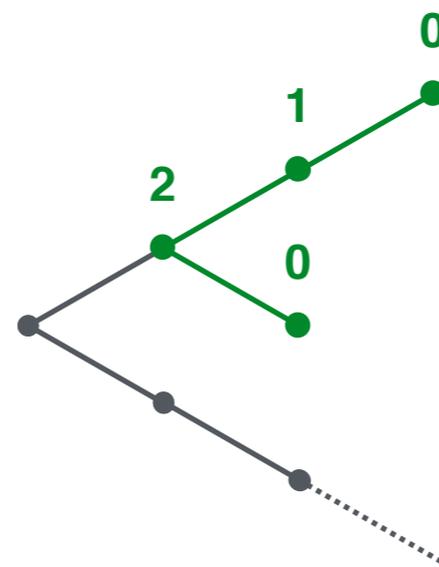
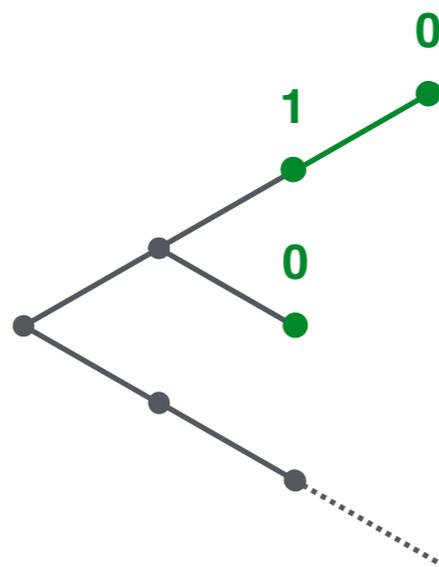
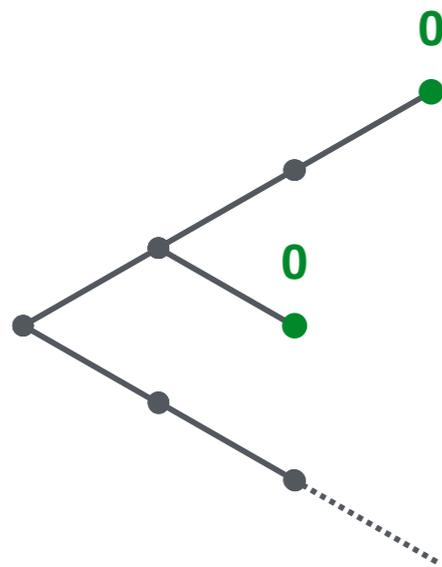
Definite Termination Semantics

$$f_1 \preceq f_2 \stackrel{\text{def}}{=} \text{dom}(f_1) \subseteq \text{dom}(f_2) \wedge \forall x \in \text{dom}(f_1): f_1(x) \leq f_2(x)$$

$$\mathcal{R}_M \stackrel{\text{def}}{=} \bar{\alpha}_M(\mathcal{T}_M) = \text{lfp}^{\preceq} \bar{F}_M$$

computational order

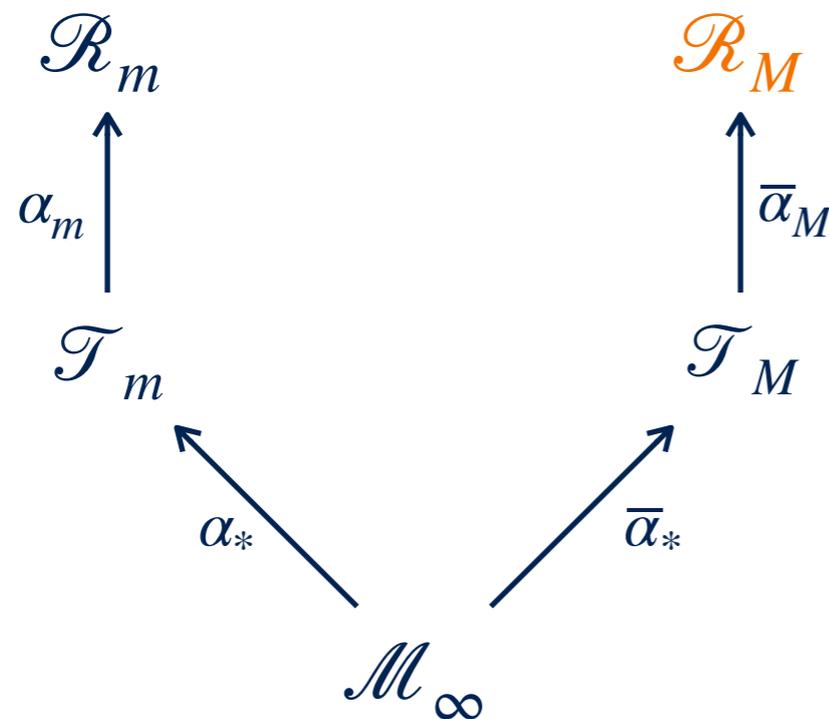
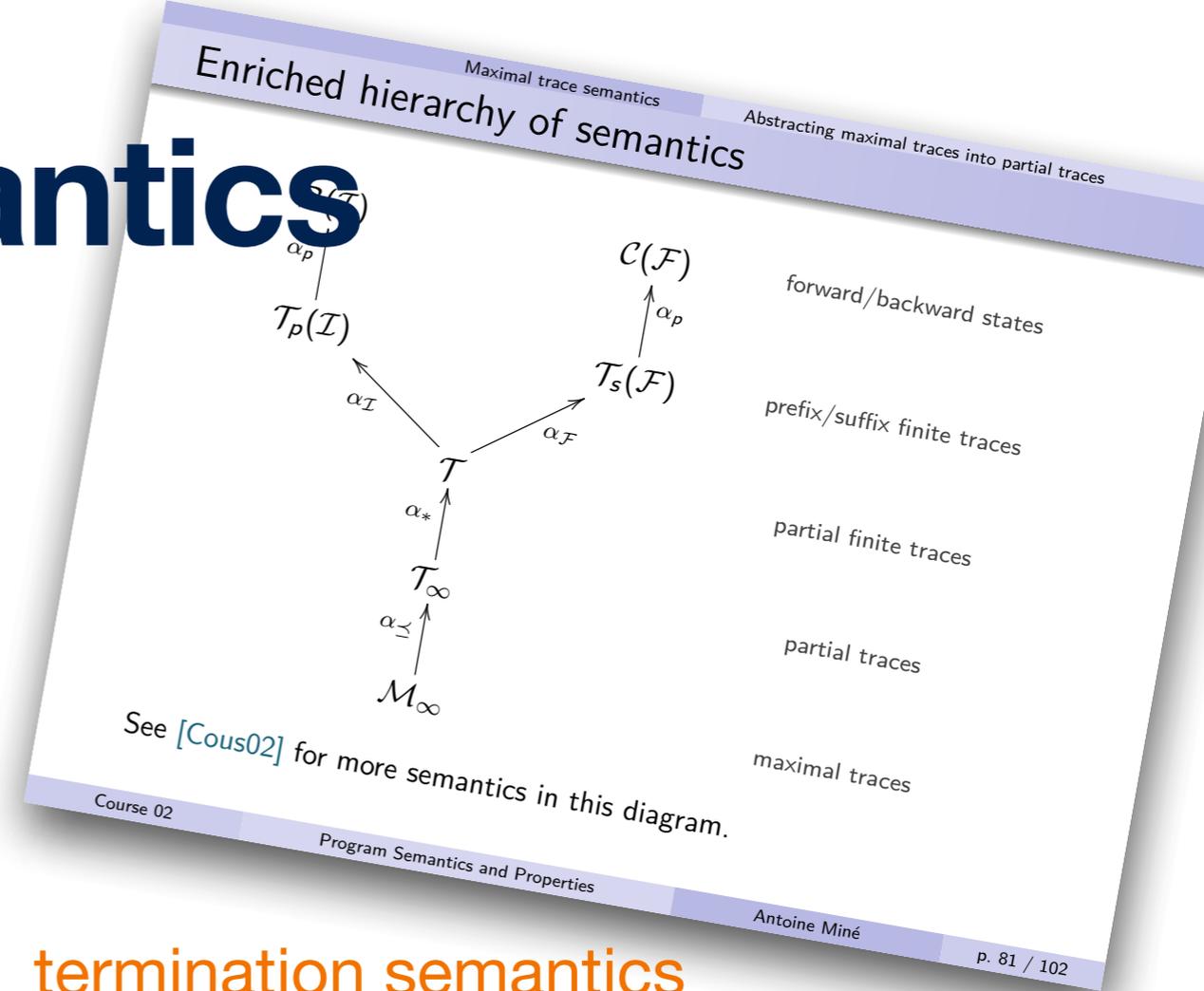
$$\bar{F}_M(f)\sigma \stackrel{\text{def}}{=} \begin{cases} 0 & \sigma \in \mathcal{B} \\ \sup\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \in \tilde{\text{pre}}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$



Theorem

A program **must terminate** for traces starting from a set of initial states \mathcal{I} if and only if $\mathcal{I} \subseteq \text{dom}(\mathcal{R}_M)$

Hierarchy of Semantics



termination semantics

termination trace semantics

maximal trace semantics

Denotational Definite Termination Semantics

We define the definite termination semantics $\mathcal{R}_M: \Sigma \rightarrow \mathbb{O}$ by partitioning with respect to the program control points, i.e.,

$$\mathcal{R}_M: \mathcal{L} \rightarrow (\mathcal{E} \rightarrow \mathbb{O}).$$

Thus, for each program instruction stat , we define a transformer

$$\mathcal{R}_M[\![\text{stat}]\!] : (\mathcal{E} \rightarrow \mathbb{O}) \rightarrow (\mathcal{E} \rightarrow \mathbb{O}):$$

- $\mathcal{R}_M[\![\ell X \leftarrow e]\!]$
- $\mathcal{R}_M[\![\text{if } \ell e \bowtie 0 \text{ then } s]\!]$
- $\mathcal{R}_M[\![\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}]\!]$
- $\mathcal{R}_M[\![s_1; s_2]\!]$

Language syntax Introduction

| | | |
|--------------------|---|--|
| ℓstat | $::=$ <ul style="list-style-type: none"> $\ell X \leftarrow \text{exp}^\ell$ $\text{if } \text{exp}^\ell \bowtie 0 \text{ then } \ell \text{stat}^\ell$ $\text{while } \ell \text{exp}^\ell \bowtie 0 \text{ do } \ell \text{stat}^\ell \text{ done}^\ell$ $\ell \text{stat}^\ell; \ell \text{stat}^\ell$ | <ul style="list-style-type: none"> (assignment) (conditional) (loop) (sequence) |
| exp | $::=$ <ul style="list-style-type: none"> X $-\text{exp}$ $\text{exp} \diamond \text{exp}$ c $[c, c']$ | <ul style="list-style-type: none"> (variable) (negation) (binary operation) (constant $c \in \mathbb{Z}$) (random input, $c, c' \in \mathbb{Z} \cup \{\pm\infty\}$) |

Simple structured, numeric language

- $X \in \mathbb{V}$, where \mathbb{V} is a finite set of **program variables**
- $\ell \in \mathcal{L}$, where \mathcal{L} is a finite set of **control points**
- numeric expressions: $\bowtie \in \{=, \leq, \dots\}$, $\diamond \in \{+, -, \times, /\}$
- **random inputs**: $X \leftarrow [c, c']$
model environment, parametric programs, unknown functions, ...

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Denotational Definite Termination Semantics

$$\mathcal{R}_M \llbracket X \leftarrow e \rrbracket$$

$$\mathcal{R}_M \llbracket X \leftarrow e \rrbracket f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} \sup \{ f(\rho[X \mapsto v]) + 1 \mid v \in E \llbracket e \rrbracket \rho \} & \exists \bar{v} \in E \llbracket e \rrbracket \rho \wedge \\ & \forall v \in E \llbracket e \rrbracket \rho : \rho[X \mapsto v] \in \text{dom}(f) \\ \text{undefined} & \text{otherwise} \end{cases}$$

Example:

Let $\mathbb{V} = \{x\}$ and $f: \mathcal{E} \rightarrow \mathbb{O}$ defined as follows:

$$f(\rho) \stackrel{\text{def}}{=} \begin{cases} 2 & \rho(x) = 1 \\ 3 & \rho(x) = 2 \\ \text{undefined} & \text{otherwise} \end{cases}$$

We have

$$\mathcal{R}_M \llbracket x \leftarrow x + [1,2] \rrbracket f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} 4 & \rho(x) = 0 \\ \text{undefined} & \text{otherwise} \end{cases}$$

Denotational Definite Termination Semantics

$$\mathcal{R}_M[\text{if } e \neq 0 \text{ then } s]$$

$$\mathcal{R}_M[\text{if } e \neq 0 \text{ then } s]f \stackrel{\text{def}}{=} \lambda\rho. \begin{cases} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \\ \text{undefined} & \text{otherwise} \end{cases}$$

$$\textcircled{1} \quad \sup\{\mathcal{R}_M[s]f(\rho) + 1, f(\rho) + 1\} \quad \rho \in \text{dom}(\mathcal{R}_M[s]f) \cap \text{dom}(f) \wedge \exists v_1, v_2 \in E[e]\rho: v_1 \neq 0 \wedge v_2 \neq 0$$

$$\textcircled{2} \quad \mathcal{R}_M[s]f(\rho) + 1 \quad \rho \in \text{dom}(\mathcal{R}_M[s]f) \wedge \forall v \in E[e]\rho: v \neq 0$$

$$\textcircled{3} \quad f(\rho) + 1 \quad \rho \in \text{dom}(f) \wedge \forall v \in E[e]\rho: v \neq 0$$

Denotational Definite Termination Semantics

$\mathcal{R}_M \llbracket \text{if } e \bowtie 0 \text{ then } s \rrbracket$ (continue)

Example:

Let $\mathbb{V} = \{x\}$ and $f: \mathcal{E} \rightarrow \mathbb{O}$, and $\mathcal{R}_M \llbracket s \rrbracket f$ defined as follows:

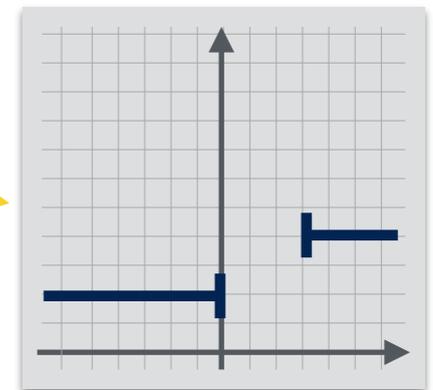
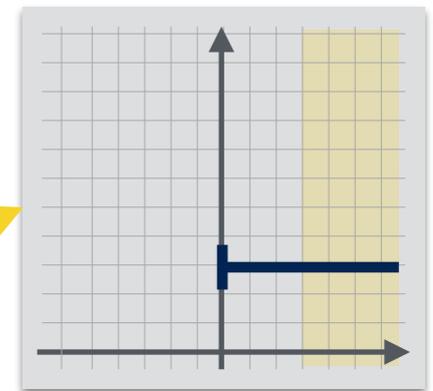
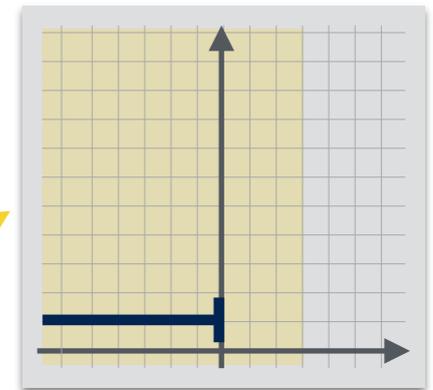
$$f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} 1 & \rho(x) \leq 0 \\ \text{undefined} & \text{otherwise} \end{cases}$$

$$\mathcal{R}_M \llbracket s \rrbracket f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} 3 & 0 \leq \rho(x) \\ \text{undefined} & \text{otherwise} \end{cases}$$

We have

$$\mathcal{R}_M \llbracket \text{if } 3 - x < 0 \text{ then } s \rrbracket f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} 2 & \rho(x) \leq 0 \\ 4 & 3 < \rho(x) \\ \text{undefined} & \text{otherwise} \end{cases}$$

$$\text{and } \mathcal{R}_M \llbracket \text{if } [-\infty, +\infty] \neq 0 \text{ then } s \rrbracket f \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} 4 & \rho(x) = 0 \\ \text{undefined} & \text{otherwise} \end{cases}$$



Denotational Definite Termination Semantics

$$\mathcal{R}_M[\text{while } e \bowtie 0 \text{ do } s \text{ done}]$$

$$\mathcal{R}_M[\text{while } e \bowtie 0 \text{ do } s \text{ done}]f \stackrel{\text{def}}{=} \text{lfp}_{\emptyset}^{\leq} \bar{F}_M$$

$$f_1 \leq f_2 \stackrel{\text{def}}{=} \text{dom}(f_1) \subseteq \text{dom}(f_2) \wedge \forall x \in \text{dom}(f_1): f_1(x) \leq f_2(x)$$

computational order

$$F_M(x) \stackrel{\text{def}}{=} \lambda \rho . \begin{cases} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \\ \text{undefined} & \text{otherwise} \end{cases}$$

- $\textcircled{1}$ $\sup\{\mathcal{R}_M[[s]]x(\rho) + 1, f(\rho) + 1\}$ $\rho \in \text{dom}(\mathcal{R}_M[[s]]x) \cap \text{dom}(f) \wedge \exists v_1, v_2 \in E[[e]]\rho: v_1 \bowtie 0 \wedge v_2 \not\bowtie 0$
- $\textcircled{2}$ $\mathcal{R}_M[[s]]x(\rho) + 1$ $\rho \in \text{dom}(\mathcal{R}_M[[s]]x) \wedge \forall v \in E[[e]]\rho: v \bowtie 0$
- $\textcircled{3}$ $f(\rho) + 1$ $\rho \in \text{dom}(f) \wedge \forall v \in E[[e]]\rho: v \not\bowtie 0$

Denotational Definite Termination Semantics

$$\mathcal{R}_M[[s_1; s_2]]$$

$$\mathcal{R}_M[[s_1; s_2]]f \stackrel{\text{def}}{=} \mathcal{R}_M[[s_1]](\mathcal{R}_M[[s_2]]f)$$

Denotational Definite Termination Semantics

Definition

The **definite termination semantics** $\mathcal{R}_M[[\text{stat}^\ell]] : \mathcal{E} \rightarrow \mathbb{O}$ of a program stat^ℓ is:

$$\mathcal{R}_M[[\text{stat}^\ell]] \stackrel{\text{def}}{=} \mathcal{R}_M[[\text{stat}]](\lambda\rho.0)$$

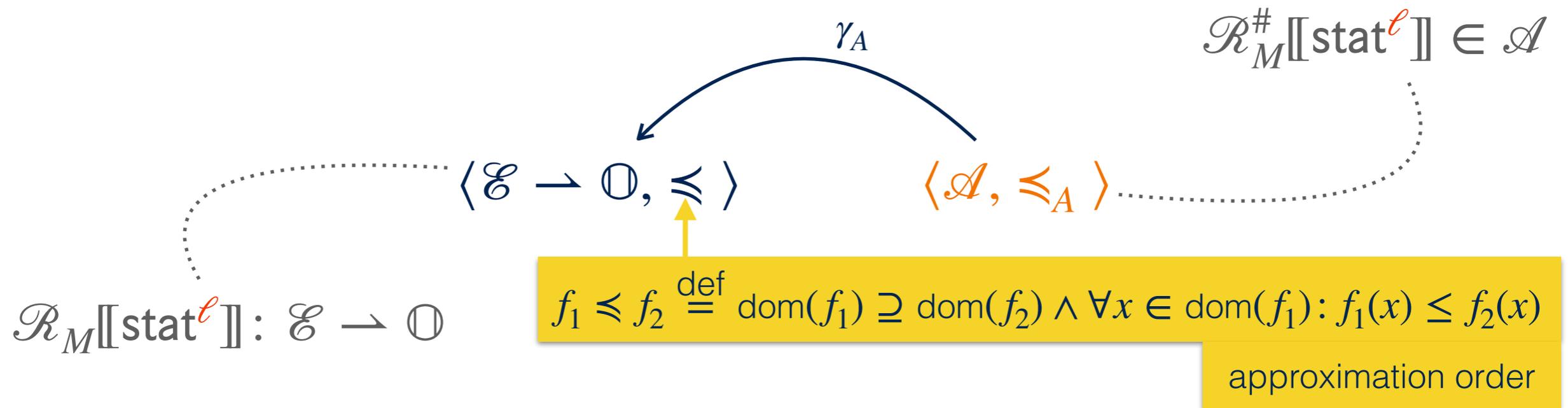
where $\mathcal{R}_M[[\text{stat}]] : (\mathcal{E} \rightarrow \mathbb{O}) \rightarrow (\mathcal{E} \rightarrow \mathbb{O})$ is the definite termination semantics of each program instruction stat

Theorem

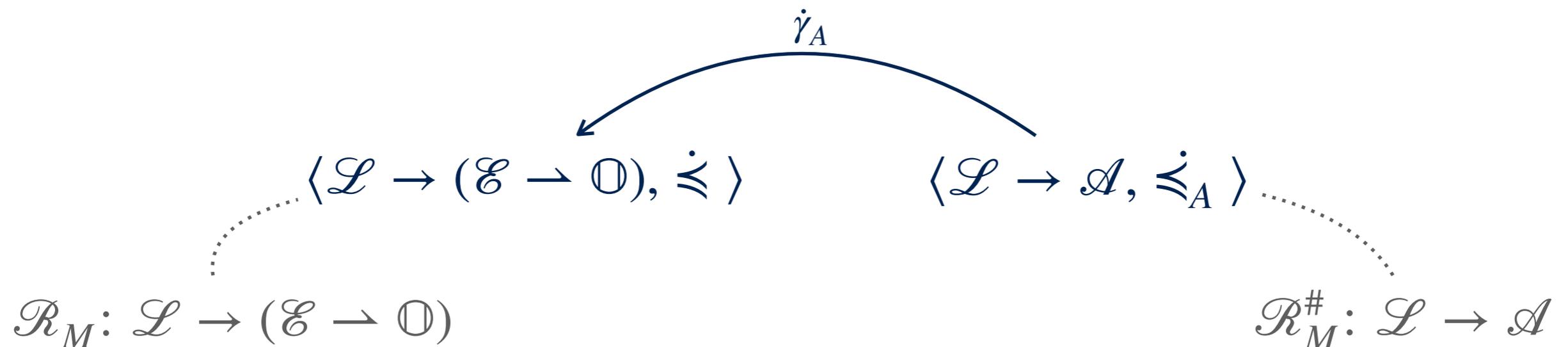
A program stat^ℓ **must terminate** for traces starting from a set of initial states \mathcal{I} if $\mathcal{I} \subseteq \text{dom}(\mathcal{R}_m[[\text{stat}^\ell]])$

Piecewise-Defined Ranking Functions Abstract Domain

Concretization-Based Piecewise Abstraction



By *pointwise lifting* we obtain an abstraction $\mathcal{R}_M^{\#}$ of \mathcal{R}_M :



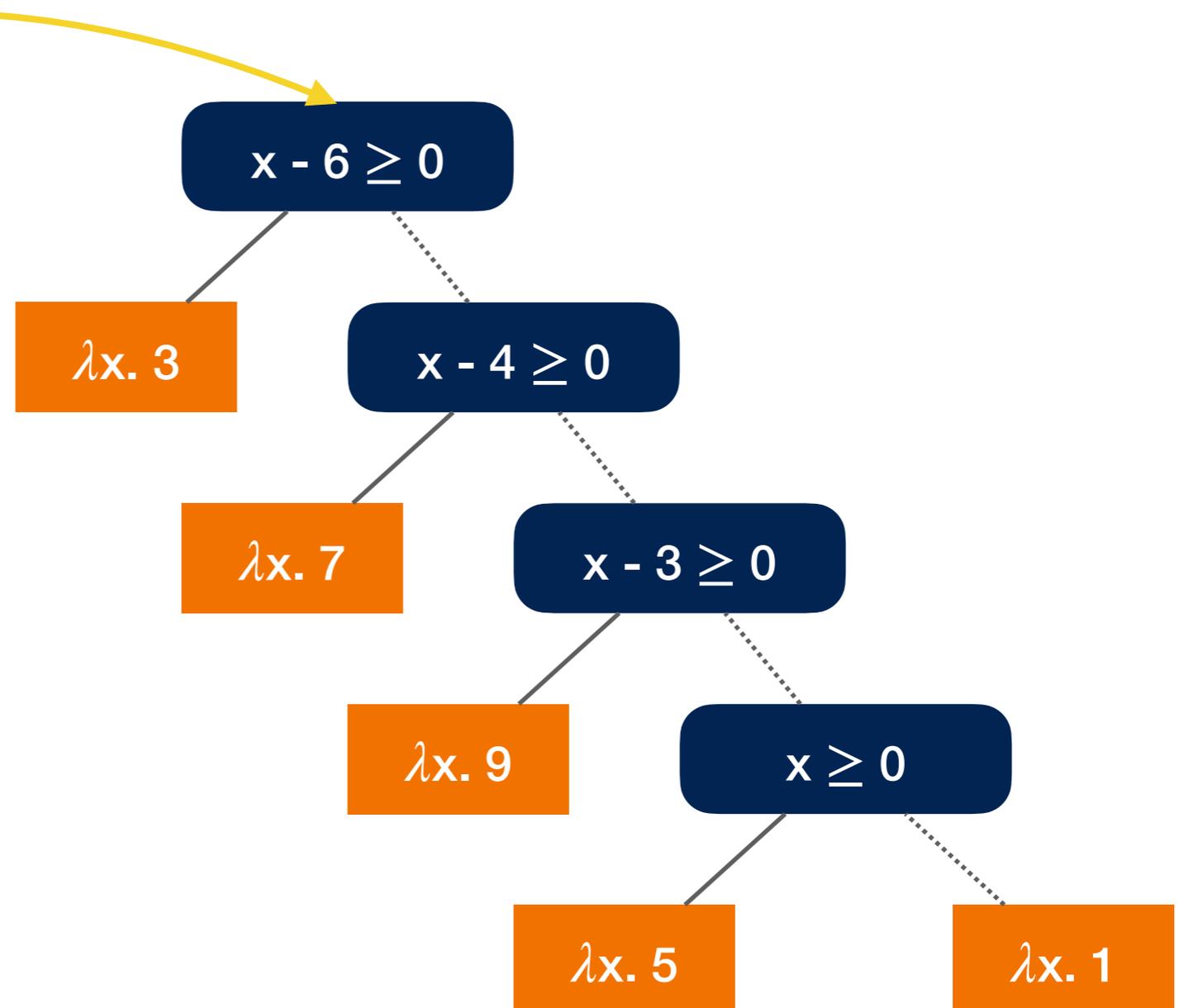
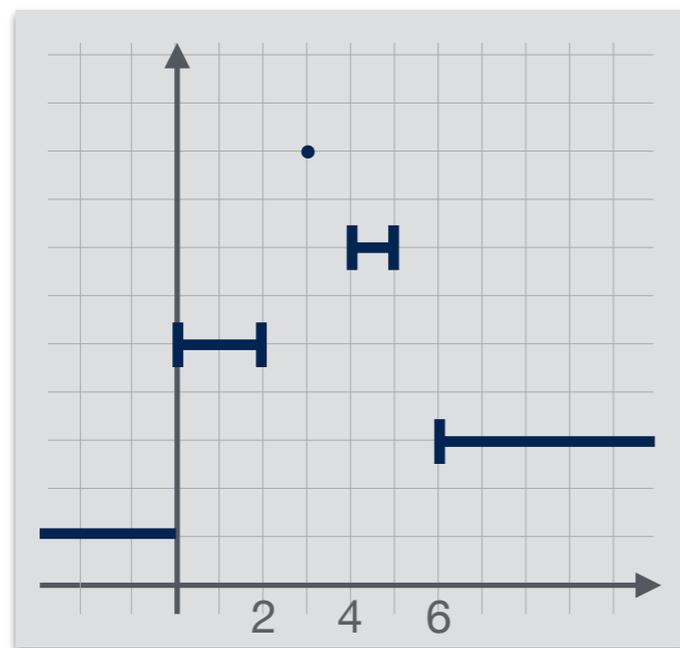
Piecewise-Defined Ranking Functions Abstract Domain

