

Non-Relational Numerical Abstract Domains

MPRI 2–6: Abstract Interpretation,
application to verification and static analysis

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Abstract interpretation: LIP6 Colloquium

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vidéo disponible sur le site



Abstract interpretation

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**29 Septembre 2016
à 18h00**

The complexity of large programs grows faster than the intellectual ability of programmers in charge of their development and maintenance. The direct consequence is a lot of errors and bugs in programs mostly debugged by their end-users. Programmers are not responsible for these bugs. They are not required to produce provably safe and secure programs. This is because professionals are only required to apply state of the art techniques, that is testing on finitely many cases. The state of the art is changing rapidly and so will responsibility, as in other manufacturing disciplines.

Scalable and cost-effective tools have appeared recently that can avoid bugs with possible unwanted consequences for example in transportation, banks, privacy of social networks, etc. Entirely automatic, they are able to capture all bugs involving the violation of software healthiness rules such as the use of operations with arguments for which they are undefined.

These tools are formally founded on abstract interpretation. They are based on a definition of the semantics of programming languages specifying all possible executions of the programs of a language. Program properties of interest are abstractions of those semantics abstracting away all aspects of the semantics not relevant to a particular reasoning on programs. This yields proof methods.

Full automation is more difficult because of undecidability: programs cannot always prove programs correct in finite time and memory. Further abstractions are therefore necessary for automation, which introduce regression. Bugs may be signaled that are impossible in any execution (but still none is forgotten). This has an economic cost, much less than testing. Monotonic (but still static) analysis tools are able to reduce these false alarms to almost zero. A time-consuming and error-prone task which is too difficult, if not impossible for programmers, without tools.

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Talk by Patrick Cousot at Paris 6, 29 September 2016, 18h00

<https://www.lip6.fr/colloquium/>

Introduction

Invariant discovery

Goal: find **intermittent** numerical **invariants**
(at each program point, properties of numerical variables)

Example

```
X:=[0,10]; Y:=100;

while X>=0 do
    // loop invariant?
    X:=X-1;

    Y:=Y+10

done
// value of X and Y?
```

Invariant discovery

Goal: find **intermittent** numerical **invariants**

(at each program point, properties of numerical variables)

Example

```
X:=[0,10]; Y:=100;  
  // X ∈ [0, 10], Y = 100  
while X>=0 do  
  // X ∈ [0, 10], Y ∈ [100, 200]  
  X:=X-1;  
  // X ∈ [-1, 9], Y ∈ [100, 200]  
  Y:=Y+10  
  // X ∈ [-1, 9], Y ∈ [110, 210]  
done  
// X = -1, Y ∈ [110, 210]
```

Variable bounds

Invariant discovery

Hope: find **the strongest** intermittent numerical invariants

(at each program point, **the strongest** properties of numerical variables)

Example

```

X:=[0,10]; Y:=100;
  //  $x \in [0, 10], y = 100$ 
while X>=0 do
  //  $x \in [0, 10], 10x + y \in [100, 200] \cap 10\mathbb{Z}$ 
  X:=X-1;
  //  $x \in [-1, 9], 10x + y \in [90, 190] \cap 10\mathbb{Z}$ 
  Y:=Y+10
  //  $x \in [-1, 9], 10x + y \in [100, 200] \cap 10\mathbb{Z}$ 
done
//  $x = -1, y \in [110, 210] \cap 10\mathbb{Z}$ 

```

Variable bounds, linear relations and congruences

Application: prove the absence of run-time error (overflow, array access, ...)

Forward-backward analysis

sign function

```
X:=[-100,100];  
if X=0 then Z:=0 else  
  Y:=X;  
  if Y < 0 then Y:=-Y;  
  Z:=X/Y  
fi
```

Forward-backward analysis

sign function

```
X:=[-100,100]; (X ∈ [-100, 100])  
if X=0 then Z:=0 else (X ∈ [-100, 100])  
  Y:=X; (X, Y ∈ [-100, 100])  
  if Y < 0 then Y:=-Y; (X ∈ [-100, 100], Y ∈ [0, 100])  
  Z:=X/Y (X ∈ [-100, 100], Y ∈ [0, 100])  
fi
```

Forward interval analysis
(possible division by 0)

Forward-backward analysis

sign function

```

X:=[-100,100]; ( $\perp$ )
if X=0 then Z:=0 else ( $X = 0$ )
  Y:=X; ( $Y = 0$ )
  if Y < 0 then Y:=-Y; ( $Y = 0$ )
  Z:=X/Y ( $Y = 0$ )
fi
  
```