$\langle \mathcal{A}, \preceq_A \rangle$

Example

```

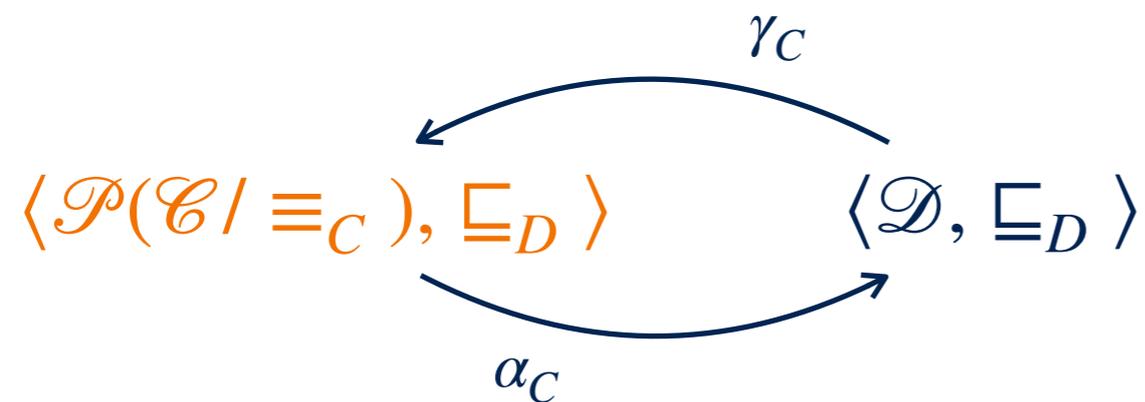
1 $x \leftarrow [-\infty, +\infty]$ 
while 2 $(x \geq 0)$  do
  3 $x \leftarrow -2 \cdot x + 10$ 
od4
  
```



Piecewise-Defined Ranking Functions Abstract Domain

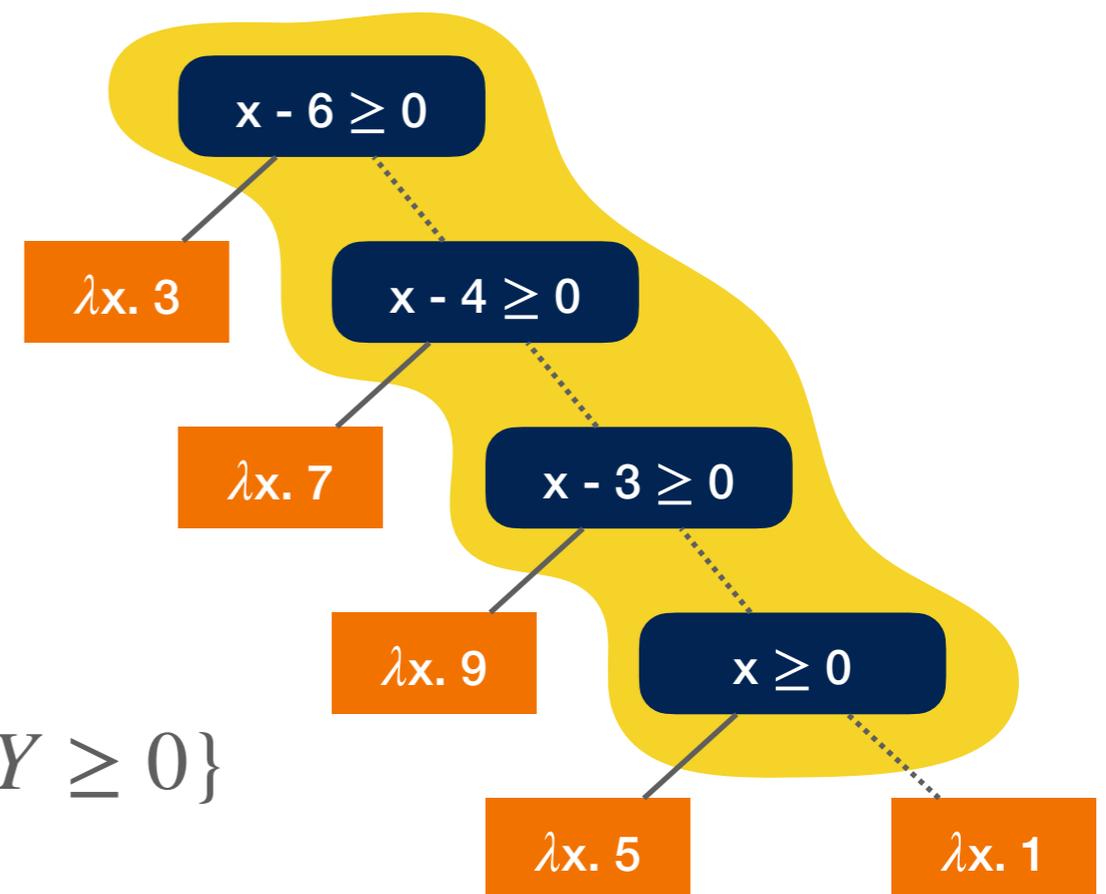
Linear Constraints Auxiliary Abstract Domain

- Parameterized by an *underlying numerical abstract domain* $\langle \mathcal{D}, \sqsubseteq_D \rangle$ (i.e., intervals, octagons, or polyhedra):



Example:

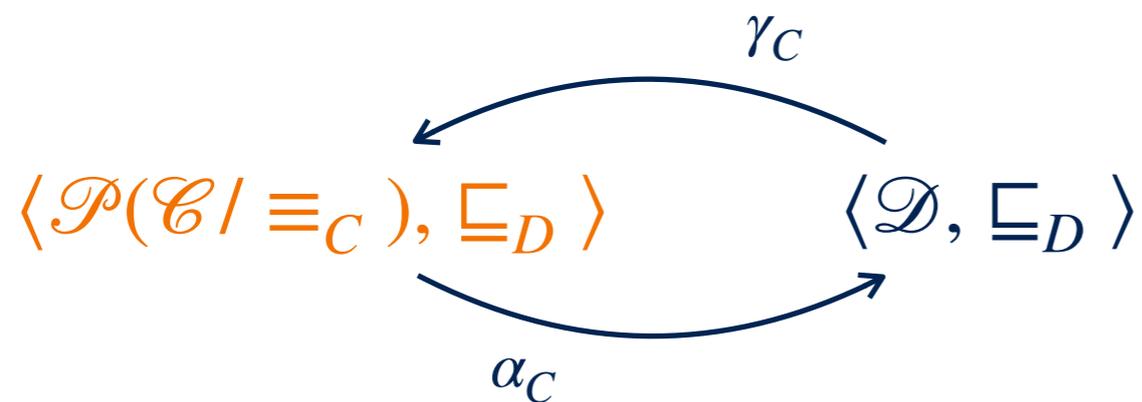
$$\begin{array}{l} X \rightarrow [-\infty, 3] \\ Y \rightarrow [0, +\infty] \end{array} \xrightarrow{\gamma_C} \{3 - X \geq 0, Y \geq 0\}$$



Piecewise-Defined Ranking Functions Abstract Domain

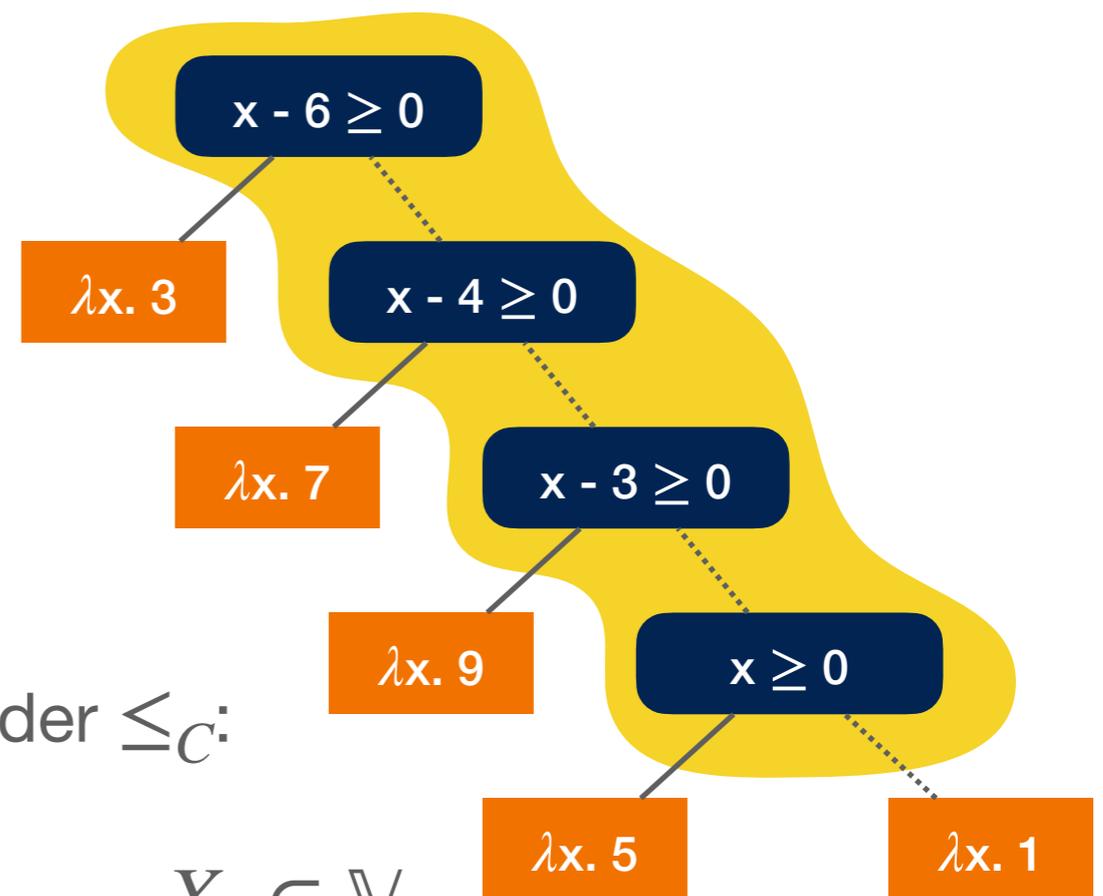
Linear Constraints Auxiliary Abstract Domain

- Parameterized by an *underlying numerical abstract domain* $\langle \mathcal{D}, \sqsubseteq_D \rangle$ (i.e., intervals, octagons, or polyhedra):



- \mathcal{C} is a set of linear constraints in canonical form, equipped with a total order \leq_C :

$$\mathcal{C} \stackrel{\text{def}}{=} \{c_1 \cdot X_1 + \dots + c_k \cdot X_k + c_{k+1} \geq 0 \mid X_1, \dots, X_k \in \mathbb{V} \wedge c_1, \dots, c_{k+1} \in \mathbb{Z} \wedge \gcd(|c_1|, \dots, |c_{k+1}|) = 1\}$$



Piecewise-Defined Ranking Functions Abstract Domain

Functions Auxiliary Abstract Domain

- Parameterized by an *underlying numerical abstract domain* $\langle \mathcal{D}, \sqsubseteq_D \rangle$

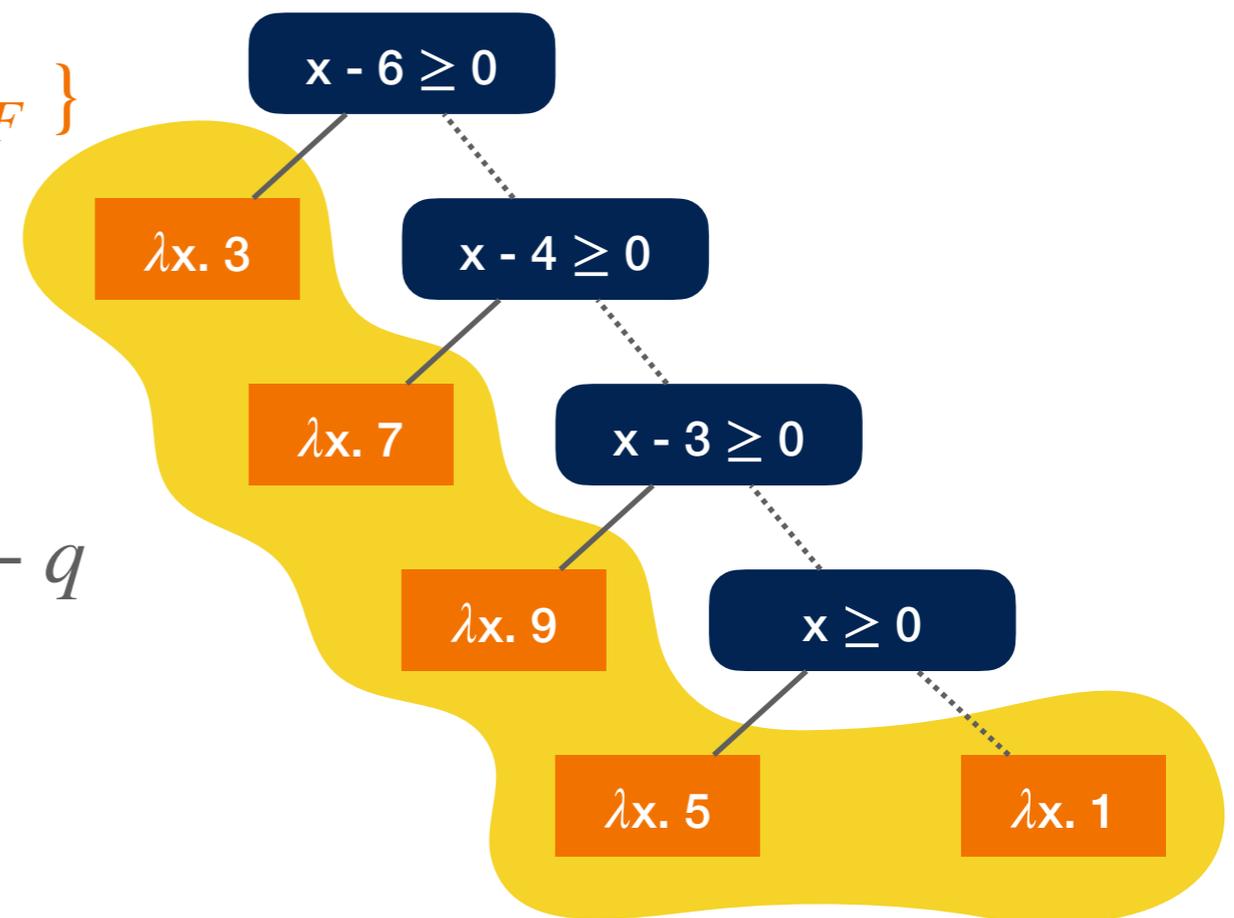
- $\mathcal{F} \stackrel{\text{def}}{=} \{ \perp_F \} \cup (\mathbb{Z}^{|M|} \rightarrow \mathbb{N}) \cup \{ \top_F \}$

We consider **affine functions**:

$$\mathcal{F}_A \stackrel{\text{def}}{=} \{ \perp_F \} \cup \{ f: \mathbb{Z}^{|M|} \rightarrow \mathbb{N} \mid$$

$$f(X_1, \dots, X_k) = \sum_{i=1}^k m_i \cdot X_i + q$$

$$\} \cup \{ \top_F \}$$



Piecewise-Defined Ranking Functions Abstract Domain

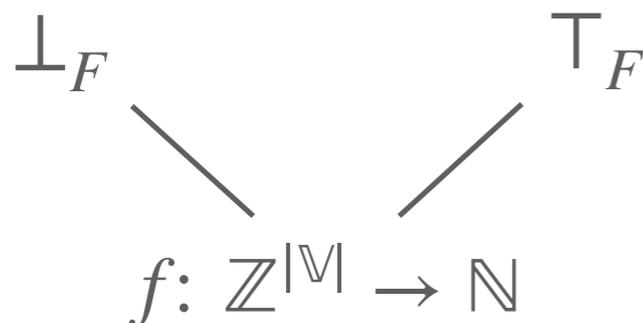
Functions Auxiliary Abstract Domain (continue)

- **approximation order** $\preceq_F [D]$, where $D \in \mathcal{D}$:

- between defined leaf nodes:

$$f_1 \preceq_F [D] f_2 \stackrel{\text{def}}{=} \forall \rho \in \gamma_D(D): f_1(\dots, \rho(X_i), \dots) \leq f_2(\dots, \rho(X_i), \dots)$$

- otherwise (i.e., when one or both leaf nodes are undefined):



Piecewise-Defined Ranking Functions Abstract Domain

Functions Auxiliary Abstract Domain (continue)

- **computational order** $\sqsubseteq_F [D]$, where $D \in \mathcal{D}$:

- between defined leaf nodes:

$$f_1 \sqsubseteq_F [D] f_2 \stackrel{\text{def}}{=} \forall \rho \in \gamma_D(D): f_1(\dots, \rho(X_i), \dots) \leq f_2(\dots, \rho(X_i), \dots)$$

- otherwise (i.e., when one or both leaf nodes are undefined):

$$\begin{array}{c} \top_F \\ | \\ f: \mathbb{Z}^{|\mathbb{V}|} \rightarrow \mathbb{N} \\ | \\ \perp_F \end{array}$$

Piecewise-Defined Ranking Functions Abstract Domain

- $\mathcal{A} \stackrel{\text{def}}{=} \{\text{LEAF}: f \mid f \in \mathcal{F}\} \cup \{\text{NODE}\{c\}: t_1; t_2 \mid c \in \mathcal{C} \wedge t_1, t_2 \in \mathcal{A}\}$
- **concretization function** $\gamma_A: \mathcal{A} \rightarrow (\mathcal{E} \rightarrow \mathbb{O})$:

$$\gamma_A(t) \stackrel{\text{def}}{=} \bar{\gamma}_A[\emptyset](t)$$

where $\bar{\gamma}_A: \mathcal{P}(\mathcal{C} / \equiv_C) \rightarrow \mathcal{A} \rightarrow (\mathcal{E} \rightarrow \mathbb{O})$:

$$\bar{\gamma}_A[C](\text{LEAF}: f) \stackrel{\text{def}}{=} \gamma_F[\alpha_C(C)](f)$$

$$\bar{\gamma}_A[C](\text{NODE}\{c\}: t_1; t_2) \stackrel{\text{def}}{=} \bar{\gamma}_A[C \cup \{c\}](t_1) \dot{\cup} \bar{\gamma}_A[C \cup \{\neg c\}](t_2)$$

and $\gamma_F: \mathcal{D} \rightarrow \mathcal{F} \rightarrow (\mathcal{E} \rightarrow \mathbb{O})$:

$$\gamma_F[D](\perp_F) \stackrel{\text{def}}{=} \dot{\emptyset}$$

$$\gamma_F[D](f) \stackrel{\text{def}}{=} \forall \rho \in \gamma_D(D): f(\dots, \rho(X_i), \dots)$$

$$\gamma_F[D](\top_F) \stackrel{\text{def}}{=} \dot{\emptyset}$$

Piecewise-Defined Ranking Functions Abstract Domain

Abstract Domain Operators

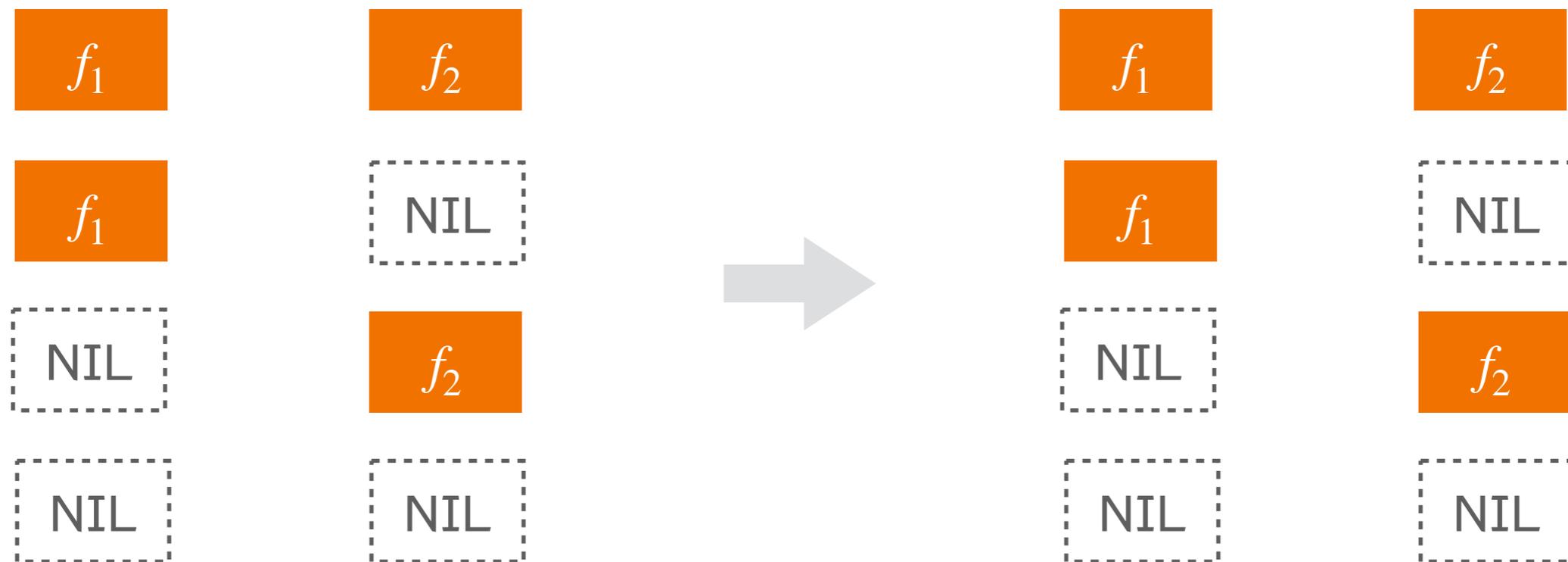
- They manipulate elements in $\mathcal{A}_{NIL} \stackrel{\text{def}}{=} \{NIL\} \cup \mathcal{A}$
- The **binary operators** rely on a tree unification algorithm
 - approximation order \preceq_A and computational order \sqsubseteq_A
 - approximation join \vee_A and computational join \sqcup_A
 - meet \wedge_A
 - widening ∇_A
- The **unary operators** rely on a tree pruning algorithm
 - assignment $\overleftarrow{\text{ASSIGN}}_A[[X \leftarrow e]]$
 - test $\text{FILTER}_A[[e]]$

Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification

Goal: find a **common refinement** for the given decision trees

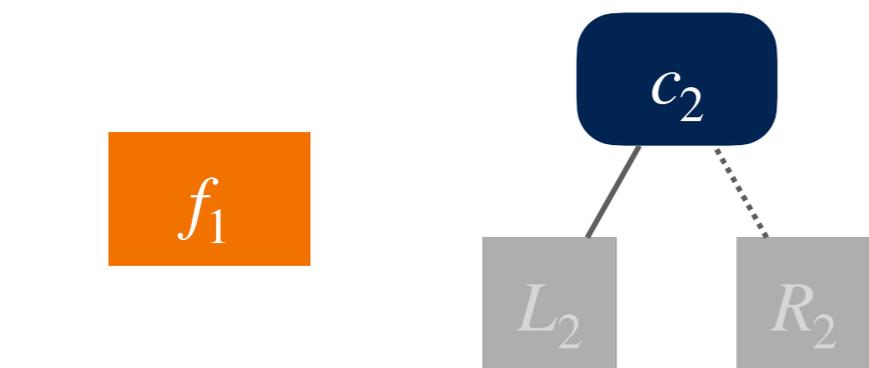
- Base cases:



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

- Case ①



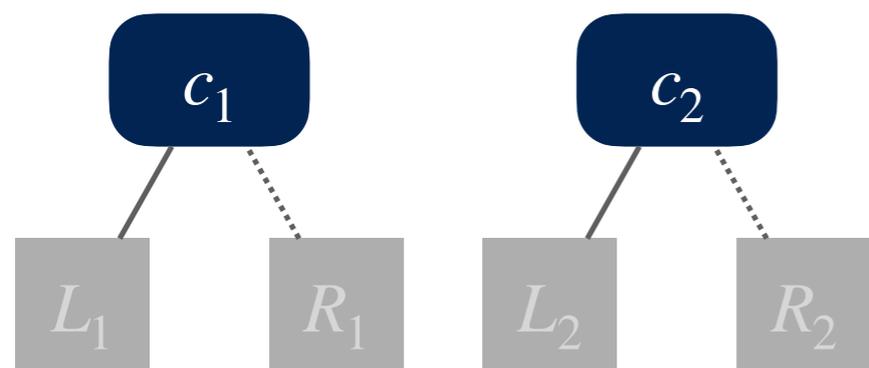
①a) c_2 is redundant



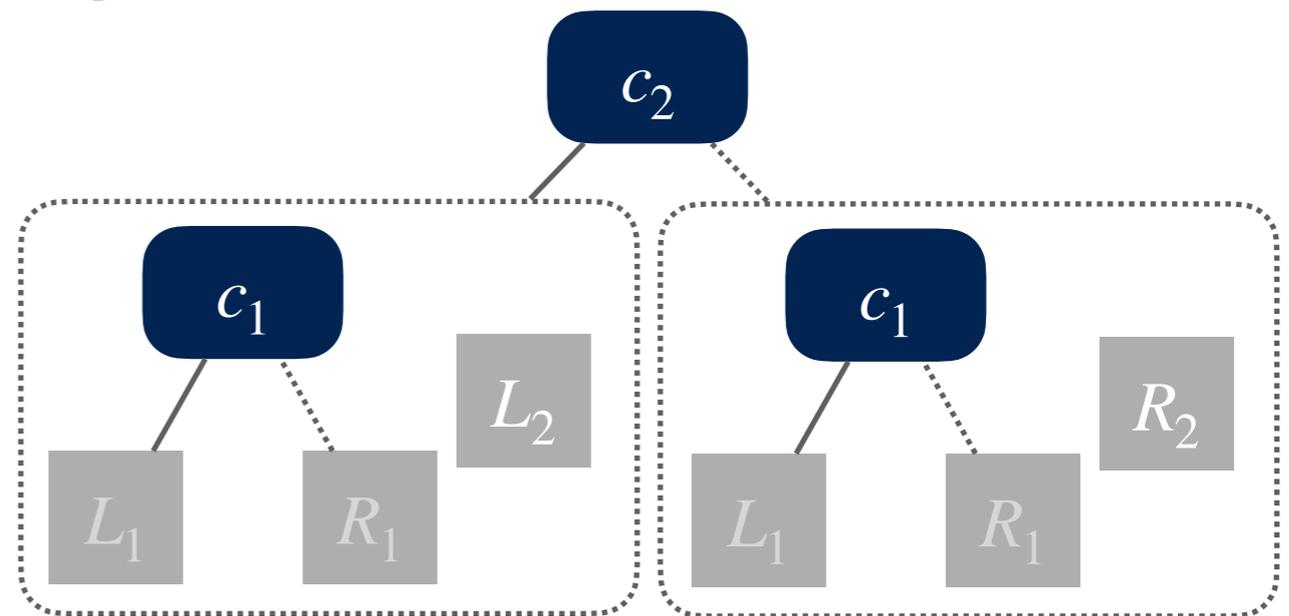
①b) $\neg c_2$ is redundant



①c) c_2 is added to t_1



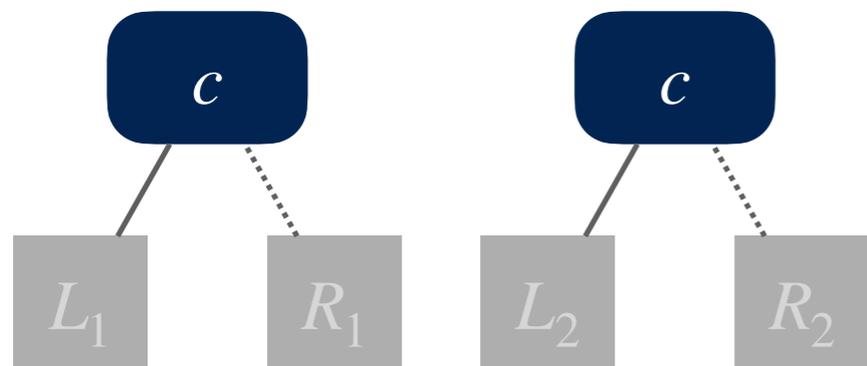
$$c_2 \leq_C c_1$$



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

- Case ② (symmetric to ①)
- Case ③



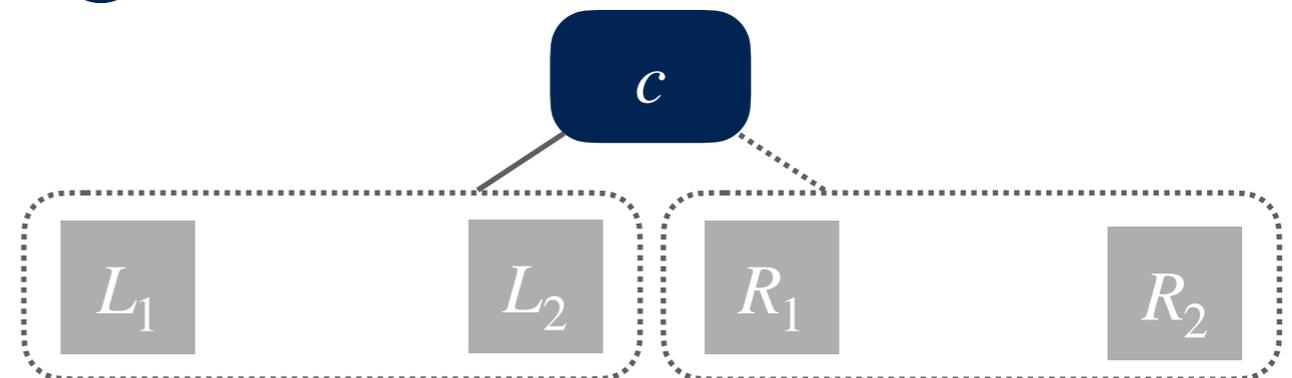
①a) c is redundant



①b) $\neg c$ is redundant



①c) c is kept in t_1 and t_2



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

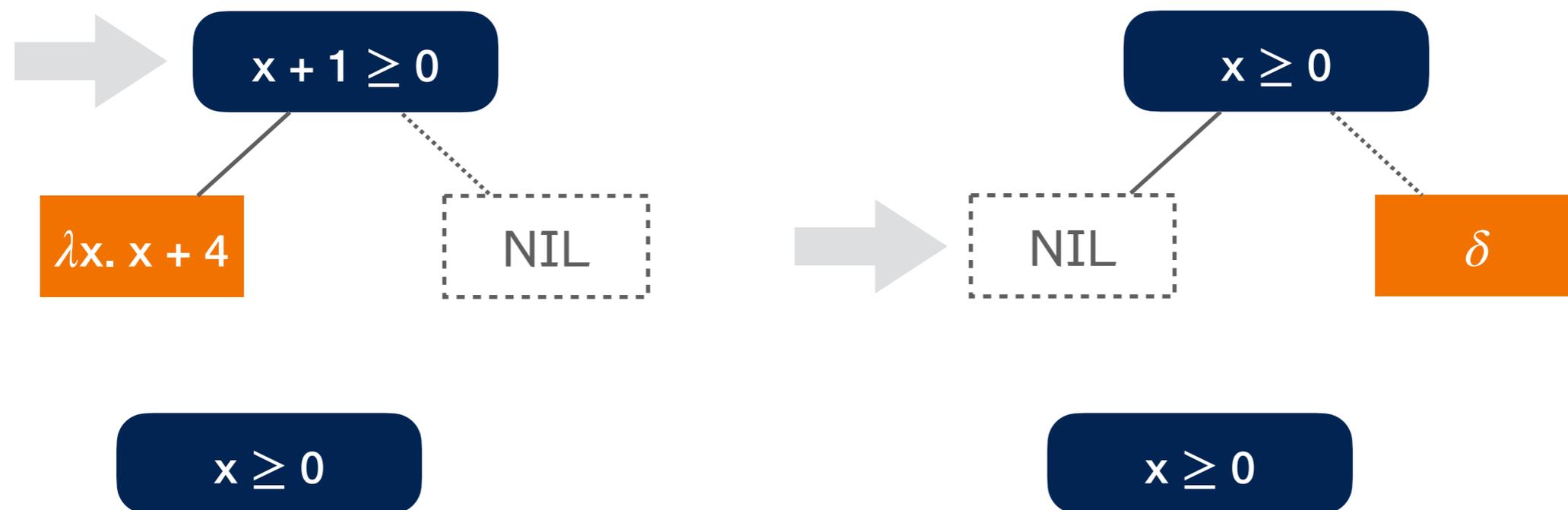
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

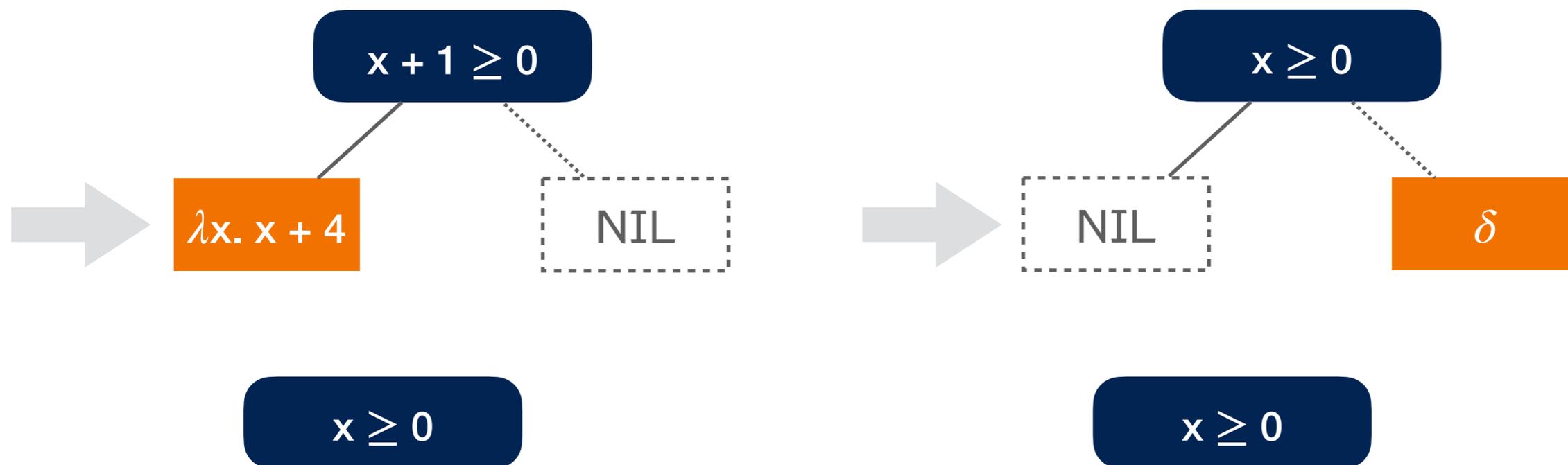
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

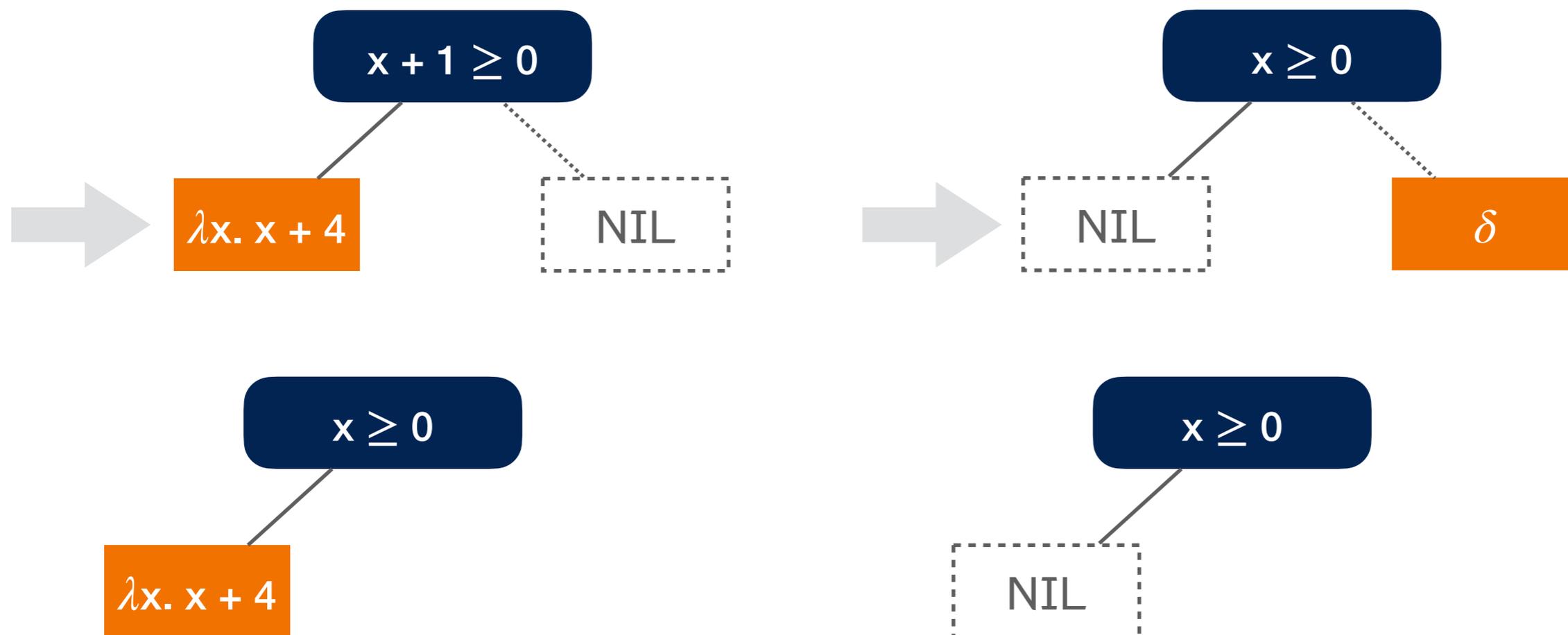
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

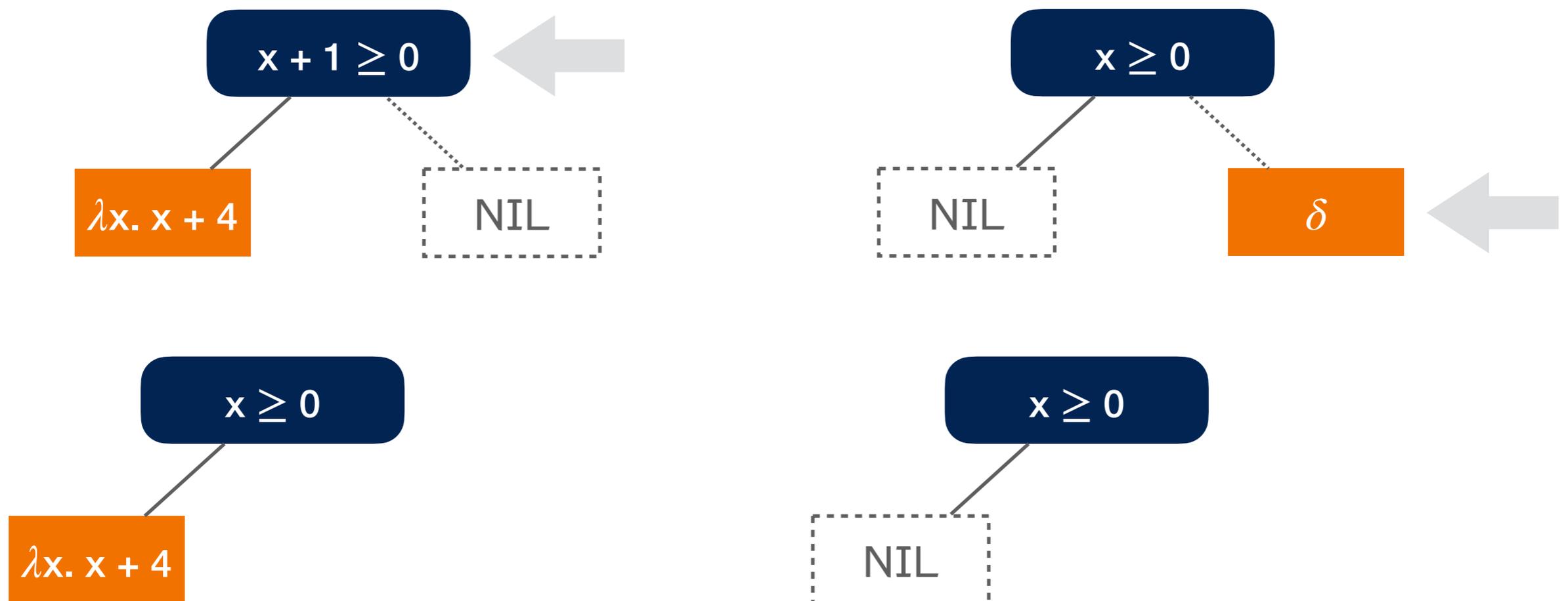
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

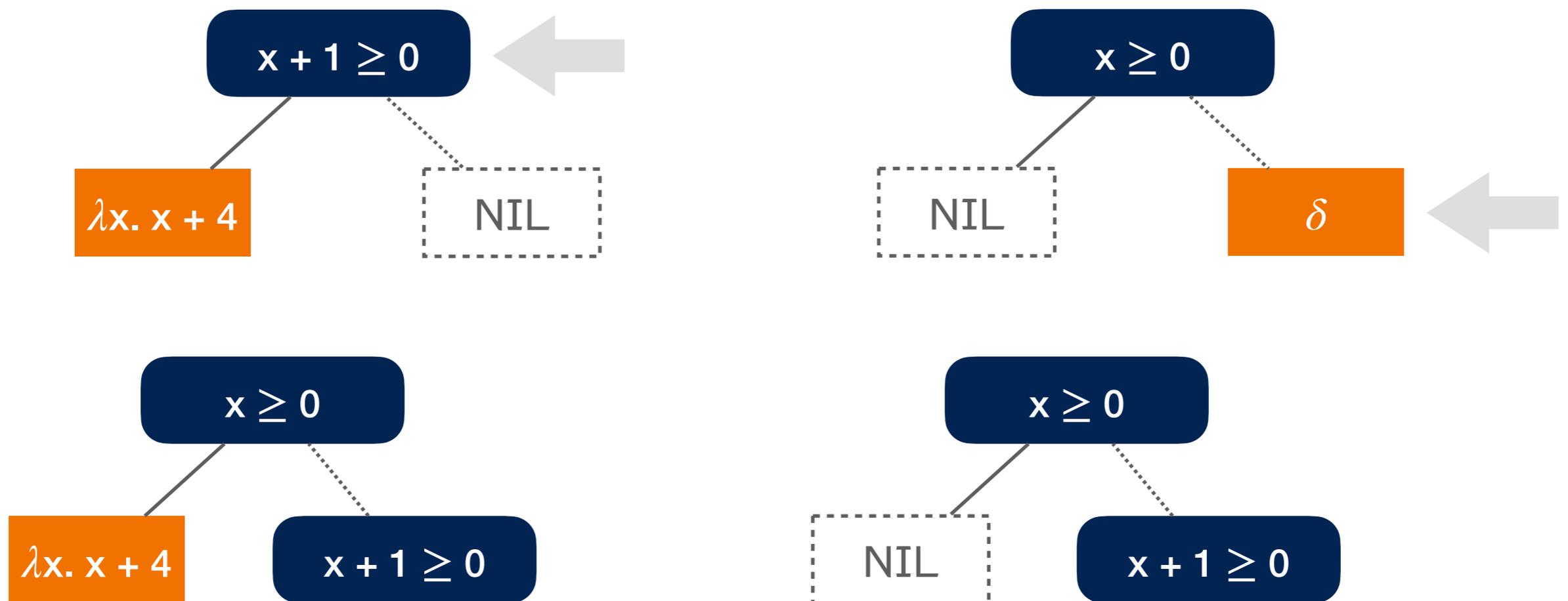
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

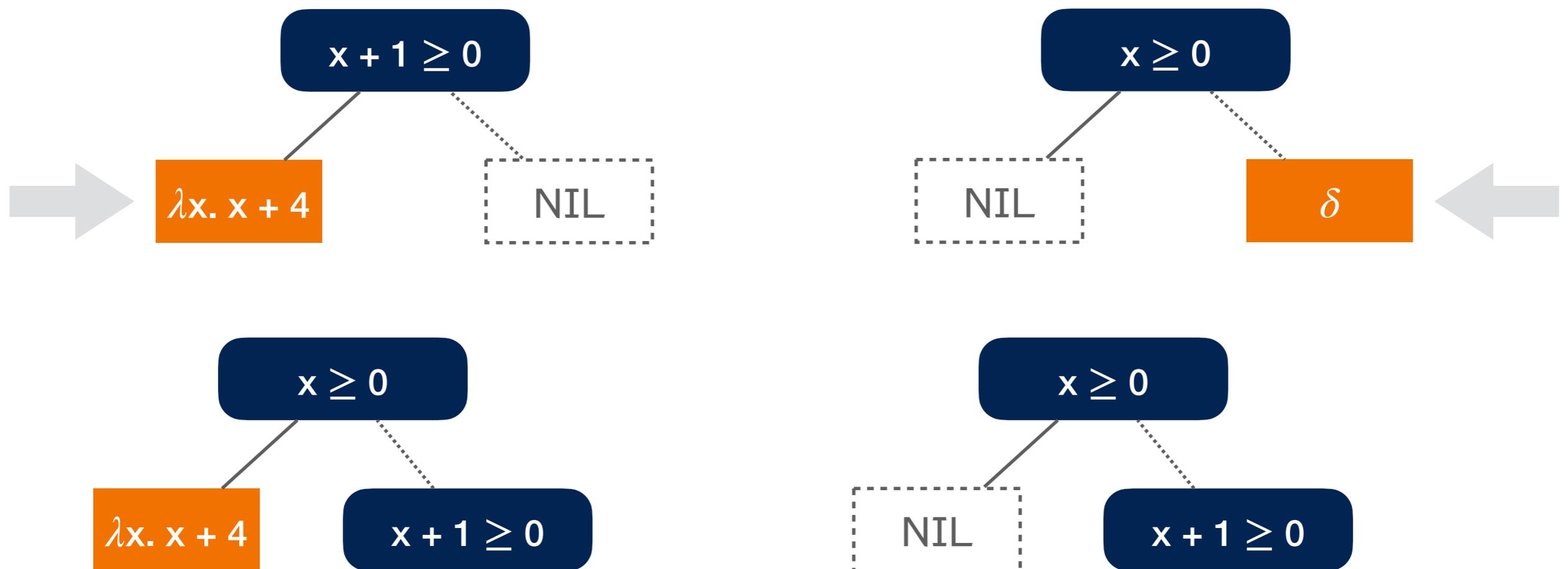
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

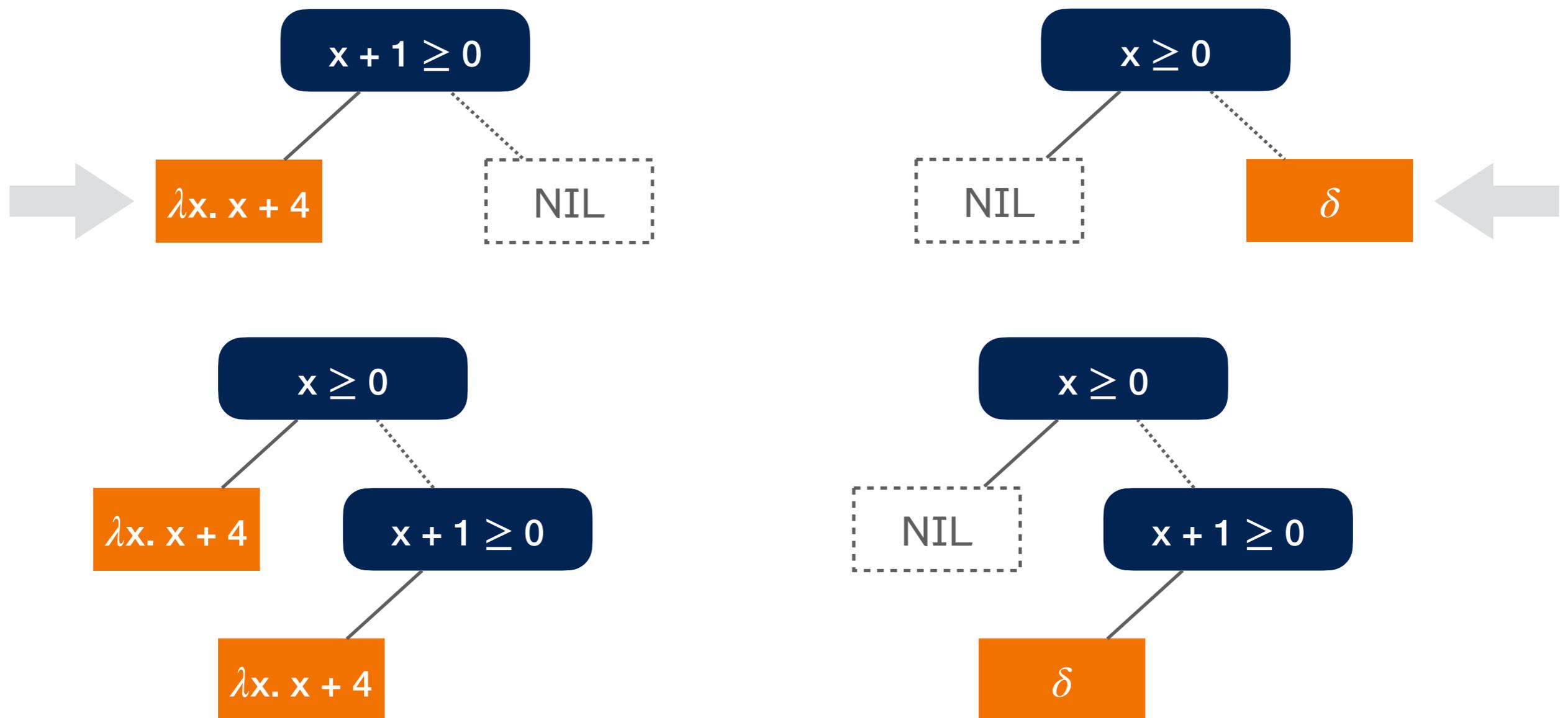
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

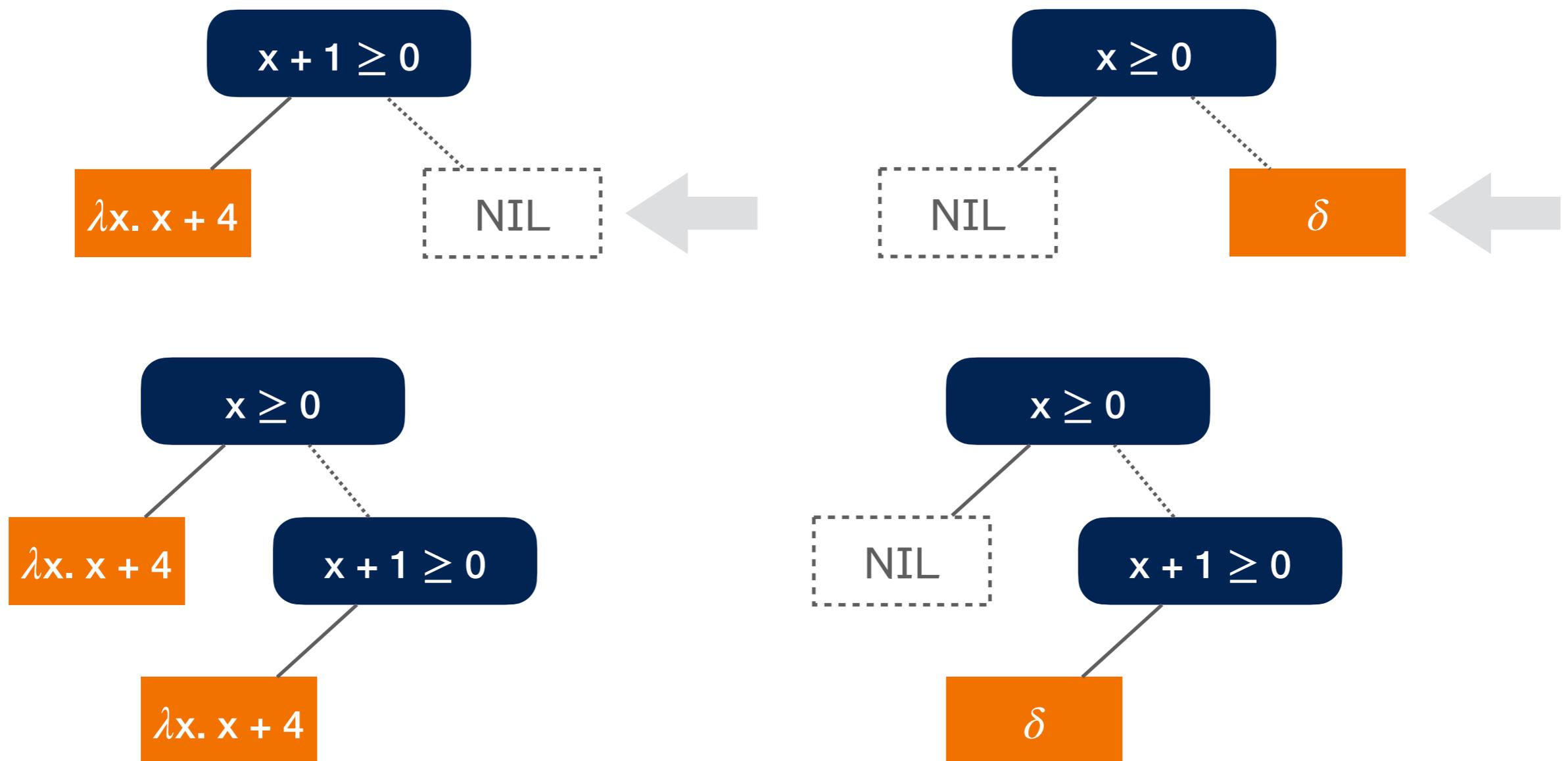
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

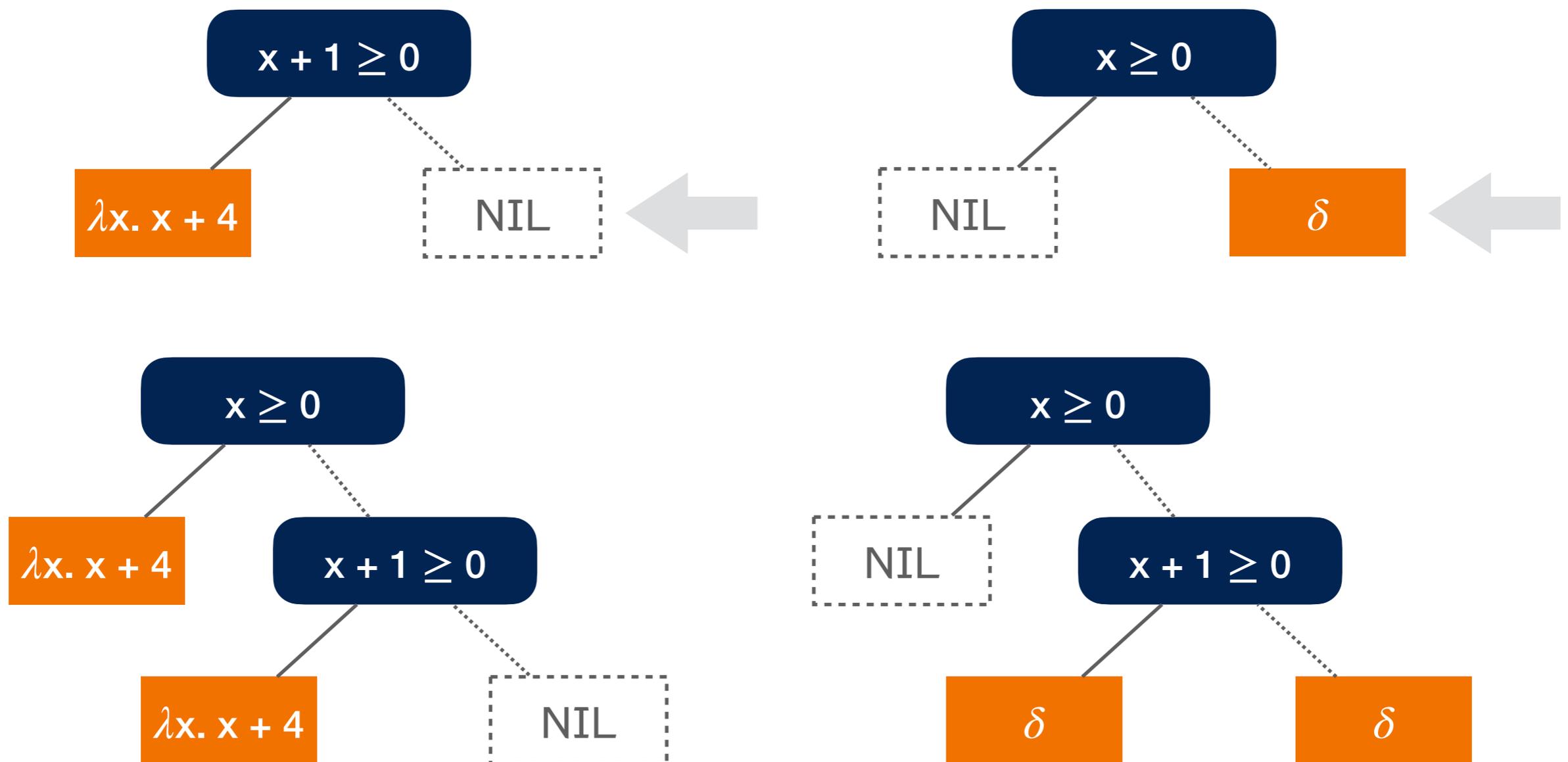
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

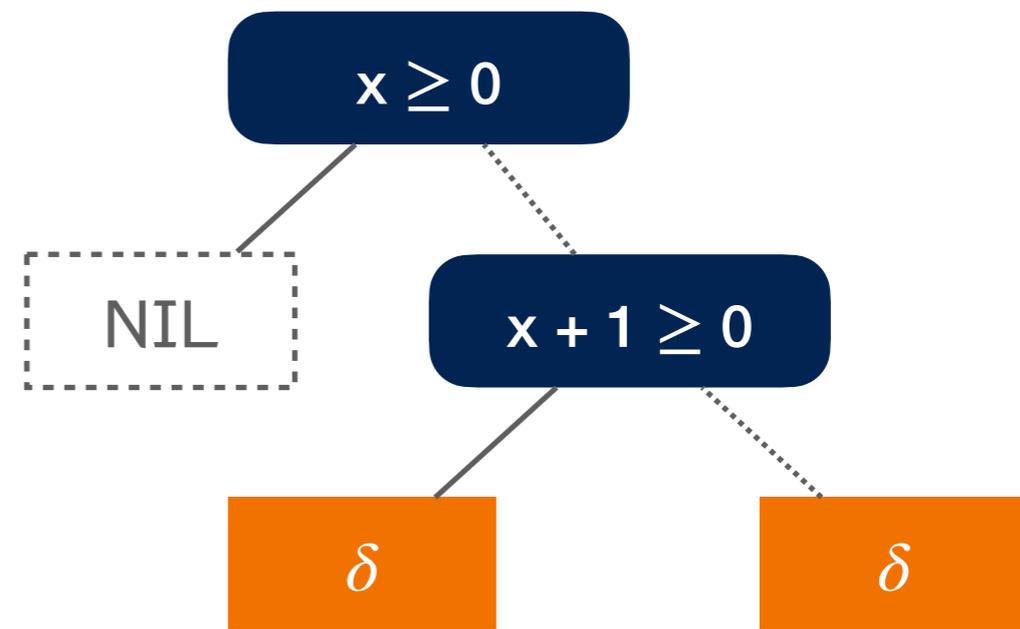
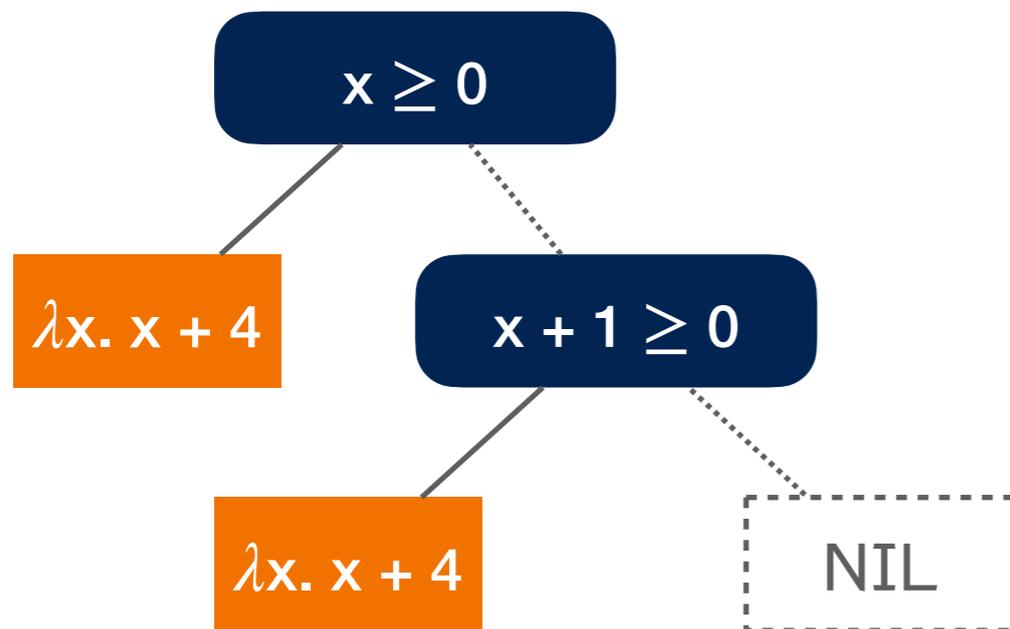
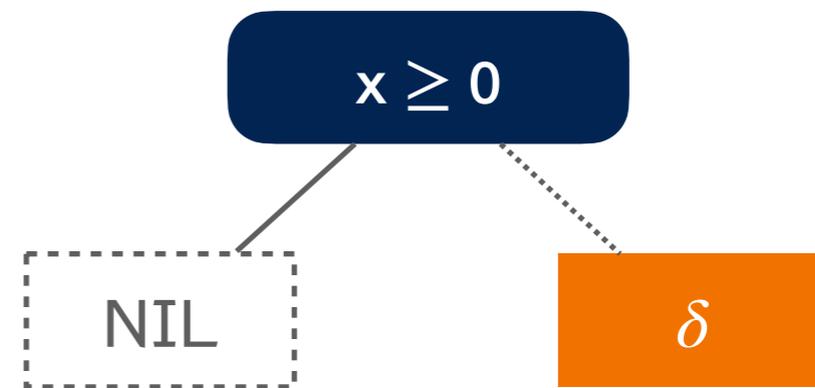
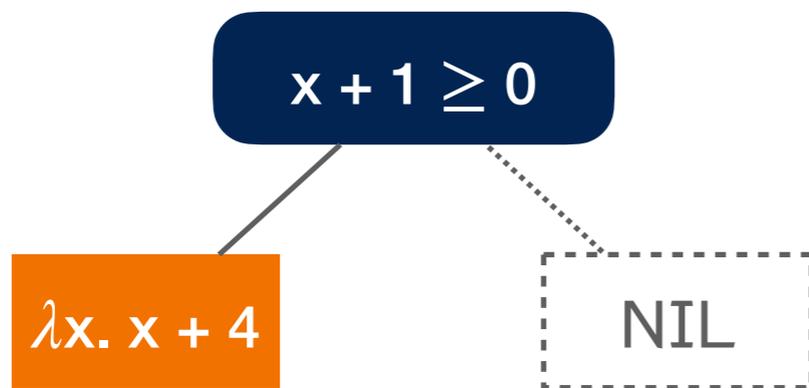
Example



Piecewise-Defined Ranking Functions Abstract Domain

Tree Unification (continue)

Example



Piecewise-Defined Ranking Functions Abstract Domain

Order

1. Perform **tree unification**
2. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C
3. Compare the leaf nodes using the **approximation order** $\preceq_F[\alpha_C(C)]$ or the **computational order** $\sqsubseteq_F[\alpha_C(C)]$

The concretization function γ_A is monotonic with respect to \preceq_A :

Lemma

$$\forall t_1, t_2 \in \mathcal{A} : t_1 \preceq_A t_2 \Rightarrow \gamma_A(t_1) \preceq \gamma_A(t_2)$$

Piecewise-Defined Ranking Functions Abstract Domain

Join

1. Perform **tree unification**
2. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C
3.
$$\text{NIL } \gamma_A t \stackrel{\text{def}}{=} t$$
$$t \gamma_A \text{NIL} \stackrel{\text{def}}{=} t$$
4. Join the leaf nodes using the **approximation join** $\gamma_F [\alpha_C(C)]$ or the **computational join** $\sqcup_F [\alpha_C(C)]$

Piecewise-Defined Ranking Functions Abstract Domain

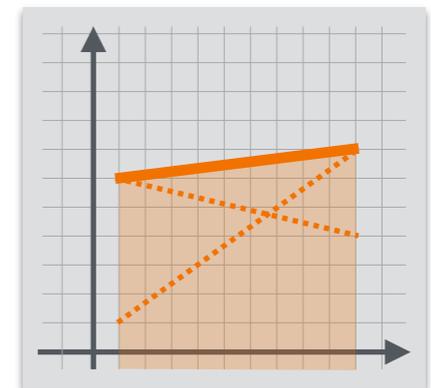
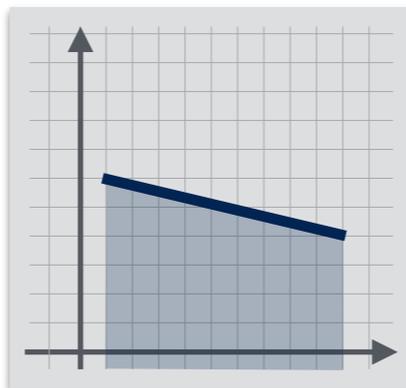
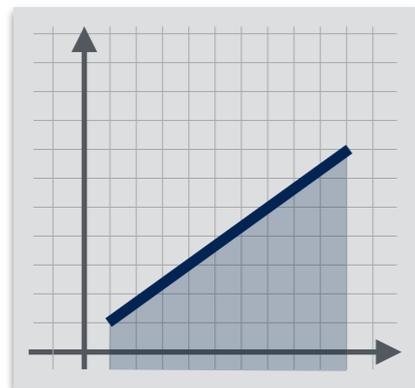
Join (continue)

- **approximation join** $\vee_F [D]$, where $D \in \mathcal{D}$:
- between defined leaf nodes:

$$f_1 \vee_F [D] f_2 \stackrel{\text{def}}{=} \begin{cases} f & f \in \mathcal{F} \setminus \{ \perp_F, \top_F \} \\ \top_F & \text{otherwise} \end{cases}$$

where $f \stackrel{\text{def}}{=}} \lambda \rho \in \gamma_D(D) : \max(f_1(\dots, \rho(X_i), \dots), f_2(\dots, \rho(X_i), \dots))$

Example:



Piecewise-Defined Ranking Functions Abstract Domain

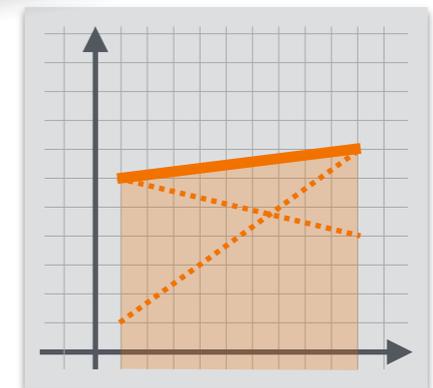
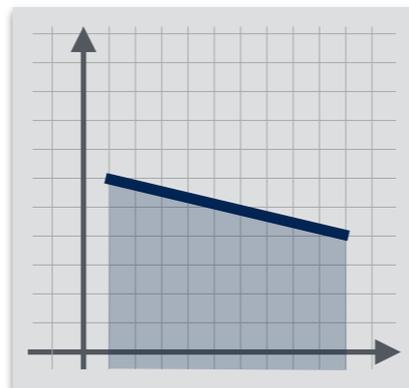
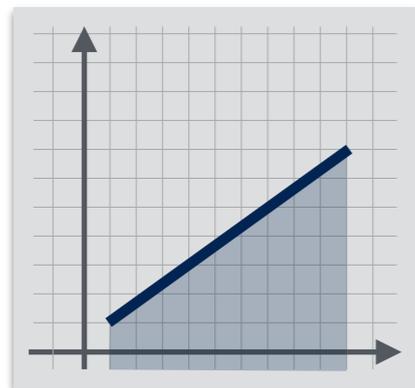
Join (continue)

- approximation join $\vee_F [D]$, where L
- between defined leaf nodes:

$$f_1 \vee_F [D] f_2 \stackrel{\text{def}}{=} \begin{cases} f & f \in \mathcal{F} \setminus \{ \dots \} \\ \top_F & \text{otherwise} \end{cases}$$

where $f \stackrel{\text{def}}{=}} \lambda \rho \in \gamma_D(D) : \max(f_1(\dots$

Example:



Polyhedron domain

Operators on polyhedra: join

Join: $\mathcal{X}^\# \cup^\# \mathcal{Y}^\# \stackrel{\text{def}}{=}} [[\mathcal{P}_{\mathcal{X}^\#} \mathcal{P}_{\mathcal{Y}^\#}], [\mathcal{R}_{\mathcal{X}^\#} \mathcal{R}_{\mathcal{Y}^\#}]]$ (join generator sets)

Examples:

two polytopes

a point and a line

$\cup^\#$ is **optimal**:
we get the **topological closure of the convex hull** of $\gamma(\mathcal{X}^\#) \cup \gamma(\mathcal{Y}^\#)$

Course 04 Relational Numerical Abstract Domains Antoine Miné p. 34 / 73

Piecewise-Defined Ranking Functions Abstract Domain

Join (continue)

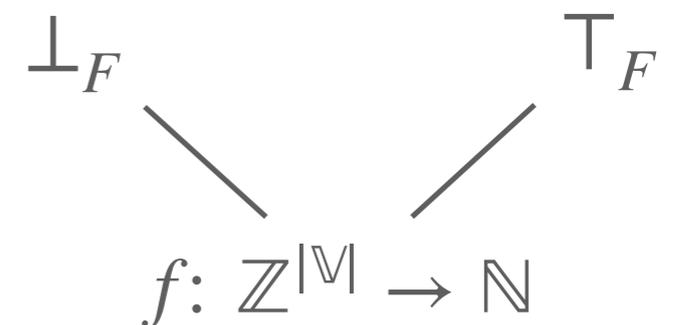
- **approximation join** $\vee_F [D]$, where $D \in \mathcal{D}$:
 - between defined leaf nodes:

$$f_1 \vee_F [D] f_2 \stackrel{\text{def}}{=} \begin{cases} f & f \in \mathcal{F} \setminus \{ \perp_F, \top_F \} \\ \top_F & \text{otherwise} \end{cases}$$

where $f \stackrel{\text{def}}{=} \lambda \rho \in \gamma_D(D) : \max(f_1(\dots, \rho(X_i), \dots), f_2(\dots, \rho(X_i), \dots))$

- otherwise (i.e., when one or both leaf nodes are undefined):

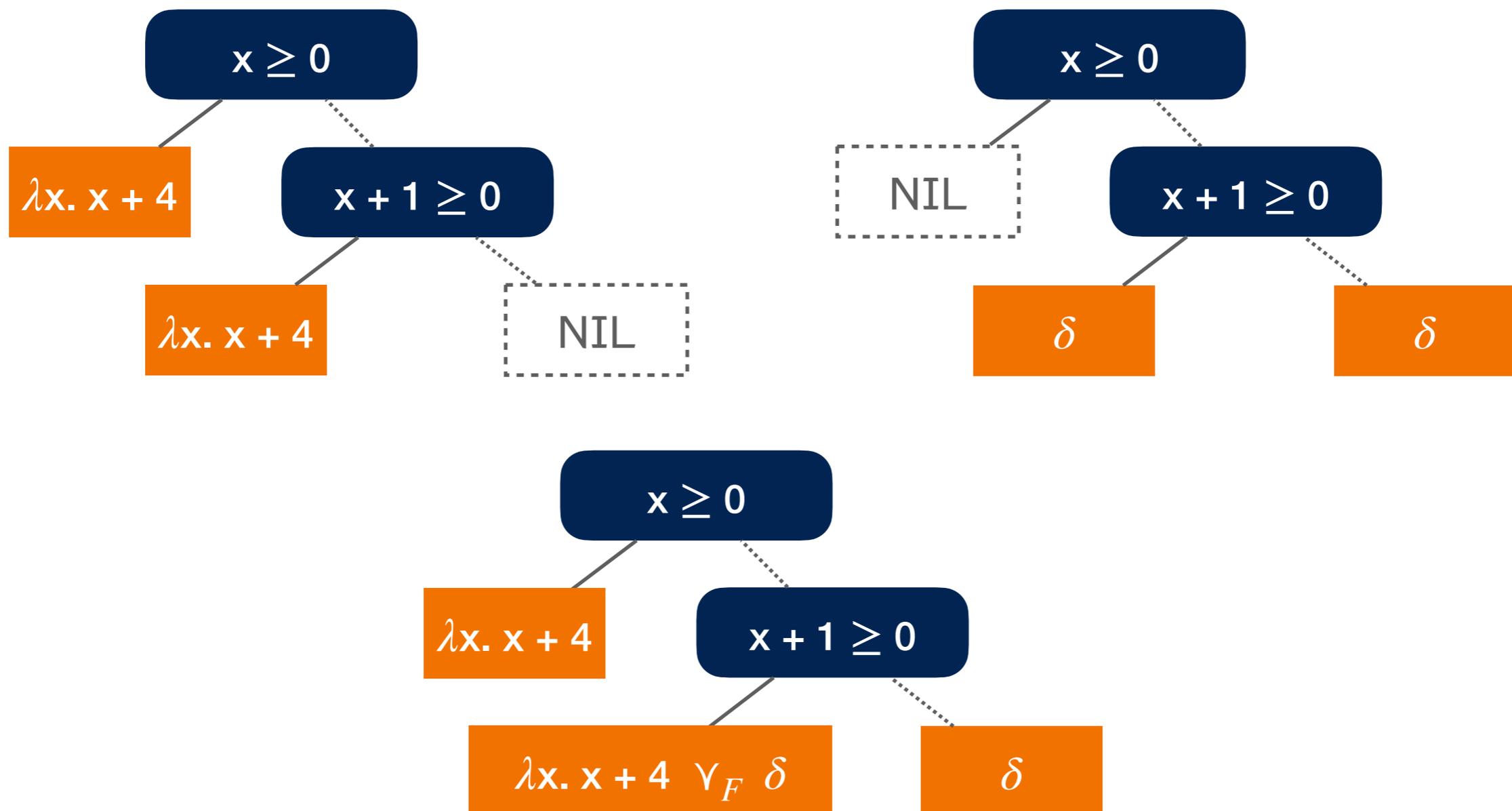
$$\begin{array}{ll} \perp_F \vee_F [D] f \stackrel{\text{def}}{=} \perp_F & f \in \mathcal{F} \setminus \{ \top_F \} \\ f \vee_F [D] \perp_F \stackrel{\text{def}}{=} \perp_F & f \in \mathcal{F} \setminus \{ \top_F \} \\ \top_F \vee_F [D] f \stackrel{\text{def}}{=} \top_F & f \in \mathcal{F} \setminus \{ \perp_F \} \\ f \vee_F [D] \top_F \stackrel{\text{def}}{=} \top_F & f \in \mathcal{F} \setminus \{ \perp_F \} \end{array}$$



Piecewise-Defined Ranking Functions Abstract Domain

Join (continue)

Example



Piecewise-Defined Ranking Functions Abstract Domain

Join (continue)

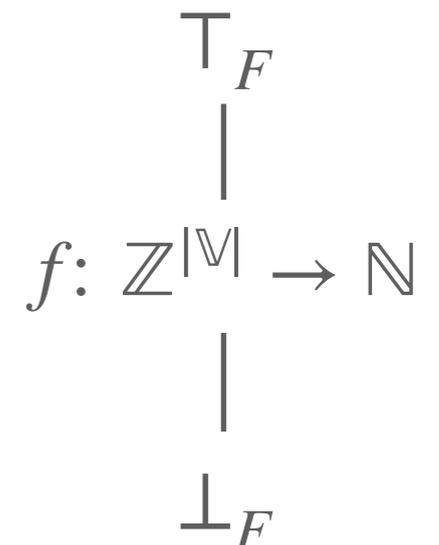
- **computational join** $\sqcup_F [D]$, where $D \in \mathcal{D}$:
 - between defined leaf nodes:

$$f_1 \vee_F [D] f_2 \stackrel{\text{def}}{=} \begin{cases} f & f \in \mathcal{F} \setminus \{ \perp_F, \top_F \} \\ \top_F & \text{otherwise} \end{cases}$$

where $f \stackrel{\text{def}}{=} \lambda \rho \in \gamma_D(D) : \max(f_1(\dots, \rho(X_i), \dots), f_2(\dots, \rho(X_i), \dots))$

- otherwise (i.e., when one or both leaf nodes are undefined):

$$\begin{aligned} \perp_F \sqcup_F [D] f &\stackrel{\text{def}}{=} f & f \in \mathcal{F} \\ f \sqcup_F [D] \perp_F &\stackrel{\text{def}}{=} f & f \in \mathcal{F} \\ \top_F \sqcup_F [D] f &\stackrel{\text{def}}{=} \top_F & f \in \mathcal{F} \\ f \sqcup_F [D] \top_F &\stackrel{\text{def}}{=} \top_F & f \in \mathcal{F} \end{aligned}$$



Piecewise-Defined Ranking Functions Abstract Domain

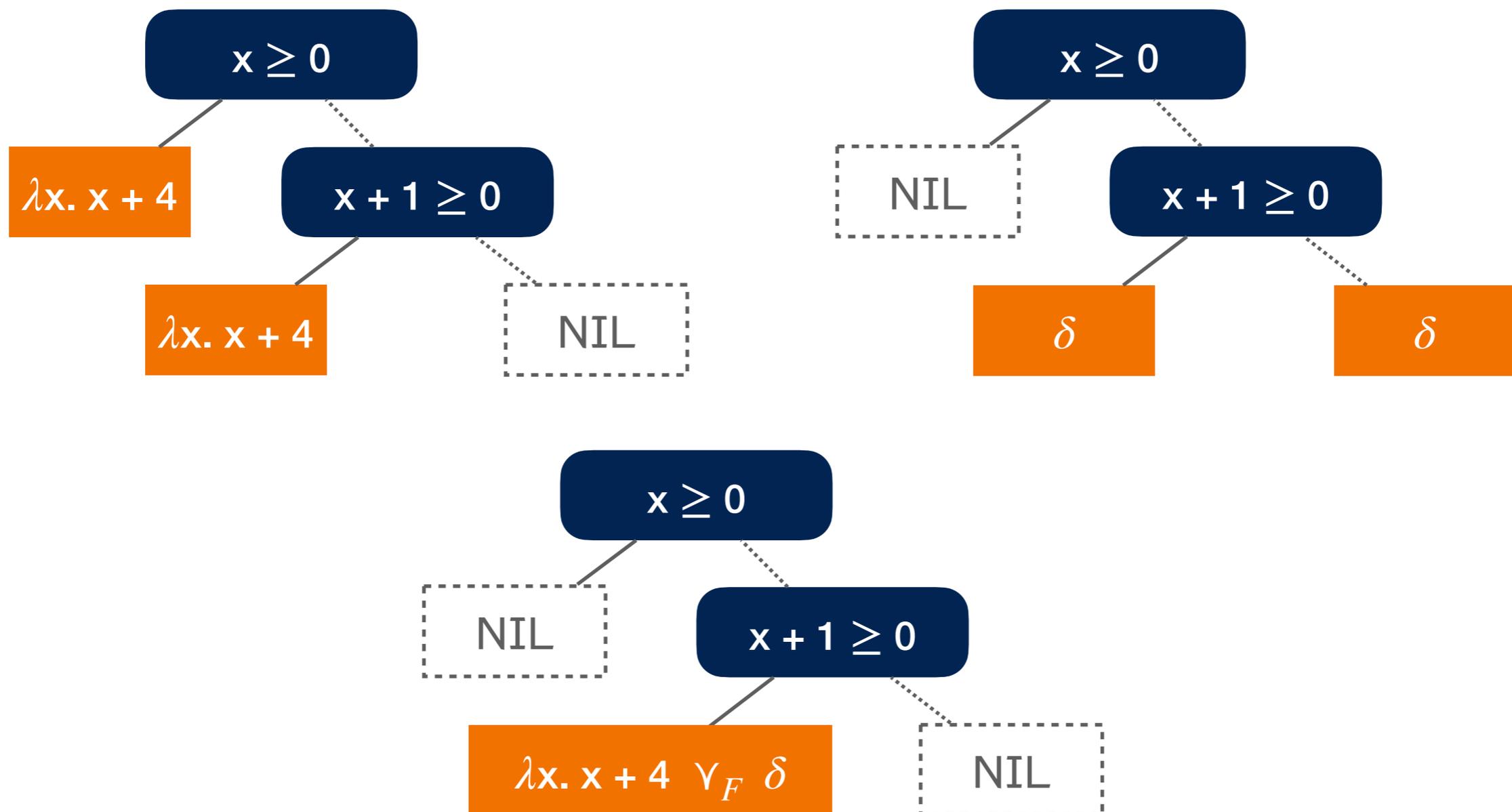
Meet

1. Perform **tree unification**
2. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C
3.
$$\begin{array}{l} \text{NIL } \gamma_A t \stackrel{\text{def}}{=} \text{NIL} \\ t \gamma_A \text{NIL} \stackrel{\text{def}}{=} \text{NIL} \end{array}$$
4. Join the leaf nodes using the **approximation join** $\gamma_F [\alpha_C(C)]$

Piecewise-Defined Ranking Functions Abstract Domain

Meet (continue)

Example



Piecewise-Defined Ranking Functions Abstract Domain

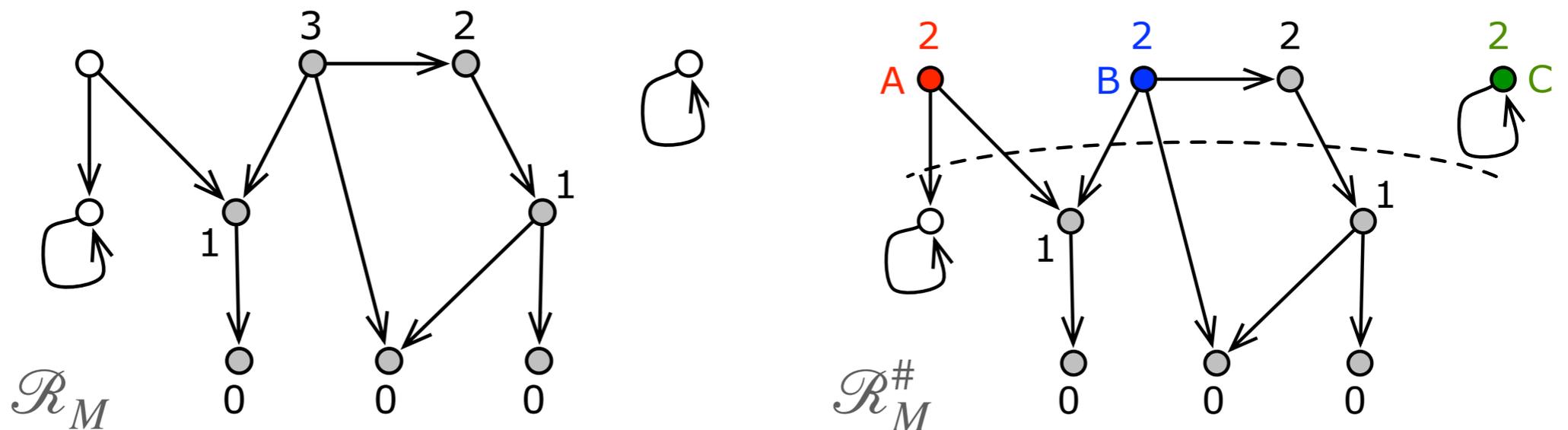
Widening

Goal: try to **predict** a valid ranking function

The prediction can (temporarily) be wrong!, i.e.,

- *under-approximates* the value of \mathcal{R}_M
- and/or
- *over-approximates* the domain $\text{dom}(\mathcal{R}_M)$ of \mathcal{R}_M

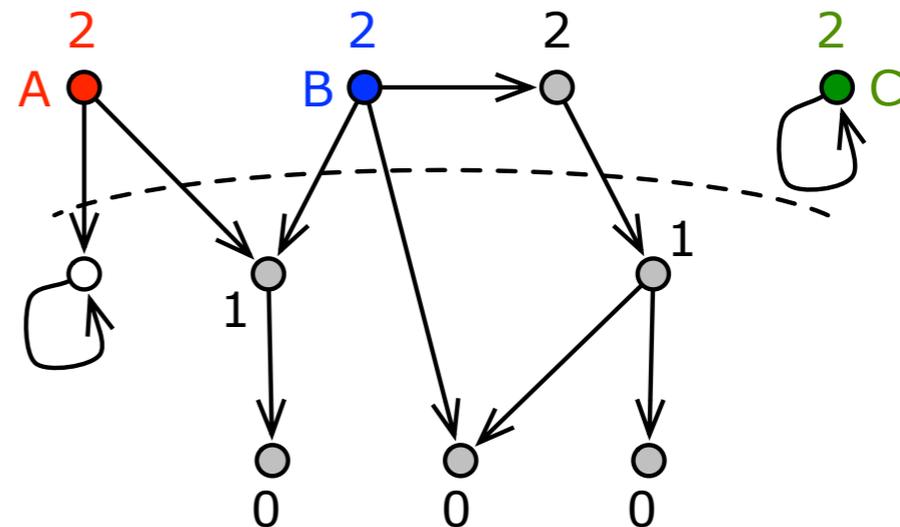
Example



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

1. Check for **case A** (i.e., wrong domain predictions)
2. Perform **domain widening**
3. Check for **case B or C** (i.e., wrong value predictions)
4. Perform **value widening**



Piecewise-Defined Ranking Functions Abstract Domain

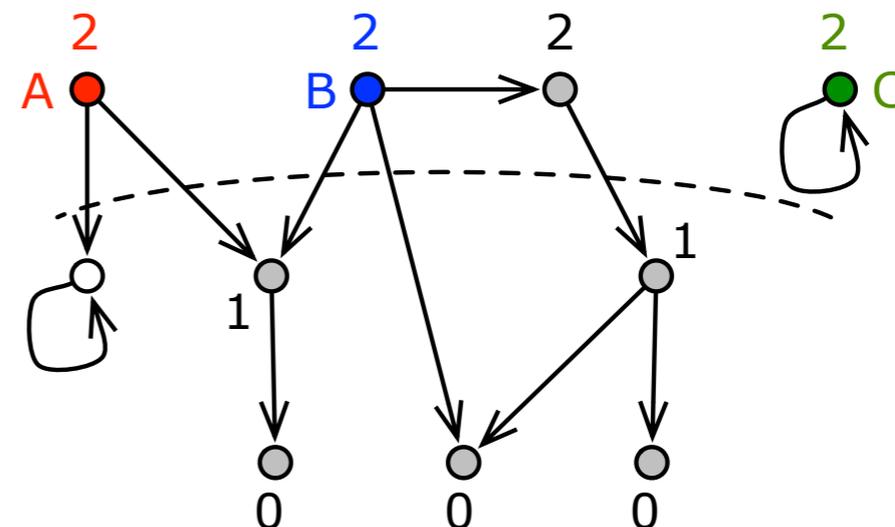
Widening (continue)

Check for Case A

Lemma

Let $\text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell)) \neq \emptyset$. Then, in case A, we have $\text{dom}(\gamma_A(\mathcal{R}_M^{\#n+1}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell)) \subset \text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell))$.

(see proof in [Urban15])



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Check for Case A

Lemma

Let $\text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell)) \neq \emptyset$. Then, in case A, we have $\text{dom}(\gamma_A(\mathcal{R}_M^{\#n+1}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell)) \subset \text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell))$.

(see proof in [\[Urban15\]](#))

1. Perform **tree unification**
2. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Domain Widening

Goal: **limit the size** of the decision trees

Left unification: variant of tree unification that forces the structure of t_1 on t_2

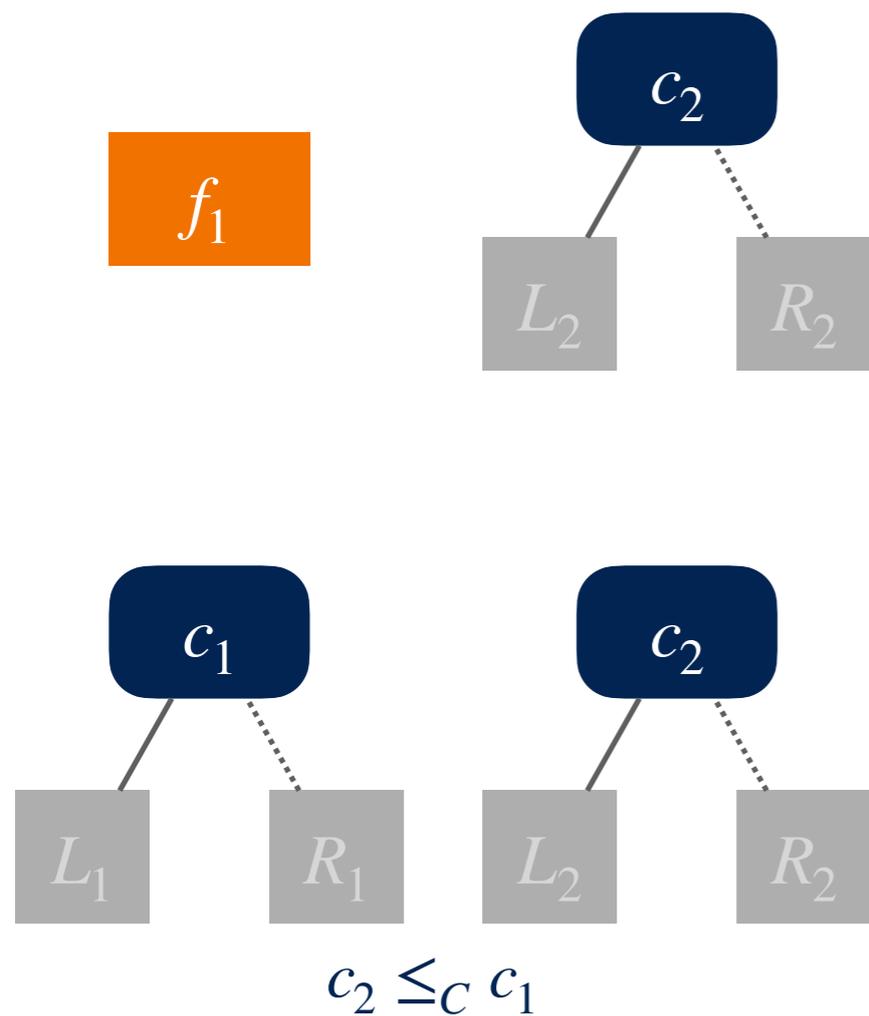
- Base case:



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

- Case ①



Domain Widening

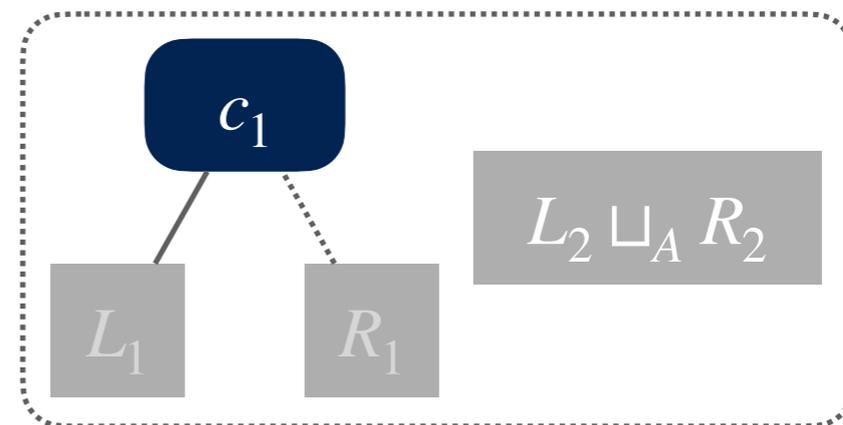
- ①a c_2 is redundant



- ①b $\neg c_2$ is redundant



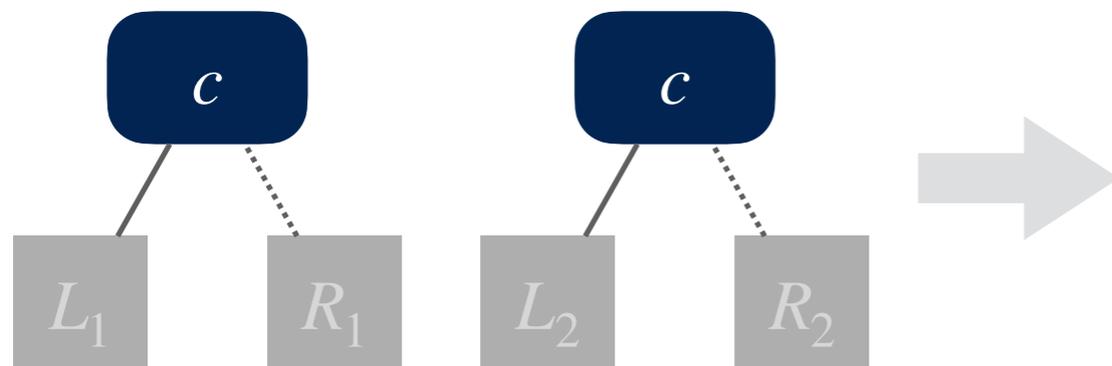
- ①c c_2 is removed from t_2



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

- Case ② (as for tree unification)
- Case ③



Domain Widening

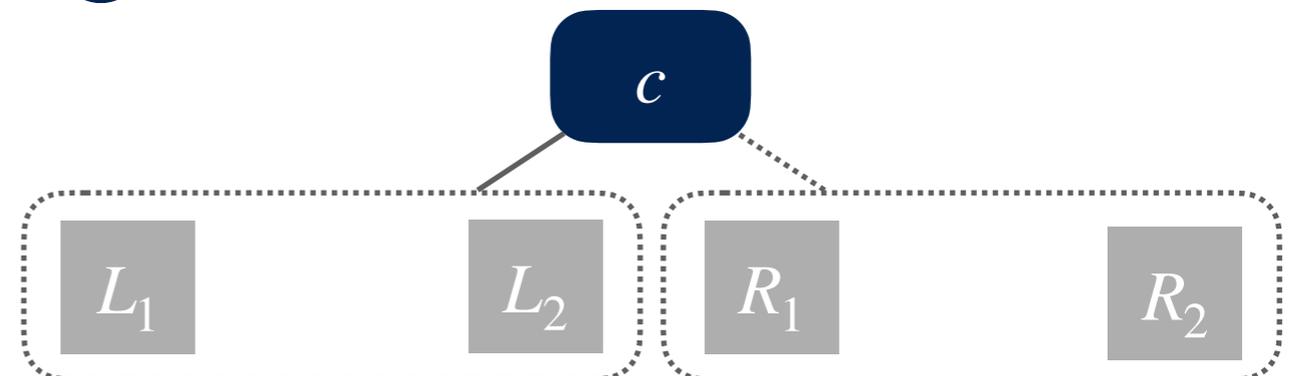
①a) c is redundant



①b) $\neg c$ is redundant



①c) c is kept in t_1 and t_2



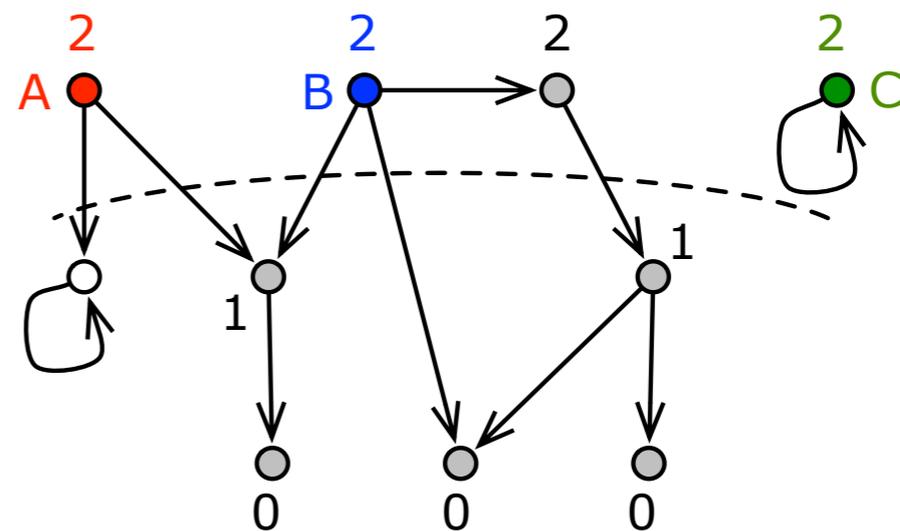
Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Check for Case B or C

Lemma

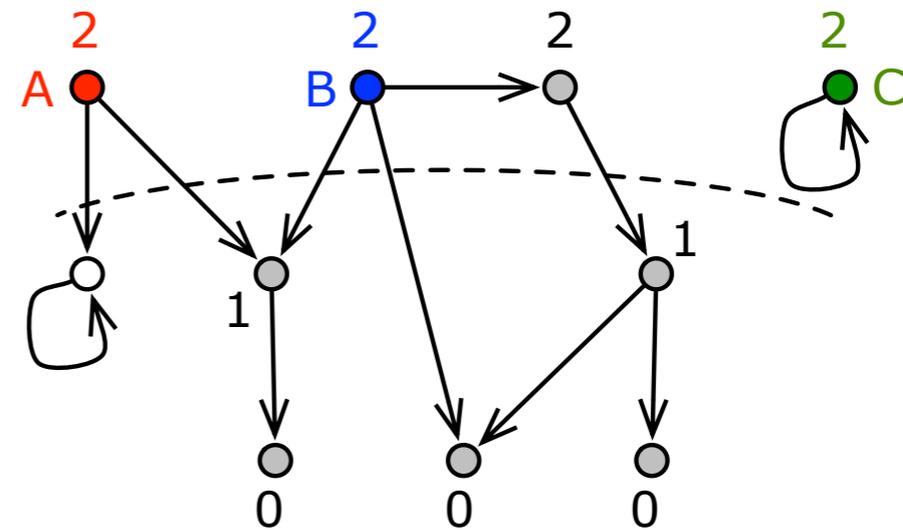
Let $\gamma_A(\mathcal{R}_M^{\#n}(\ell))(\bar{\rho}) < \mathcal{R}_M(\ell)(\bar{\rho})$ for some $\bar{\rho} \in \text{dom}(\mathcal{R}_M(\ell)) \cap \text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell)))$ (case B). Then, there exists $\rho \in \text{dom}(\gamma_A(\mathcal{R}_M^{\#n+1}(\ell))) \cap \text{dom}(\mathcal{R}_M^{\#n}(\ell))$ such that $\gamma_A(\mathcal{R}_M^{\#n}(\ell))(\rho) < \gamma_A(\mathcal{R}_M^{\#n+1}(\ell))(\rho)$.



Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Check for Case B or C



Lemma

Let $\text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell)) \neq \emptyset$. Then, for all $\rho \in \text{dom}(\gamma_A(\mathcal{R}_M^{\#n}(\ell))) \setminus \text{dom}(\mathcal{R}_M(\ell))$ in case C, we have $\gamma_A(\mathcal{R}_M^{\#n}(\ell))(\rho) < \gamma_A(\mathcal{R}_M^{\#n+1}(\ell))(\rho)$.

(see proof in [\[Urban15\]](#))

Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Check for Case B or C

1. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C



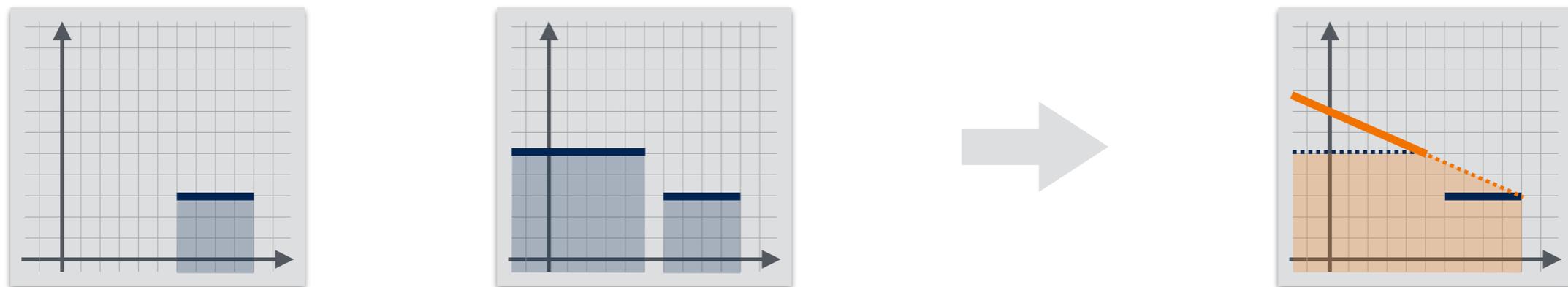
Piecewise-Defined Ranking Functions Abstract Domain

Widening (continue)

Value Widening

1. Recursively descend the trees while *accumulating the linear constraints encountered along the paths* into a set of constraints C
2. Widen each (defined) leaf node f with respect to each of their adjacent (defined) leaf node \bar{f} using the **extrapolation operator** $\nabla_F [\alpha_C(\bar{C}), \alpha_C(C)]$, where \bar{C} is the set of constraints along the path to \bar{f}

Example:

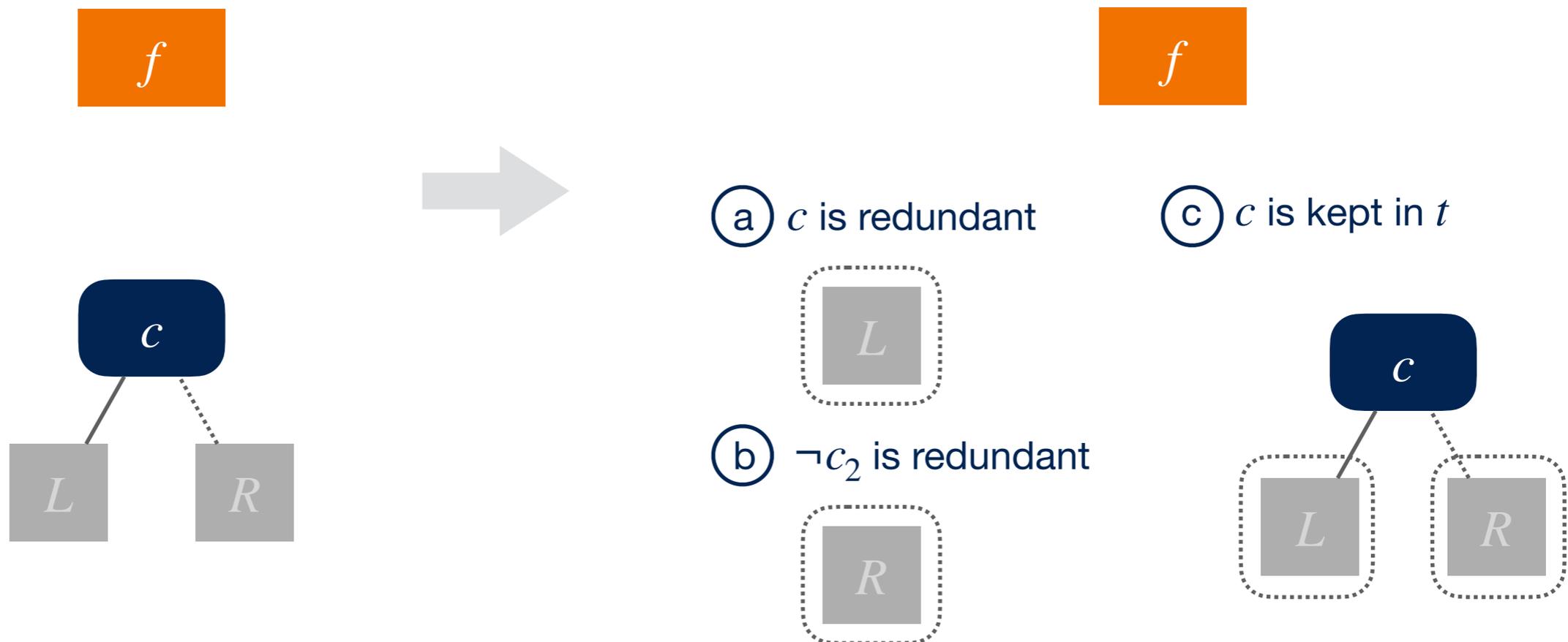


Piecewise-Defined Ranking Functions Abstract Domain

Tree Pruning

Goal: **add** a set J of **linear constraints** to the decision tree

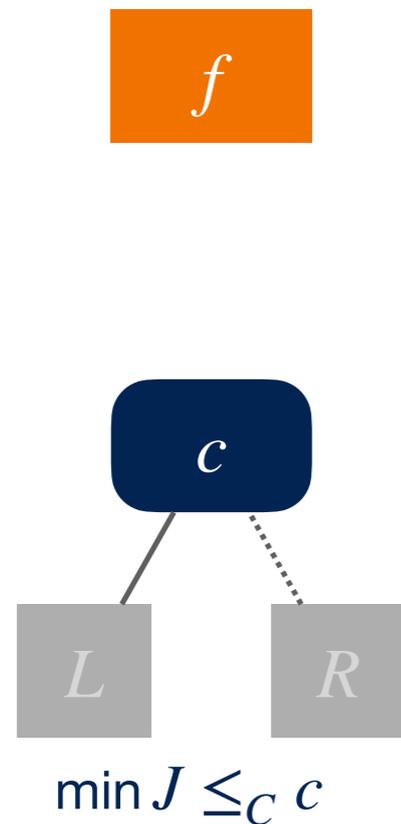
- Base case ($J = \emptyset$)



Piecewise-Defined Ranking Functions Abstract Domain

Tree Pruning (continue)

- Case ①



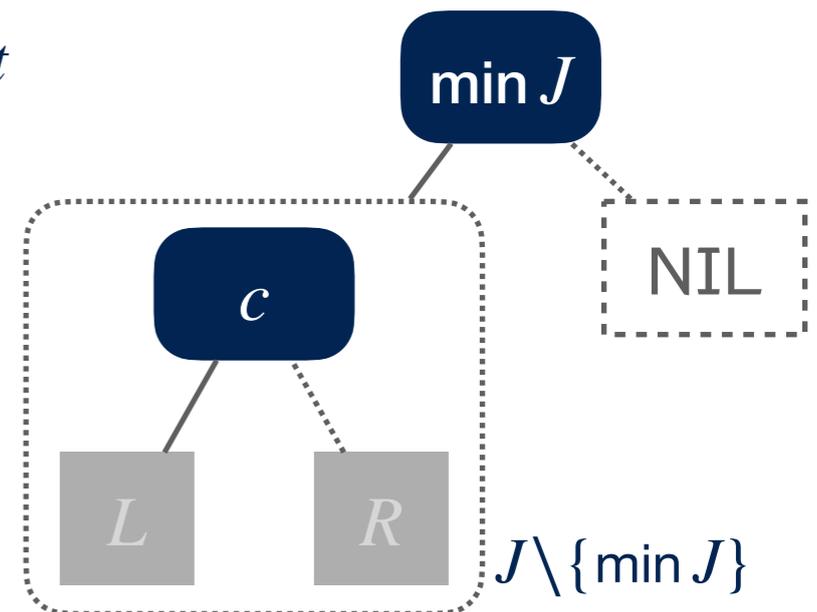
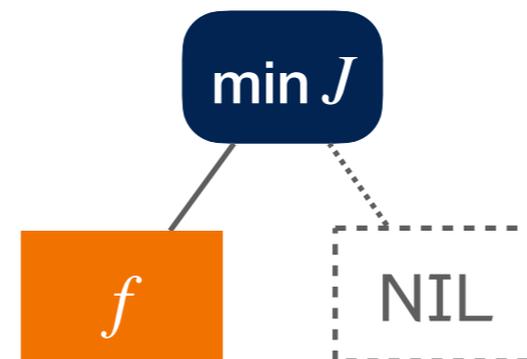
①a) $\min J$ is redundant



①b) $\neg \min J$ is redundant



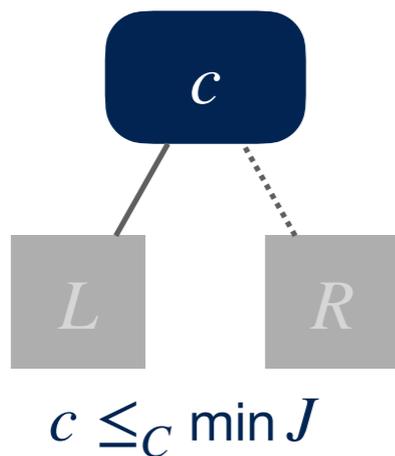
①c) $\min J$ is added to t



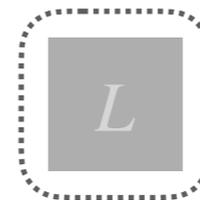
Piecewise-Defined Ranking Functions Abstract Domain

Tree Pruning (continue)

- Case ②



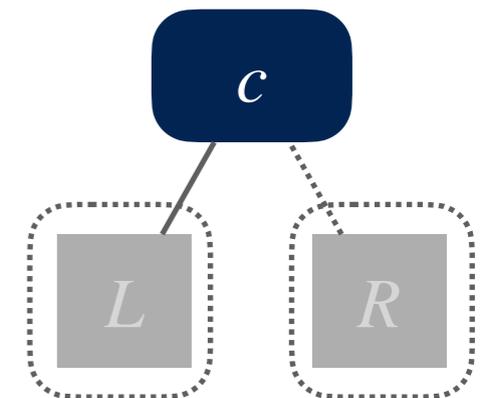
- ②a) c is redundant



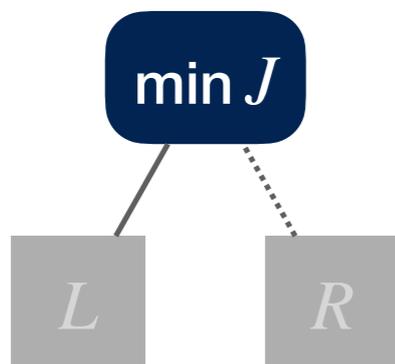
- ②b) $\neg c_2$ is redundant



- ②c) c is kept in t



- Case ③



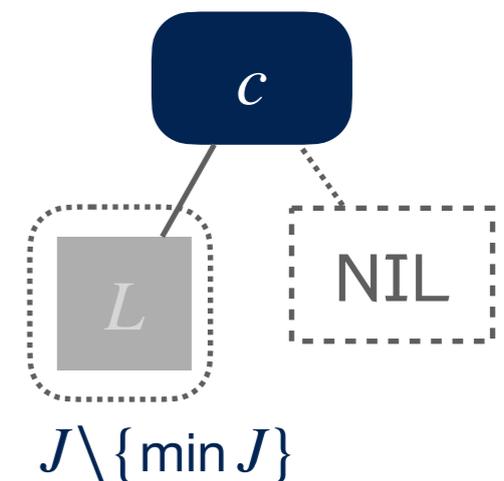
- ③a) $\min J$ is redundant



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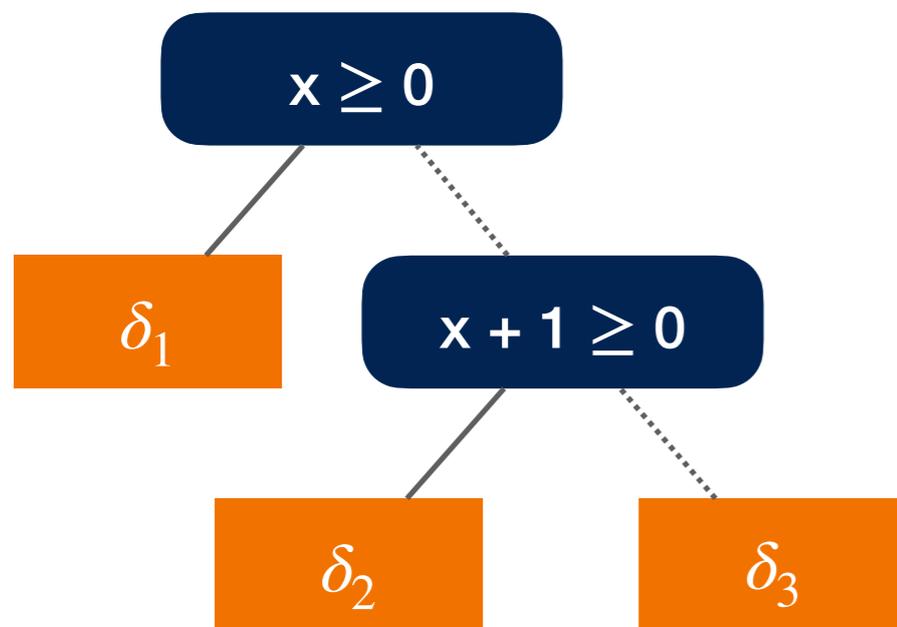
- ③c) $\min J$ is kept in t



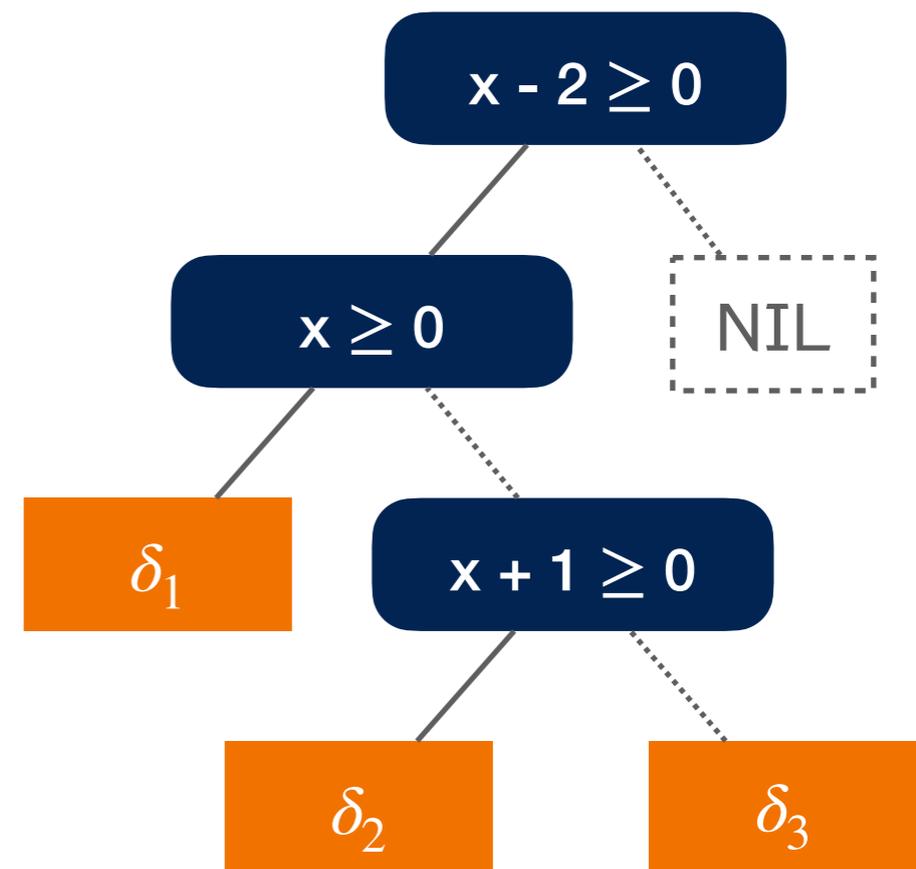
Piecewise-Defined Ranking Functions Abstract Domain

Tree Pruning (continue)

Example



$J \stackrel{\text{def}}{=} \{x - 2 \geq 0\}$



Piecewise-Defined Ranking Functions Abstract Domain

Assignments

$$\overleftarrow{\text{ASSIGN}}_A[[X \leftarrow e]]$$

- Base case (f)

Apply $\overleftarrow{\text{ASSIGN}}_F[[X \leftarrow e]][\alpha_C(C)]$ on the defined leaf nodes

$$\overleftarrow{\text{ASSIGN}}_F[[X \leftarrow e]][D](f) \stackrel{\text{def}}{=} \begin{cases} \bar{f} & \bar{f} \in \mathcal{F} \setminus \{ \perp_F, \top_F \} \\ \top_F & \text{otherwise} \end{cases} \quad f \in \mathcal{F} \setminus \{ \perp_F, \top_F \}$$

where $\bar{f}(\dots, X_i, X, \dots) \stackrel{\text{def}}{=} \max\{f(\dots, \rho(X_i), v, \dots) + 1 \mid \rho \in \gamma_D(R) \wedge v \in E[[e]]\rho\}$
and $R \stackrel{\text{def}}{=} \overleftarrow{\text{ASSIGN}}_D[[X \leftarrow e]]D$

Example:

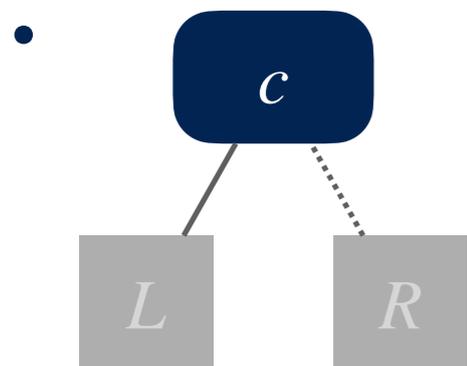
$$\overleftarrow{\text{ASSIGN}}_F[[x \leftarrow x + [1,2]]][\top_D](\lambda x . x + 1) = \lambda x . x + 4$$

(since $f(x + [1,2]) + 1 = x + [1,2] + 1 + 1 = x + [3,4]$ and $\max(3,4) = 4$)

Piecewise-Defined Ranking Functions Abstract Domain

Assignments

$$\overleftarrow{\text{ASSIGN}}_A[[X \leftarrow e]]$$



Convert $\overleftarrow{\text{ASSIGN}}_D[[X \leftarrow e]](\alpha_C(\{c\}))$ and $\overleftarrow{\text{ASSIGN}}_D[[X \leftarrow e]](\alpha_C(\{\neg c\}))$ into sets I and J of linear constraints *in canonical form*

case ① $I = J = \emptyset$



case ② $I = \emptyset \wedge \perp_C \in J$



case ③ $\perp_C \in I \wedge J = \emptyset$



case ④

1. perform **tree pruning** on  and 

2. join the results with γ_A

Piecewise-Defined Ranking Functions Abstract Domain

Tests

$\text{FILTER}_A[[e]]$

1. Recursively descend the tree and apply STEP_F on the defined leaf nodes to account for one more execution step needed before termination:

$$\text{STEP}_F(f) \stackrel{\text{def}}{=} \lambda X_1, \dots, X_k. f(X_1, \dots, X_k) + 1 \quad f \in \mathcal{F} \setminus \{ \perp_F, \top_F \}$$

2. **Convert e into a set J of linear constraints in canonical form**

Example: $\alpha_C(\text{FILTER}_D[[e]] \top_D)$

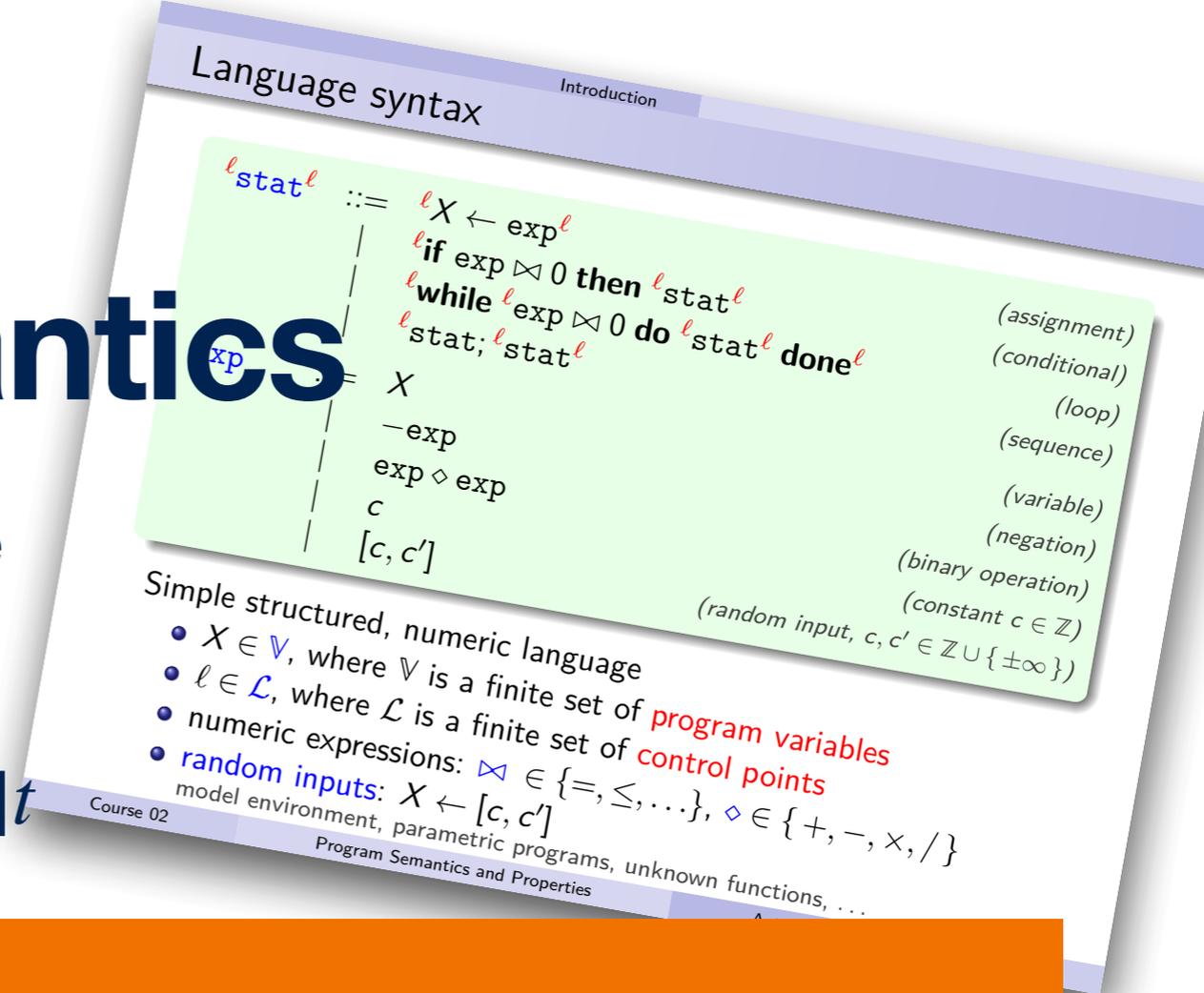
where $\langle \mathcal{D}, \sqsubseteq_D \rangle$ is the underlying numerical domain

3. **Perform tree pruning with J**

Abstract Definite Termination Semantics

For each program instruction stat , we define a transformer $\mathcal{R}_M^\# \llbracket \text{stat} \rrbracket : \mathcal{A} \rightarrow \mathcal{A}$:

- $\mathcal{R}_M^\# \llbracket \ell X \leftarrow e \rrbracket t \stackrel{\text{def}}{=} \text{ASSIGN}_A \llbracket X \leftarrow e \rrbracket t$



Lemma (Soundness)

$$\mathcal{R}_M \llbracket \ell X \leftarrow e \rrbracket \gamma_A(t) \preceq \gamma_A(\mathcal{R}_M^\# \llbracket \ell X \leftarrow e \rrbracket t)$$

(see proof in [Urban15])

Abstract Definite Termination Semantics

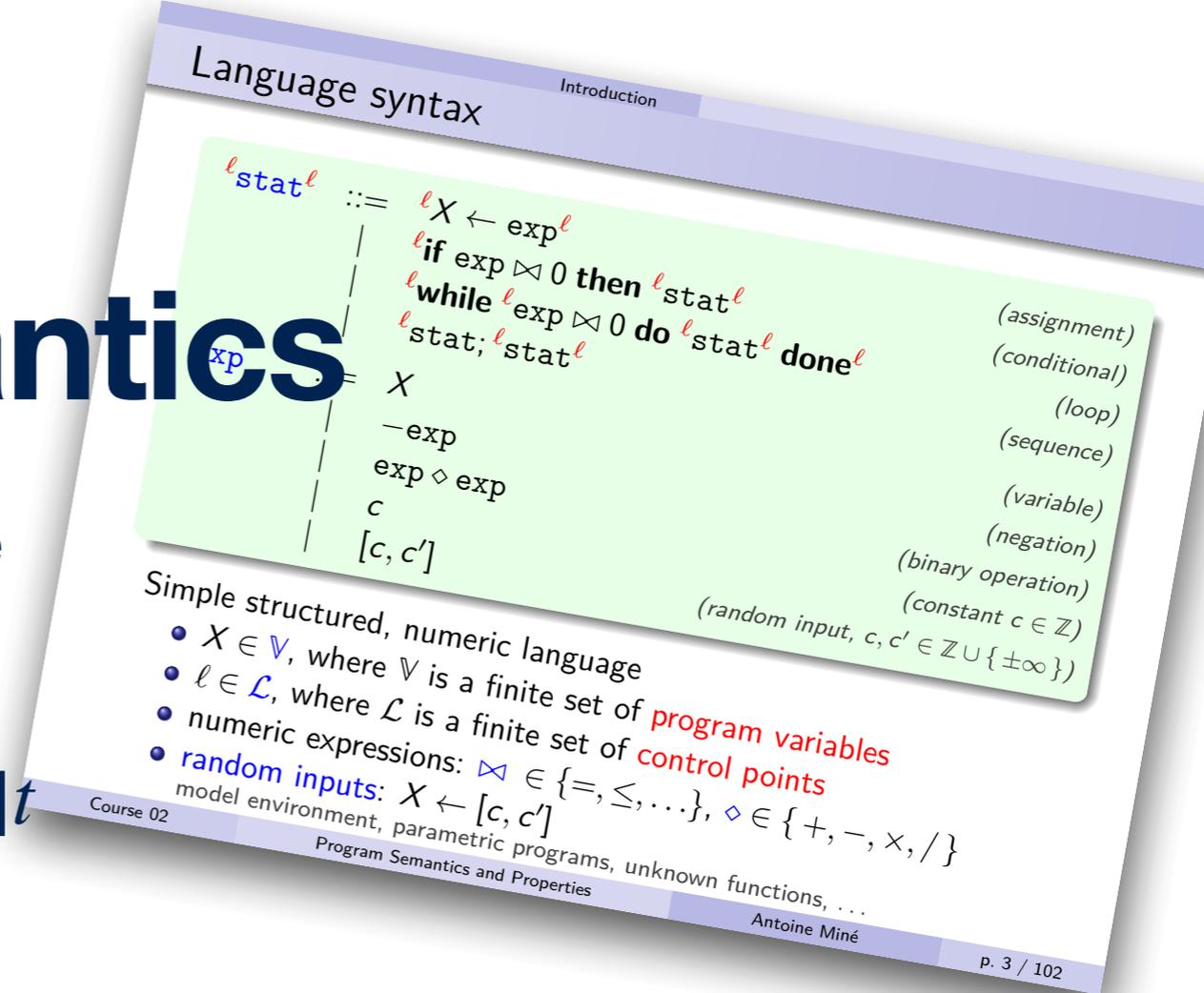
For each program instruction stat , we define a transformer $\mathcal{R}_M^\#[\text{stat}]: \mathcal{A} \rightarrow \mathcal{A}$:

- $\mathcal{R}_M^\#[\ell X \leftarrow e]t \stackrel{\text{def}}{=} \text{ASSIGN}_A[X \leftarrow e]t$
- $\mathcal{R}_M^\#[\text{if } \ell e \bowtie 0 \text{ then } s]t \stackrel{\text{def}}{=} \text{FILTER}_A[e \bowtie 0](\mathcal{R}_M^\#[s]t) \vee_T \text{FILTER}_A[e \bowtie 0]t$

Lemma (Soundness)

$$\mathcal{R}_M[\text{if } \ell e \bowtie 0 \text{ then } s]\gamma_A(t) \leq \gamma_A(\mathcal{R}_M^\#[\text{if } \ell e \bowtie 0 \text{ then } s]t)$$

(see proof in [Urban15])



Abstract Definite Termination Semantics

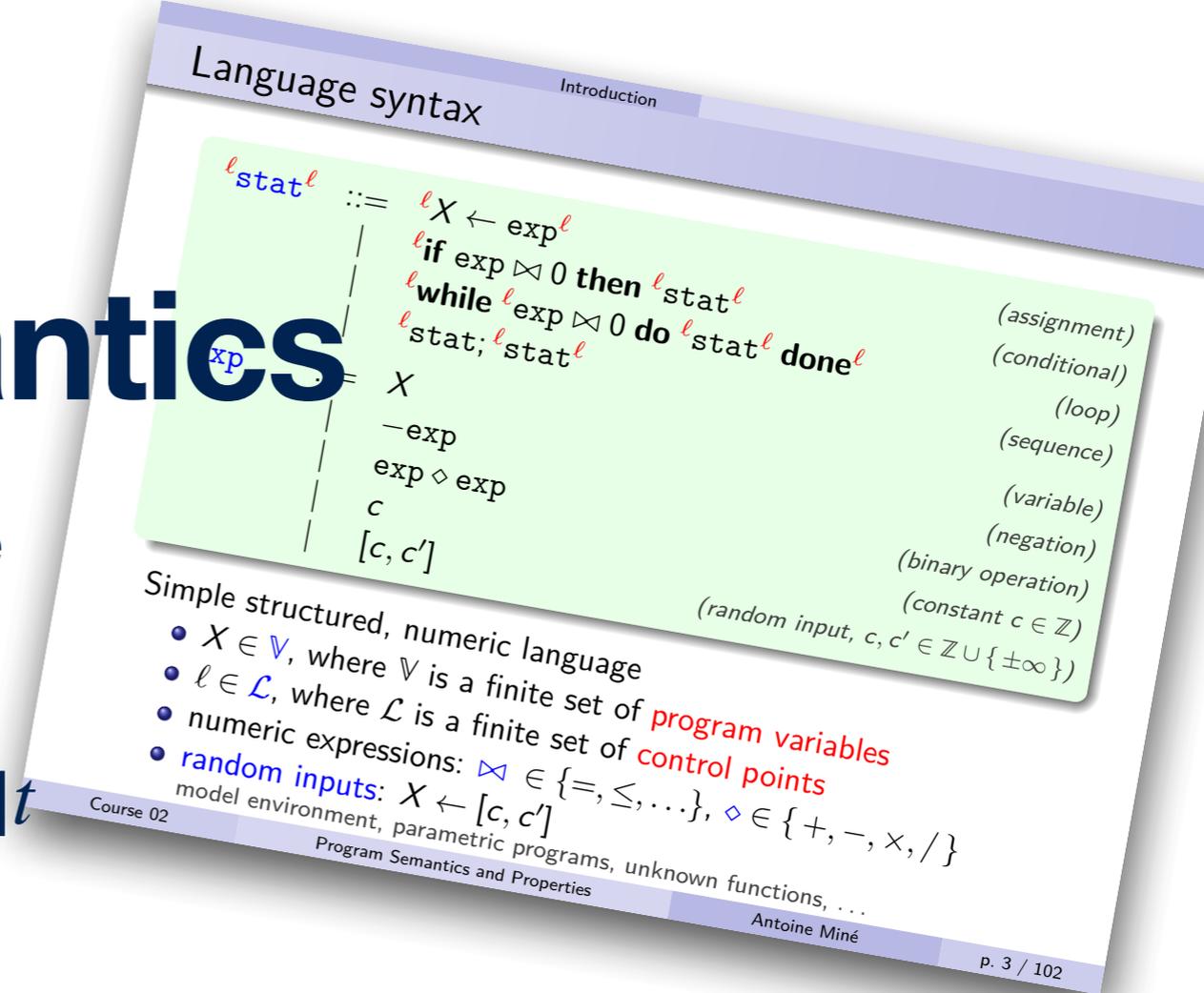
For each program instruction stat , we define a transformer $\mathcal{R}_M^\#[\text{stat}]: \mathcal{A} \rightarrow \mathcal{A}$:

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- $\mathcal{R}_M^\#[\text{if } \ell e \bowtie 0 \text{ then } s]t \stackrel{\text{def}}{=} \text{FILTER}_A[e \bowtie 0](\mathcal{R}_M^\#[s]t) \vee_T \text{FILTER}_A[e \bowtie 0]t$
- $\mathcal{R}_M^\#[\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}]t \stackrel{\text{def}}{=} \text{lfp}^\# \bar{F}_M^\#$
 where $\bar{F}_M^\#(x) \stackrel{\text{def}}{=} \text{FILTER}_A[e \bowtie 0](\mathcal{R}_M^\#[s]x) \vee_T \text{FILTER}_A[e \bowtie 0](t)$

Lemma (Soundness)

$$\mathcal{R}_M[\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}]\gamma_A(t) \preceq \gamma_A(\mathcal{R}_M^\#[\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}]t)$$

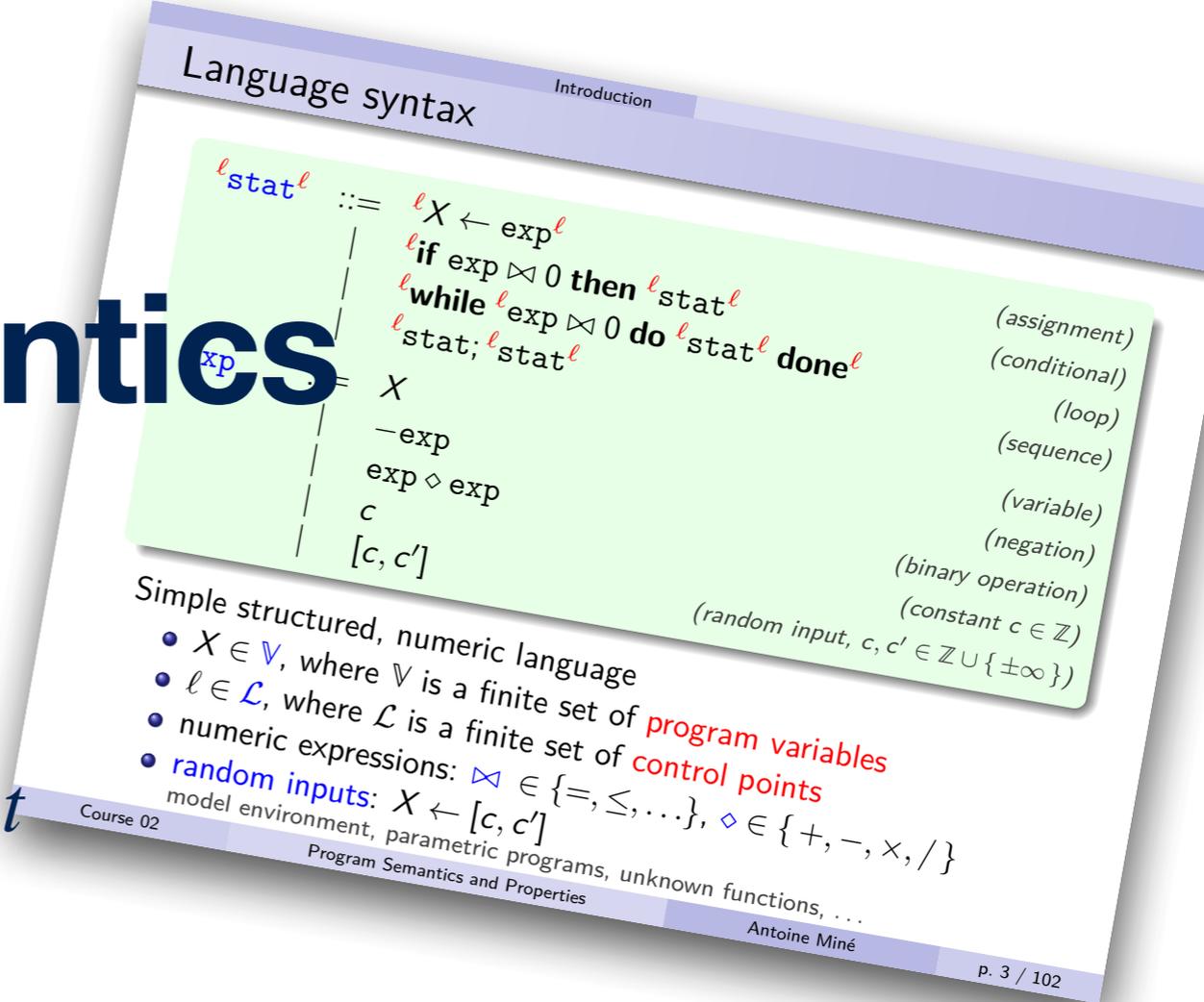
(see proof in [Urban15])



Abstract Definite Termination Semantics

For each program instruction stat , we define a transformer $\mathcal{R}_M^\#[\text{stat}]: \mathcal{A} \rightarrow \mathcal{A}$:

- $\mathcal{R}_M^\#[\ell X \leftarrow e]t \stackrel{\text{def}}{=} \text{ASSIGN}_A[X \leftarrow e]t$
- $\mathcal{R}_M^\#[\text{if } \ell e \bowtie 0 \text{ then } s]t \stackrel{\text{def}}{=} \text{FILTER}_A[e \bowtie 0](\mathcal{R}_M^\#[s]t) \vee_T \text{FILTER}_A[e \bowtie 0]t$
- $\mathcal{R}_M^\#[\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}]t \stackrel{\text{def}}{=} \text{lfp}^\# \bar{F}_M^\#$
 where $\bar{F}_M^\#(x) \stackrel{\text{def}}{=} \text{FILTER}_A[e \bowtie 0](\mathcal{R}_M^\#[s]x) \vee_T \text{FILTER}_A[e \bowtie 0](t)$
- $\mathcal{R}_M^\#[s_1; s_2]t \stackrel{\text{def}}{=} \mathcal{R}_M^\#[s_1](\mathcal{R}_M^\#[s_2]t)$



Abstract Definite Termination Semantics

Definition

The **abstract definite termination semantics** $\mathcal{R}_M^\# \llbracket \text{stat}^\ell \rrbracket \in \mathcal{A}$ of a program stat^ℓ is:

$$\mathcal{R}_M^\# \llbracket \text{stat}^\ell \rrbracket \stackrel{\text{def}}{=} \mathcal{R}_M^\# \llbracket \text{stat} \rrbracket (\text{LEAF} : \lambda X_1, \dots, X_k. 0)$$

where $\mathcal{R}_M^\# \llbracket \text{stat} \rrbracket : \mathcal{A} \rightarrow \mathcal{A}$ is the abstract definite termination semantics of each program instruction stat

Theorem (Soundness)

$$\mathcal{R}_M \llbracket \text{stat}^\ell \rrbracket \preceq \gamma_A(\mathcal{R}_M^\# \llbracket \text{stat}^\ell \rrbracket)$$

Corollary (Soundness)

A program stat^ℓ **must terminate** for traces starting from a set of initial states \mathcal{I} if $\mathcal{I} \subseteq \text{dom}(\gamma_A(\mathcal{R}_M^\# \llbracket \text{stat}^\ell \rrbracket))$

Abstract Definite Termination Semantics

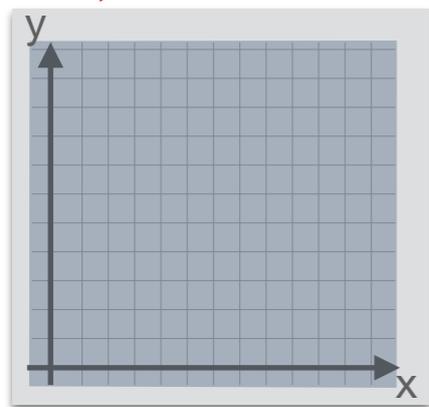
Example

```
1x ← [-∞, +∞]  
2y ← [-∞, +∞]  
while 3(x > 0) do  
    4x ← x - y  
od5
```

Abstract Definite Termination Semantics

Example

```
1  $x \leftarrow [-\infty, +\infty]$   
2  $y \leftarrow [-\infty, +\infty]$   
  while 3  $(x > 0)$  do  
    4  $x \leftarrow x - y$   
  od5
```

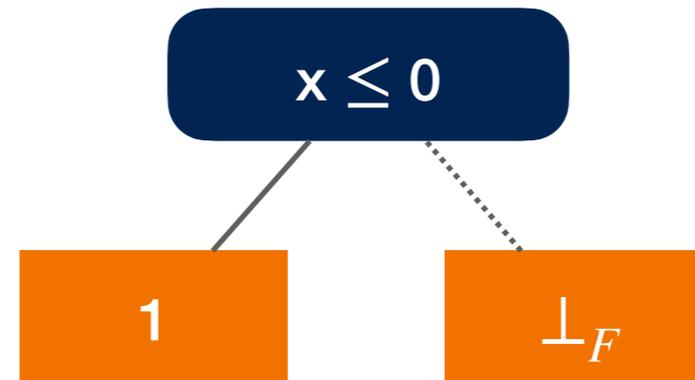
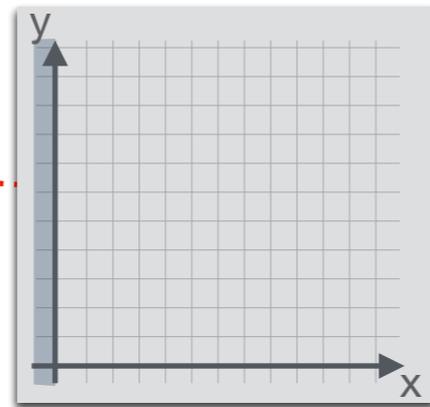


0

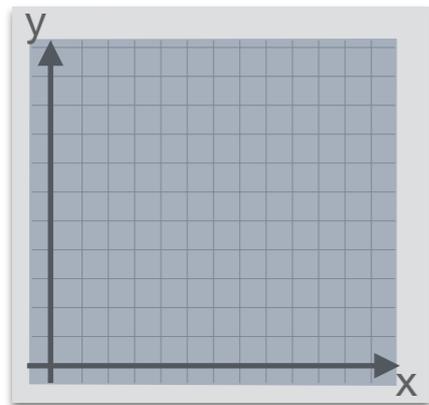
Abstract Definite Termination Semantics

Example

```
1  $x \leftarrow [-\infty, +\infty]$   
2  $y \leftarrow [-\infty, +\infty]$   
while 3  $(x > 0)$  do  
  4  $x \leftarrow x - y$   
od 5
```



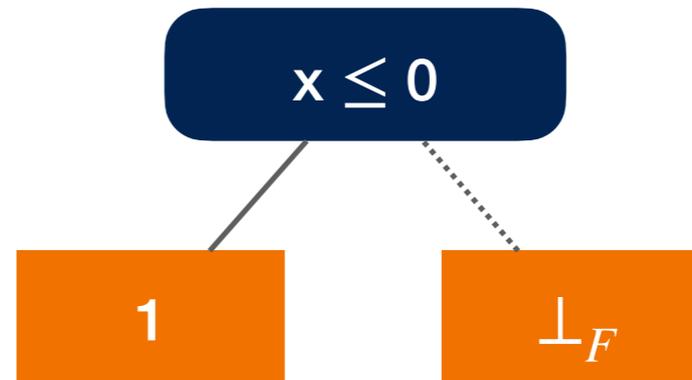
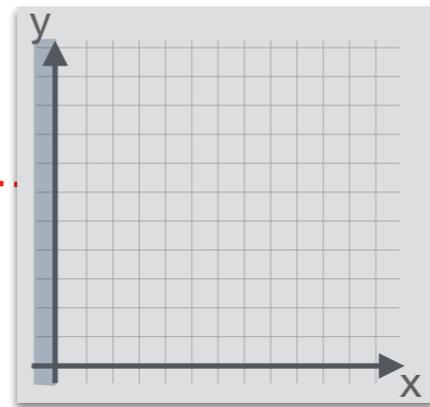
$\text{FILTER}_A[[x \leq 0]]$



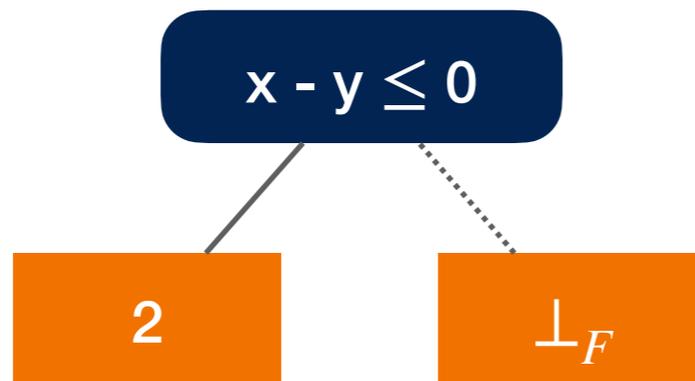
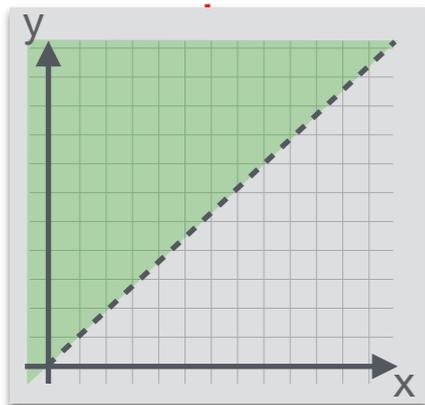
Abstract Definite Termination Semantics

Example

```
1  $x \leftarrow [-\infty, +\infty]$   
2  $y \leftarrow [-\infty, +\infty]$   
while 3  $(x > 0)$  do  
4  $x \leftarrow x - y$   
od 5
```



$\text{ASSIGN}_A[[x \leftarrow x - y]]$



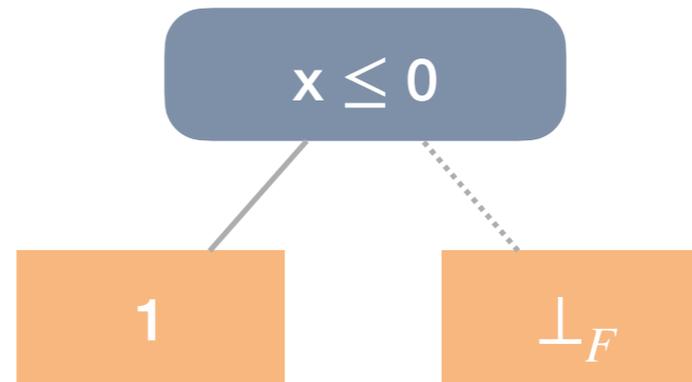
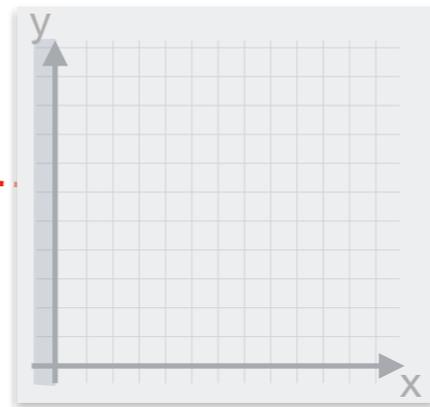
Abstract Definite Termination Semantics

Example

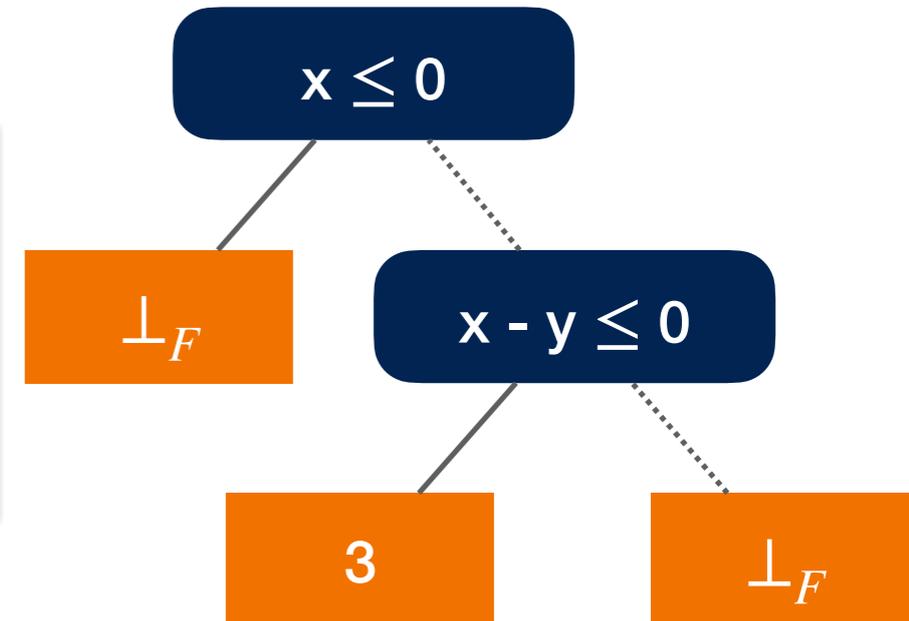
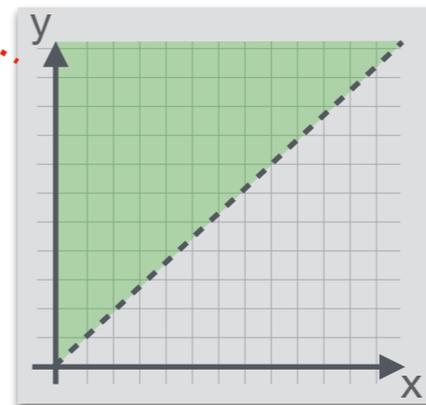
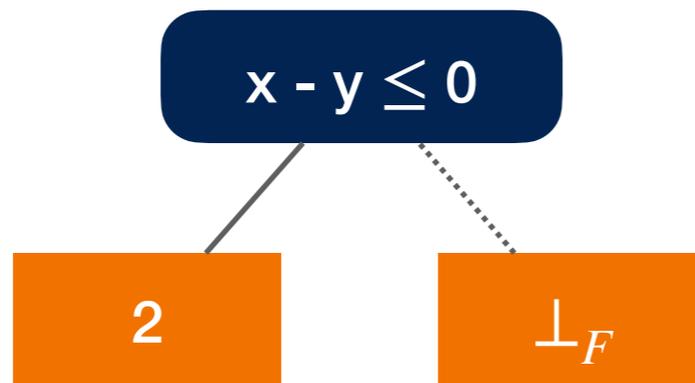
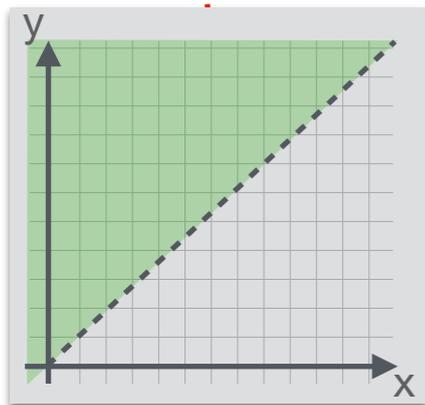
```

1  $x \leftarrow [-\infty, +\infty]$ 
2  $y \leftarrow [-\infty, +\infty]$ 
while 3  $(x > 0)$  do
4  $x \leftarrow x - y$ 
od 5

```



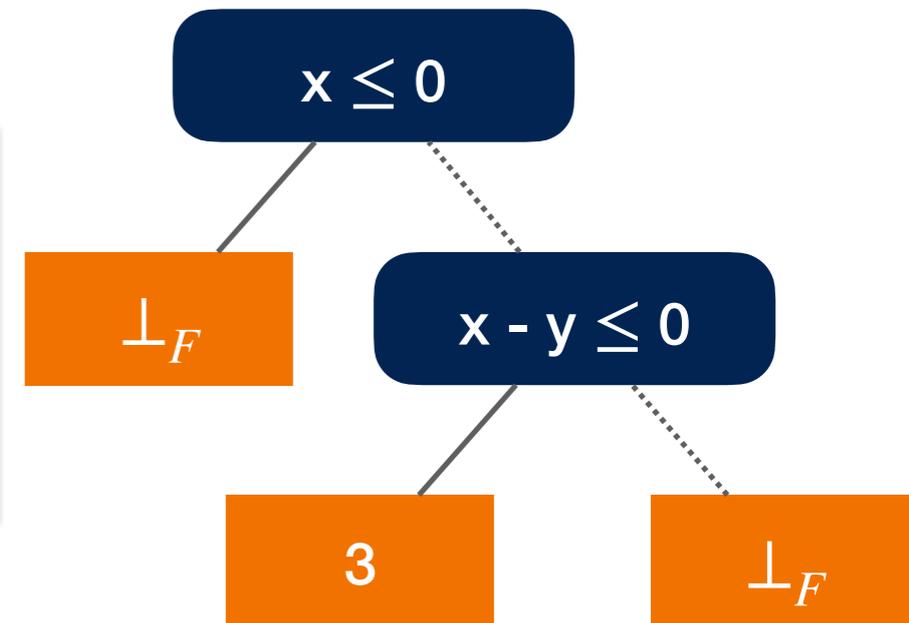
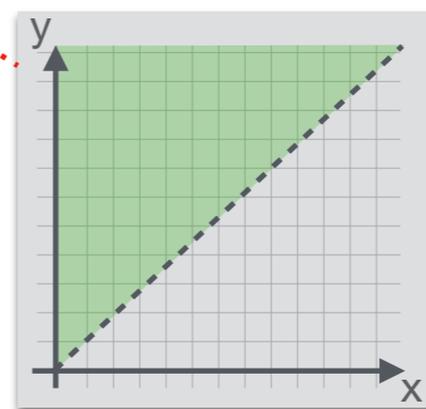
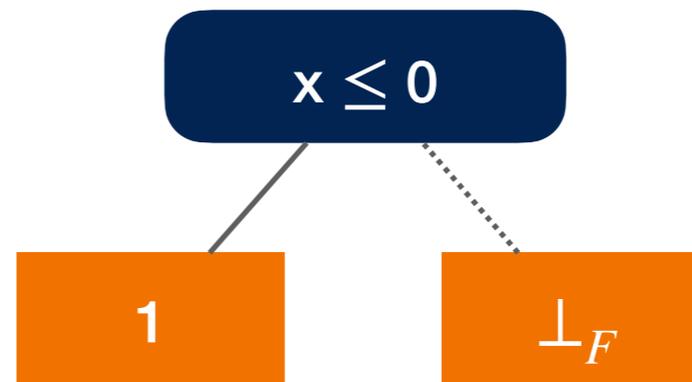
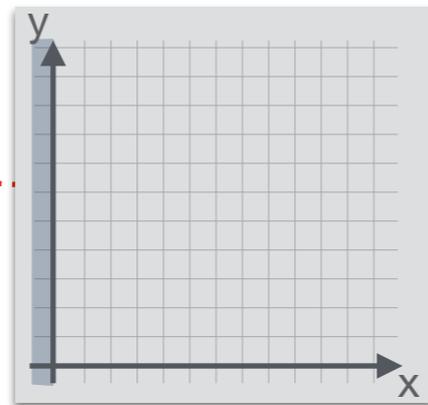
$\text{FILTER}_A[[x > 0]]$



Abstract Definite Termination Semantics

Example

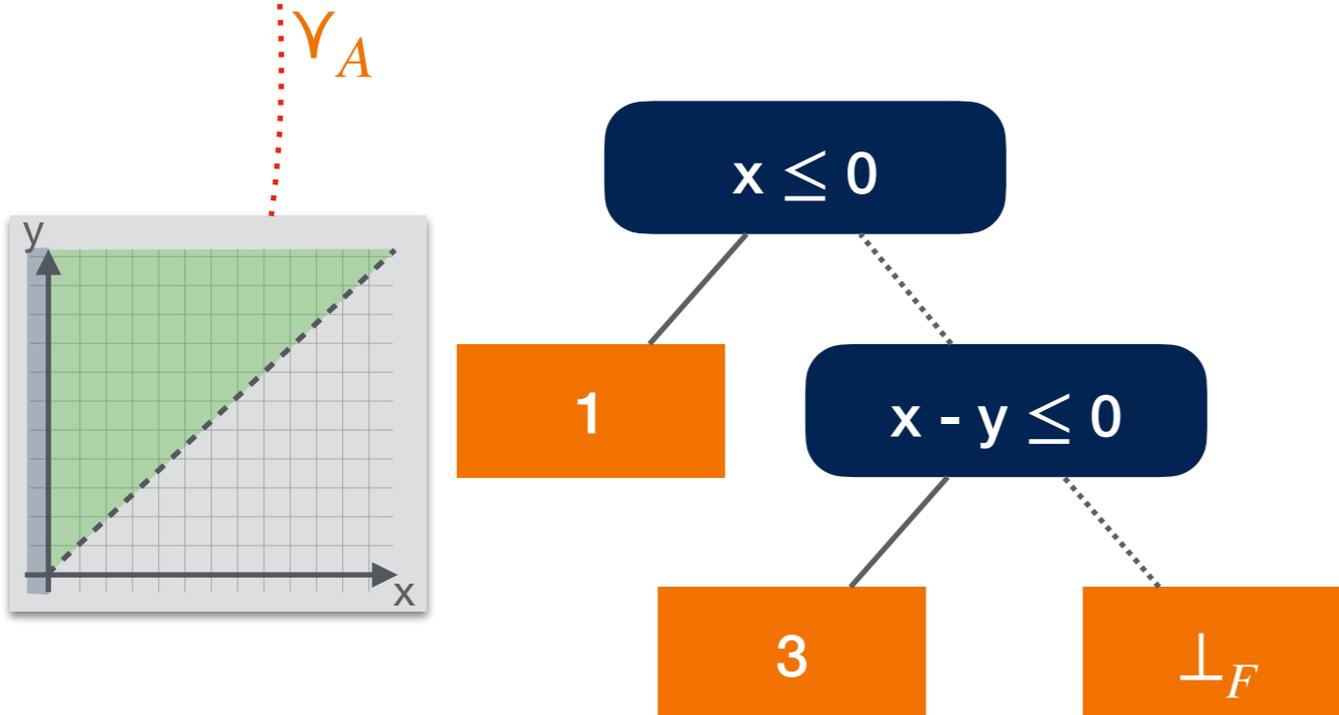
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```



Abstract Definite Termination Semantics

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```



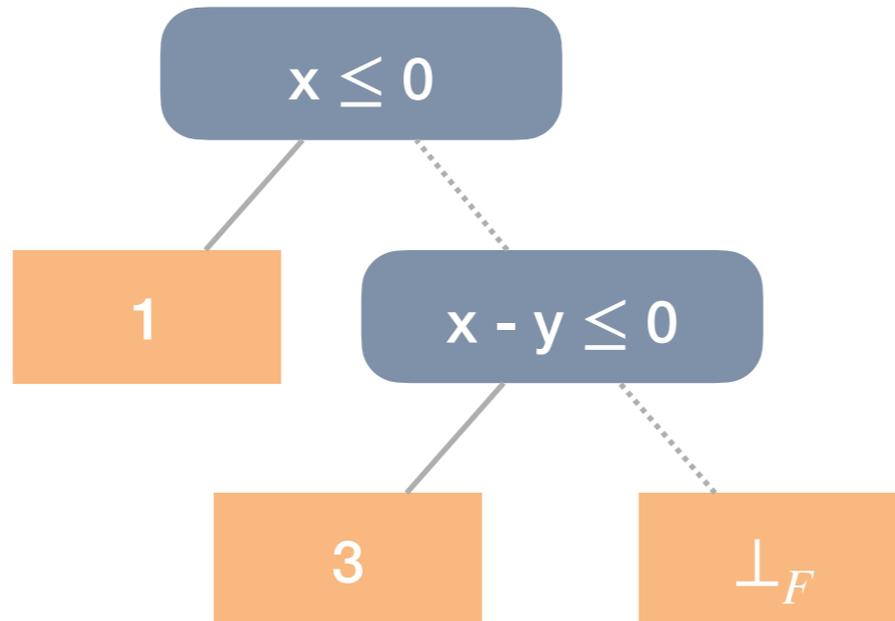
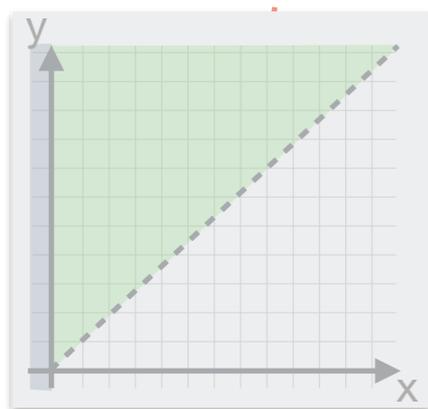
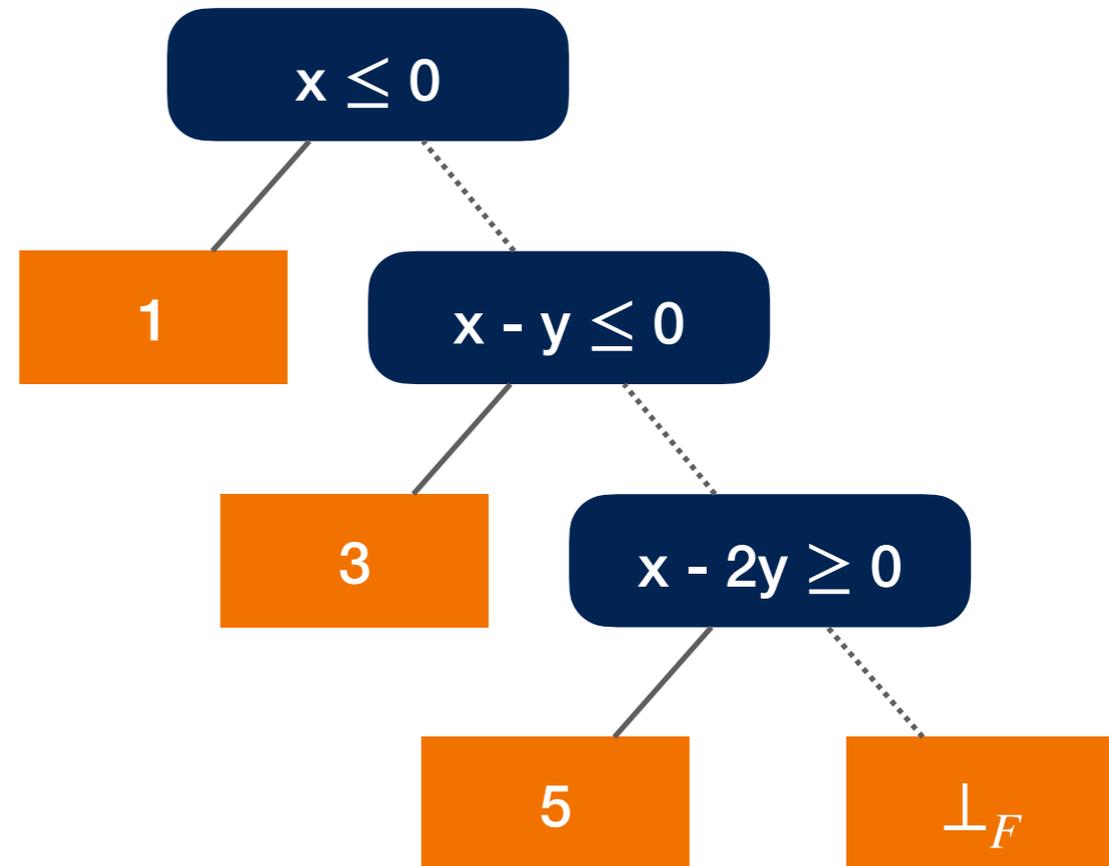
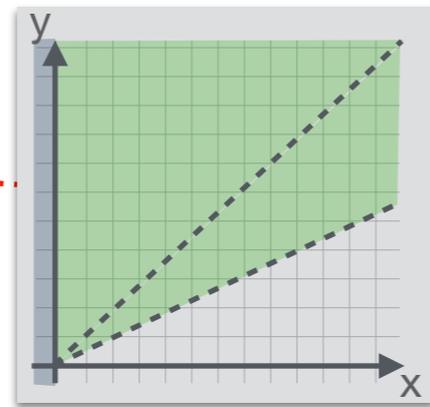
Abstract Definite Termination Semantics

Example

```

1  $x \leftarrow [-\infty, +\infty]$ 
2  $y \leftarrow [-\infty, +\infty]$ 
while 3 $(x > 0)$  do
4 $x \leftarrow x - y$ 
od5

```



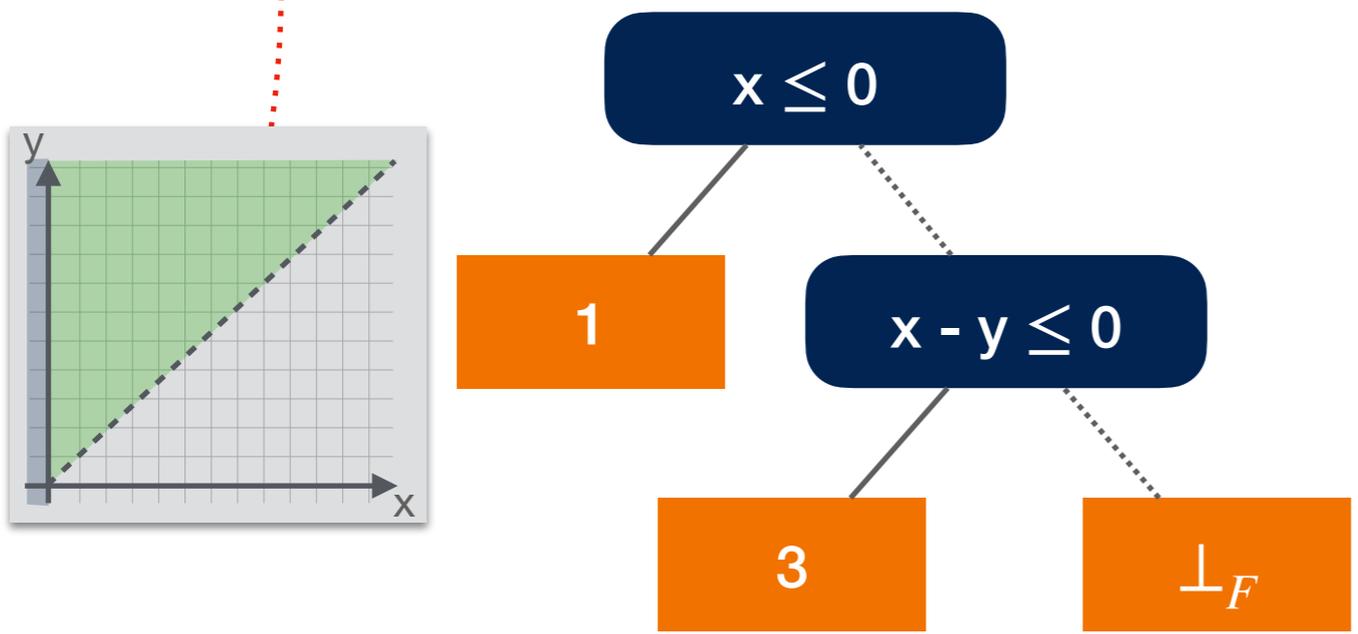
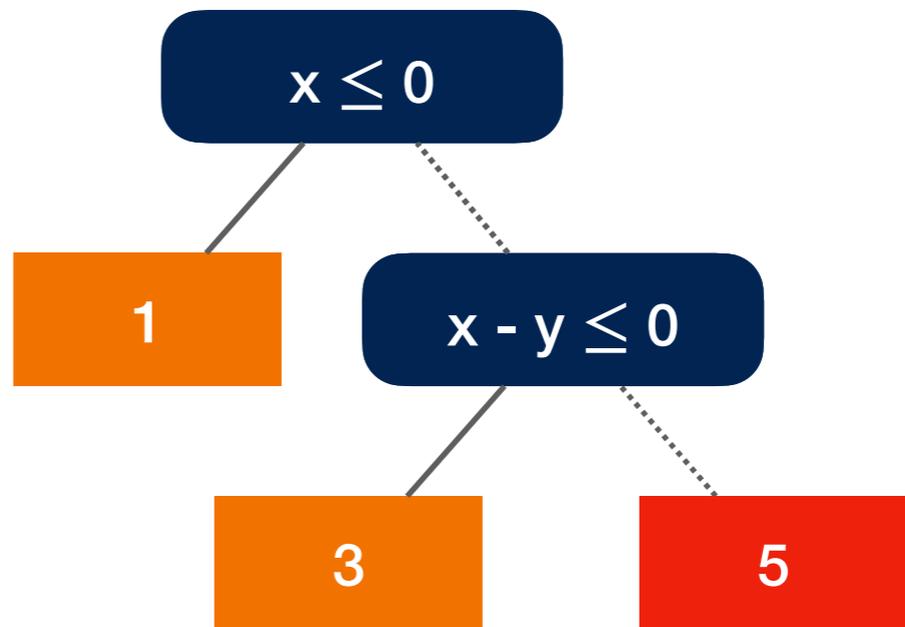
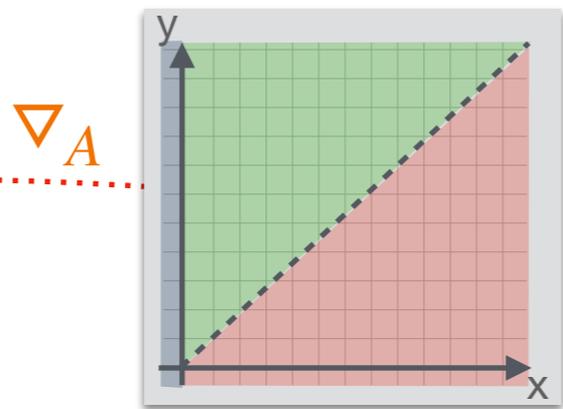
Abstract Definite Termination Semantics

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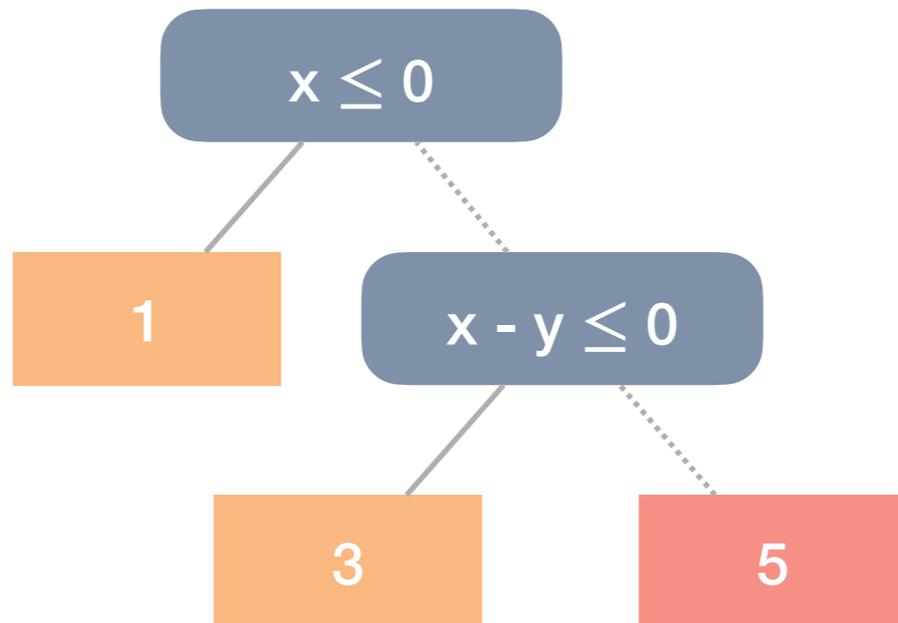
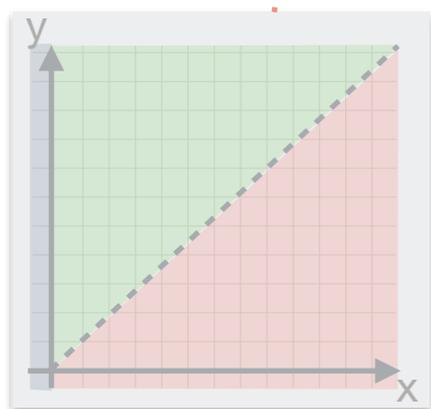
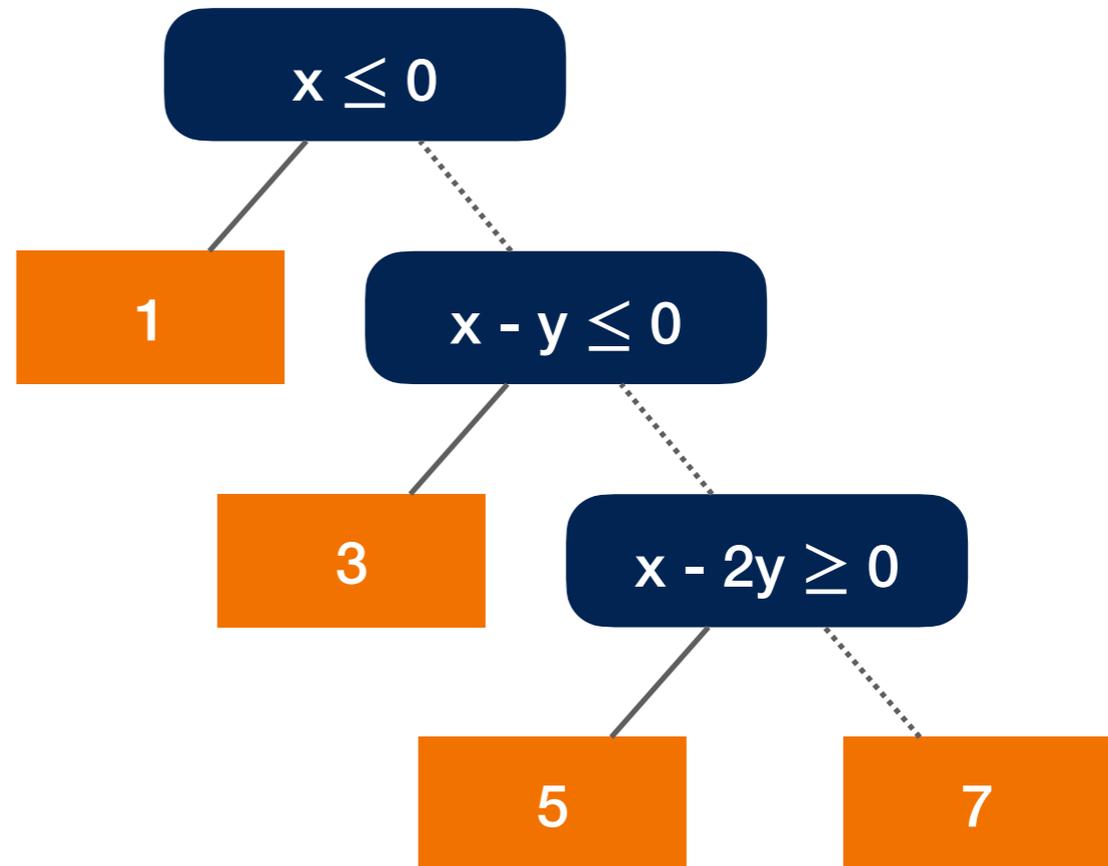
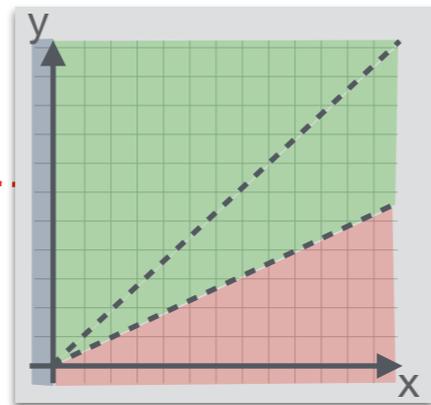


Abstract Definite Termination Semantics

Example

```

1  $x \leftarrow [-\infty, +\infty]$ 
2  $y \leftarrow [-\infty, +\infty]$ 
while 3  $(x > 0)$  do
  4  $x \leftarrow x - y$ 
5od
  
```

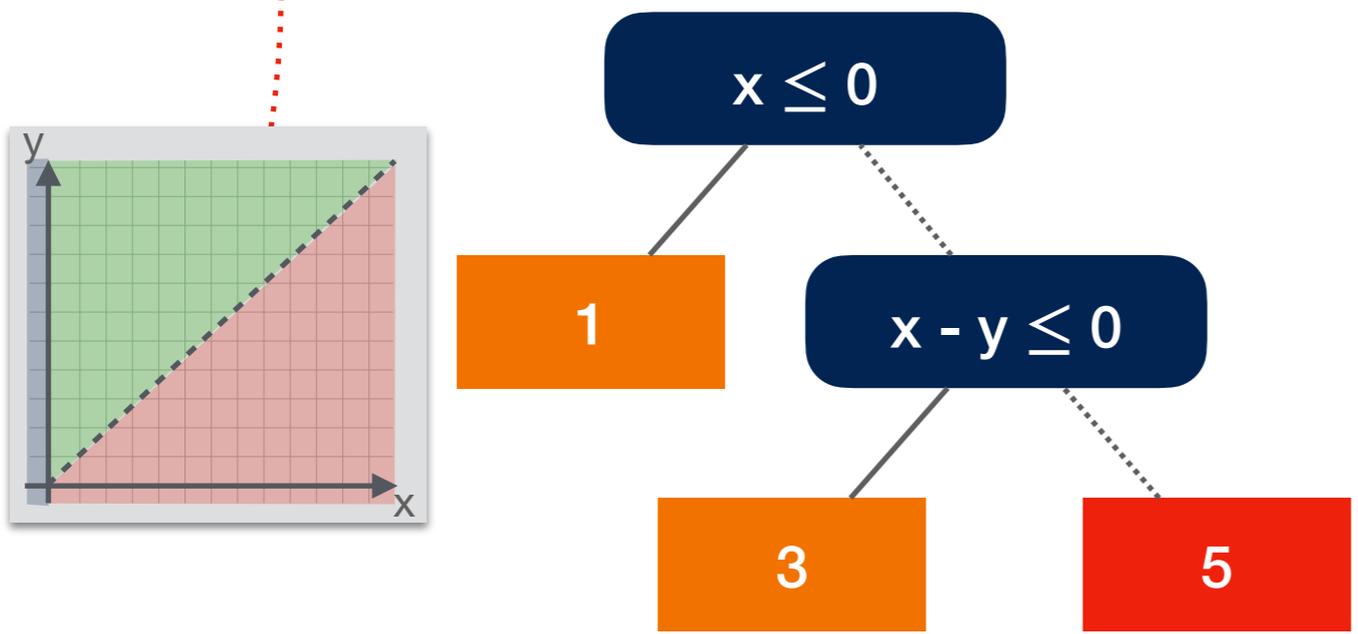
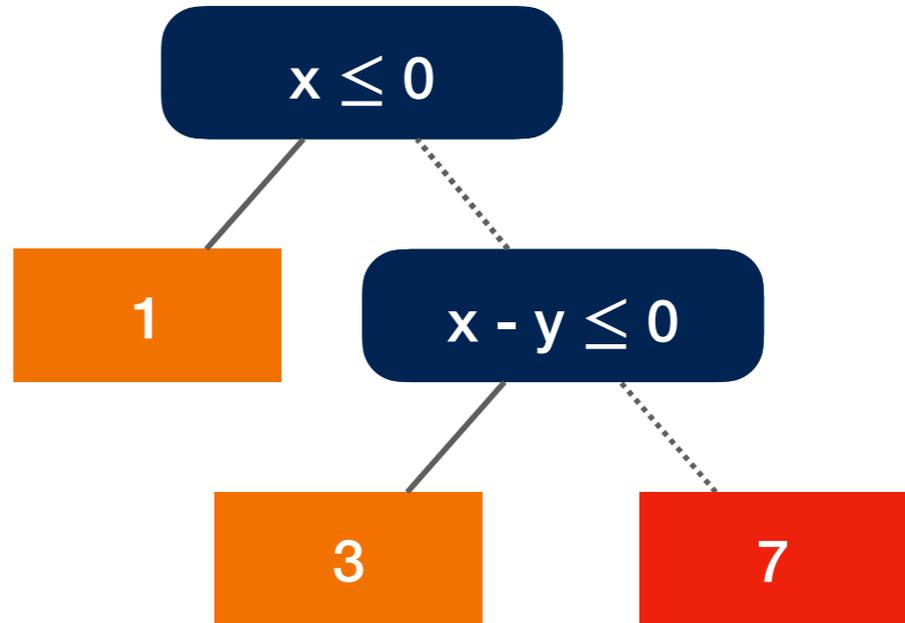
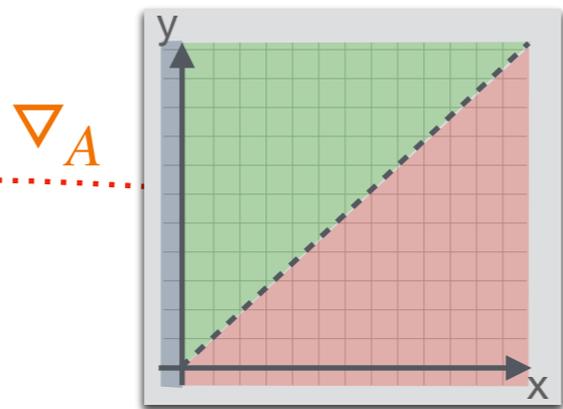


Abstract Definite Termination Semantics

Example

```

1  $x \leftarrow [-\infty, +\infty]$ 
2  $y \leftarrow [-\infty, +\infty]$ 
  while 3 $(x > 0)$  do
    4 $x \leftarrow x - y$ 
  od5
  
```

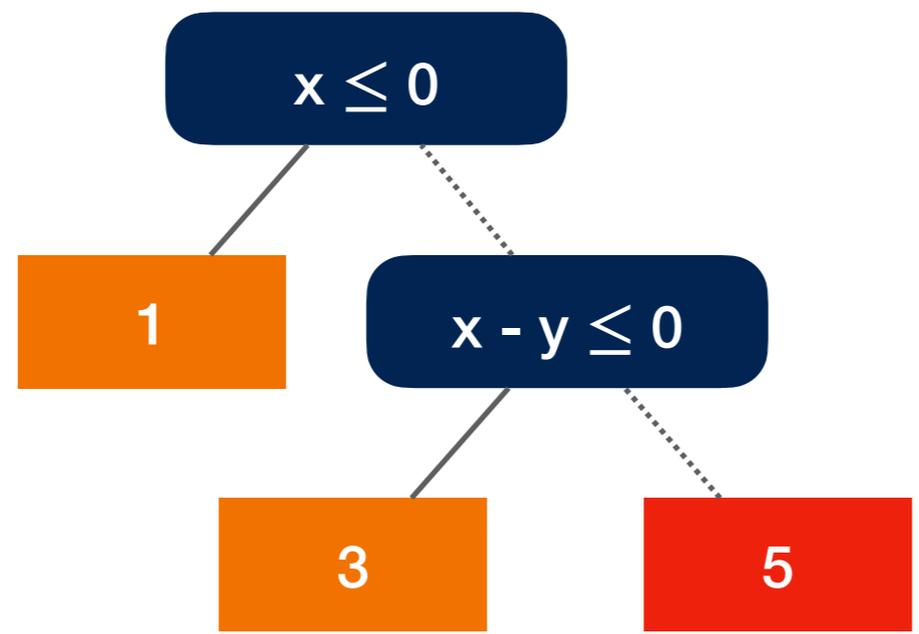
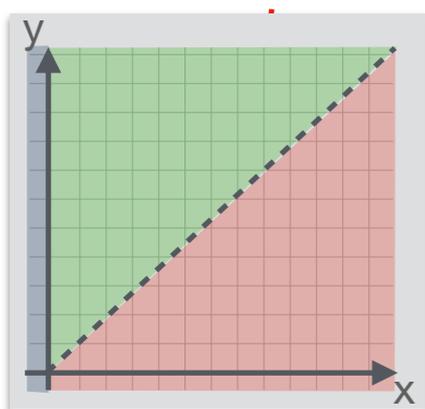
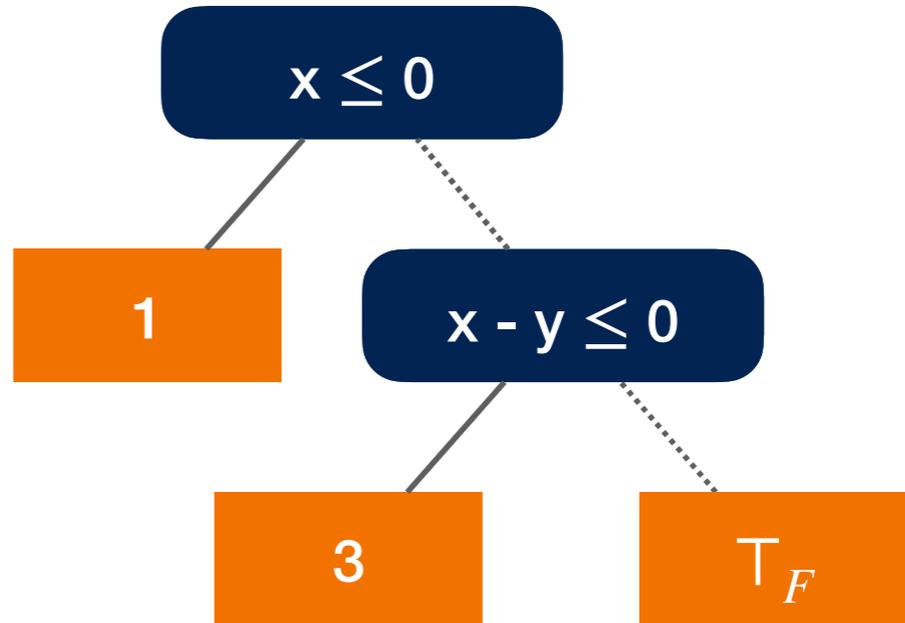
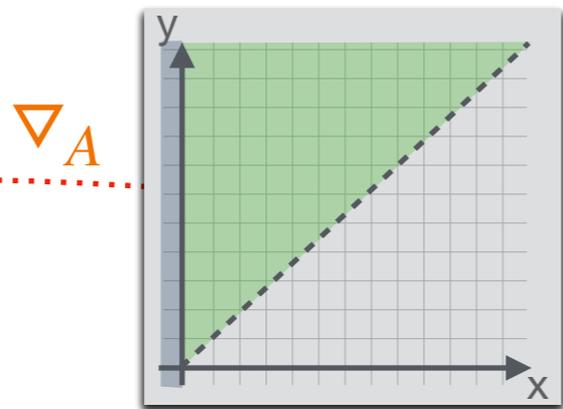


Abstract Definite Termination Semantics

Example

```

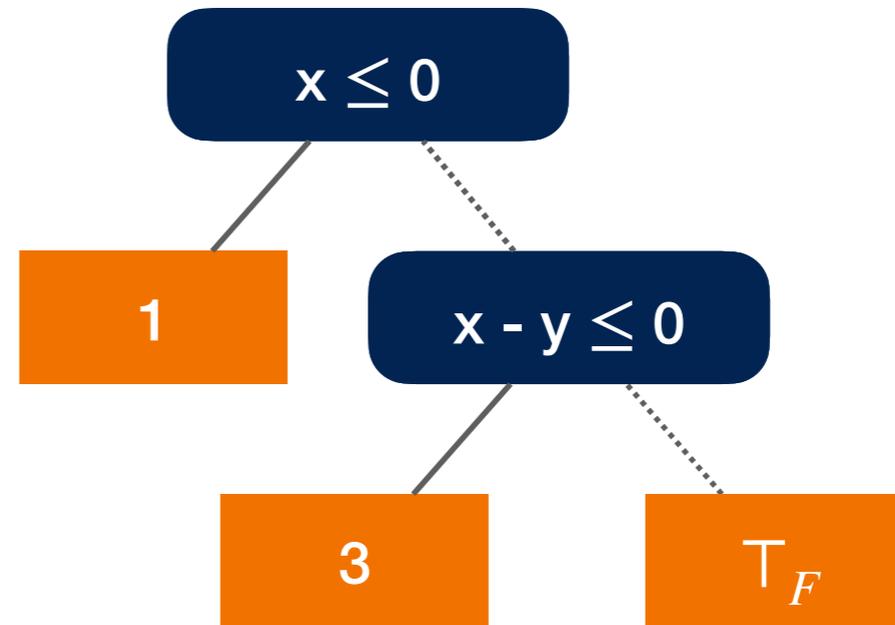
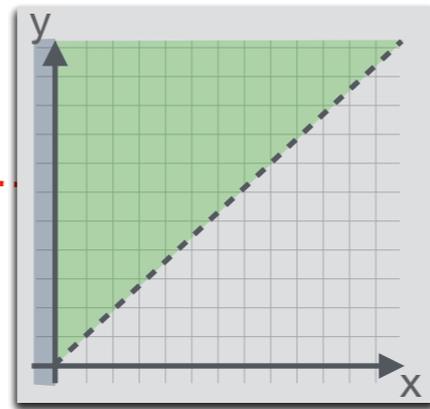
1  $x \leftarrow [-\infty, +\infty]$ 
2  $y \leftarrow [-\infty, +\infty]$ 
while 3 $(x > 0)$  do
  4 $x \leftarrow x - y$ 
5od
  
```



Abstract Definite Termination Semantics

Example

```
1  $x \leftarrow [-\infty, +\infty]$   
2  $y \leftarrow [-\infty, +\infty]$   
while 3  $(x > 0)$  do  
    4  $x \leftarrow x - y$   
od 5
```



Guarantee Properties

Guarantee Properties

“something good eventually happens at least once”

$AF \varphi$

$\varphi ::= e \bowtie 0 \mid \ell : e \bowtie 0 \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \quad \ell \in \mathcal{L}$

Example:

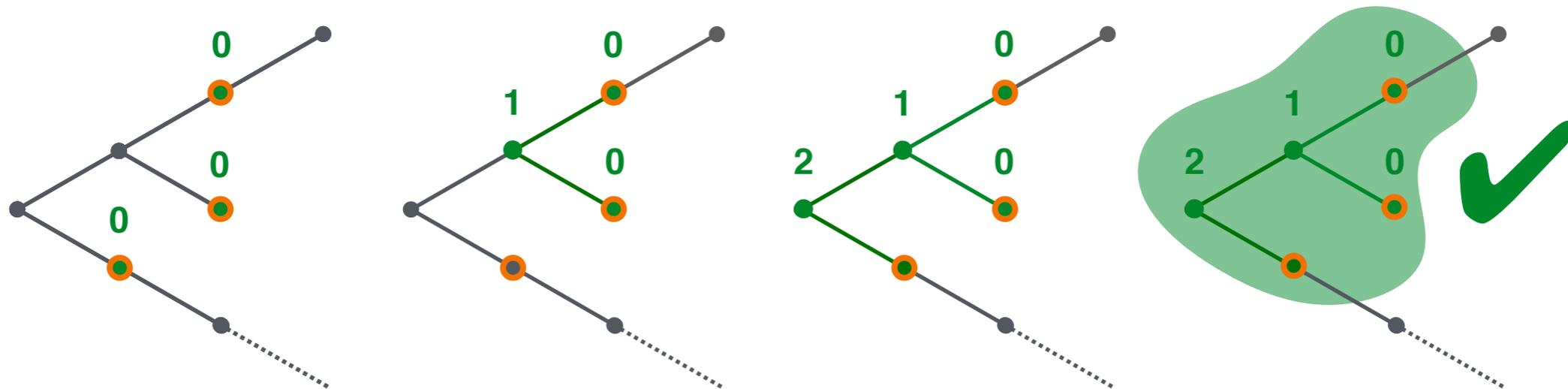
$AF(x = 3)$ is satisfied for $\mathcal{F} \stackrel{\text{def}}{=} \{(1, \rho) \in \Sigma \mid \rho(x) \leq 3\}$

```
1 x ← [-∞, +∞]
  while 2(x ≥ 0) do
    3 x ← x + 1
  od4
  while 5(0 ≥ 0) do
    if 6(x ≤ 10) do
      7 x ← x + 1
    else
      8 x ← -x
    od9
```

Guarantee Semantics

$$\mathcal{R}_G^\varphi \stackrel{\text{def}}{=} \text{lfp}^{\preceq} \bar{F}_G[\{\sigma \in \Sigma \mid \sigma \models \varphi\}]$$

$$\bar{F}_G[S]f \stackrel{\text{def}}{=} \lambda\sigma. \begin{cases} 0 & \sigma \in S \\ \sup\{f(\sigma') + 1 \mid (\sigma, \sigma') \in \tau\} & \sigma \notin S \wedge \sigma \in \text{pre}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$



Theorem

A program satisfies a **guarantee property** $\text{AF } \varphi$ for traces starting from a set of initial states \mathcal{I} if and only if $\mathcal{I} \subseteq \text{dom}(\mathcal{R}_G^\varphi)$

Abstract Guarantee Semantics

For each program instruction stat , we define $\mathcal{R}_G^{\varphi\#}[\![\text{stat}]\!] : \mathcal{A} \rightarrow \mathcal{A}$:

- $\mathcal{R}_G^{\varphi\#}[\![\ell X \leftarrow e]\!]t \stackrel{\text{def}}{=} \text{RESET}_A^G[\![\varphi]\!](\overleftarrow{\text{ASSIGN}}_A[\![X \leftarrow e]\!]t)$
- $\mathcal{R}_G^{\varphi\#}[\![\text{if } \ell e \bowtie 0 \text{ then } s]\!]t \stackrel{\text{def}}{=} \text{RESET}_A^G[\![\varphi]\!](X)$
 where $X \stackrel{\text{def}}{=} \text{FILTER}_A[\![e \bowtie 0]\!](\mathcal{R}_G^{\varphi\#}[\![s]\!]t) \vee_T \text{FILTER}_A[\![e \bowtie 0]\!]t)$
- $\mathcal{R}_G^{\varphi\#}[\![\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}\!]t \stackrel{\text{def}}{=} \text{lfp}^{\#} \overline{F}_G^{\varphi\#}$
 where $\overline{F}_G^{\varphi\#}(x) \stackrel{\text{def}}{=} \text{RESET}_A^G[\![\varphi]\!](X)$
 $X \stackrel{\text{def}}{=} \text{FILTER}_A[\![e \bowtie 0]\!](\mathcal{R}_G^{\varphi\#}[\![s]\!]x) \vee_T \text{FILTER}_A[\![e \bowtie 0]\!](t)$
- $\mathcal{R}_G^{\varphi\#}[\![s_1; s_2]\!]t \stackrel{\text{def}}{=} \mathcal{R}_G^{\varphi\#}[\![s_1]\!](\mathcal{R}_G^{\varphi\#}[\![s_2]\!]t)$

Abstract Guarantee Semantics

Definition

The **abstract guarantee semantics** $\mathcal{R}_G^{\varphi\#}[\text{stat}^\ell] \in \mathcal{A}$ of a program stat^ℓ is:

$$\mathcal{R}_G^{\varphi\#}[\text{stat}^\ell] \stackrel{\text{def}}{=} \mathcal{R}_G^{\varphi\#}[\text{stat}](\text{RESET}_A^G[\varphi](\text{LEAF}: \perp_F))$$

where $\mathcal{R}_G^{\varphi\#}[\text{stat}]: \mathcal{A} \rightarrow \mathcal{A}$ is the abstract guarantee semantics of each program instruction stat

Corollary (Soundness)

A program stat^ℓ satisfies a **guarantee property** $\text{AF } \varphi$ for traces starting from a set of initial states \mathcal{I} if $\mathcal{I} \subseteq \text{dom}(\gamma_A(\mathcal{R}_G^{\varphi\#}[\text{stat}^\ell]))$

Recurrence Properties

“something good eventually happens infinitely often”

$AG AF \varphi$

$\varphi ::= e \bowtie 0 \mid \ell : e \bowtie 0 \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \quad \ell \in \mathcal{L}$

Example:

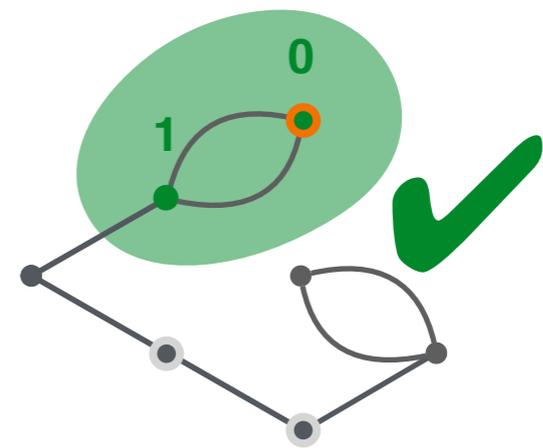
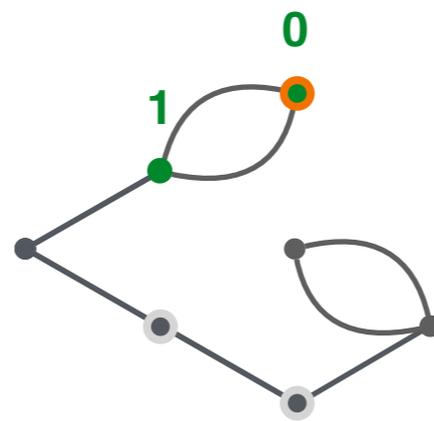
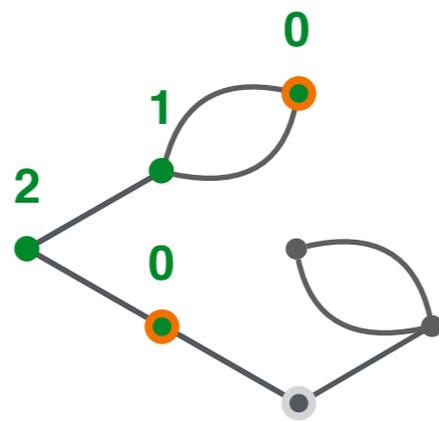
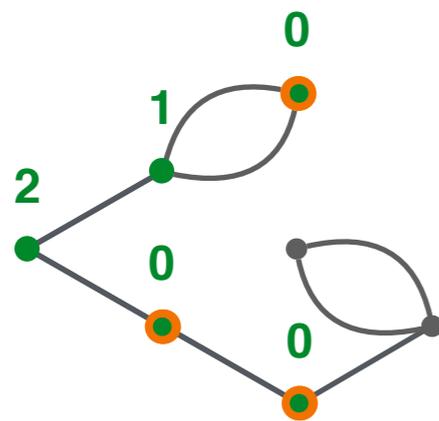
$\mathbf{1}x \leftarrow [-\infty, +\infty]$ $AG AF (x = 3)$ is satisfied for $\mathcal{F} \stackrel{\text{def}}{=} \{(1, \rho) \in \Sigma \mid \rho(x) < 0\}$

```
while  $\mathbf{2}(x \geq 0)$  do  
   $\mathbf{3}x \leftarrow x + 1$   
od $\mathbf{4}$   
while  $\mathbf{5}(0 \geq 0)$  do  
  if  $\mathbf{6}(x \leq 10)$  do  
     $\mathbf{7}x \leftarrow x + 1$   
  else  
     $\mathbf{8}x \leftarrow -x$   
od $\mathbf{9}$ 
```

Recurrence Semantics

$$\mathcal{R}_R^\varphi \stackrel{\text{def}}{=} \text{gfp}_{\mathcal{R}_G^\varphi} \leq \bar{F}_R$$

$$\bar{F}_R(f)\sigma \stackrel{\text{def}}{=} \begin{cases} f(s) & \sigma \in \text{pre}_\tau(\text{dom}(f)) \\ \text{undefined} & \text{otherwise} \end{cases}$$



Theorem

A program satisfies a **recurrence property** $\text{AG AF } \varphi$ for traces starting from a set of initial states \mathcal{I} if and only if $\mathcal{I} \subseteq \text{dom}(\mathcal{R}_R^\varphi)$

Abstract Recurrence Semantics

For each program instruction stat , we define $\mathcal{R}_G^{\varphi\#}[\![\text{stat}]\!] : \mathcal{A} \rightarrow \mathcal{A}$:

- $\mathcal{R}_R^{\varphi\#}[\![\ell X \leftarrow e]\!]t \stackrel{\text{def}}{=} \text{RESET}_A^R[\![\varphi]\!](\overleftarrow{\text{ASSIGN}}_A[\![X \leftarrow e]\!]t)$
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- $\mathcal{R}_R^{\varphi\#}[\![\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}\!]t \stackrel{\text{def}}{=} \text{gfp}_{G(t)}^{\#} \overline{F}_R^{\varphi\#}$
 where $G \stackrel{\text{def}}{=} \mathcal{R}_G^{\varphi\#}[\![\text{while } \ell e \bowtie 0 \text{ do } s \text{ done}\!]$
 $\overline{F}_R^{\varphi\#}(x) \stackrel{\text{def}}{=} \text{RESET}_A^R[\![\varphi]\!](X)$
 $X \stackrel{\text{def}}{=} \text{FILTER}_A[\![e \bowtie 0]\!](\mathcal{R}_R^{\varphi\#}[\![s]\!]x) \vee_T \text{FILTER}_A[\![e \bowtie 0]\!](t)$
- $\mathcal{R}_R^{\varphi\#}[\![s_1; s_2]\!]t \stackrel{\text{def}}{=} \mathcal{R}_R^{\varphi\#}[\![s_1]\!](\mathcal{R}_R^{\varphi\#}[\![s_2]\!]t)$

Abstract Recurrence Semantics

Definition

The **abstract recurrence semantics** $\mathcal{R}_R^{\varphi\#}[\text{stat}^\ell] \in \mathcal{A}$ of a program stat^ℓ is:

$$\mathcal{R}_R^{\varphi\#}[\text{stat}^\ell] \stackrel{\text{def}}{=} \mathcal{R}_R^{\varphi\#}[\text{stat}](\text{LEAF: } \perp_F)$$

where $\mathcal{R}_R^{\varphi\#}[\text{stat}]: \mathcal{A} \rightarrow \mathcal{A}$ is the abstract recurrence semantics of each program instruction stat

Corollary (Soundness)

A program stat^ℓ satisfies a **recurrence property** $\text{AG AF } \varphi$ for traces starting from a set of initial states \mathcal{I} if $\mathcal{I} \subseteq \text{dom}(\gamma_A(\mathcal{R}_R^{\varphi\#}[\text{stat}^\ell]))$

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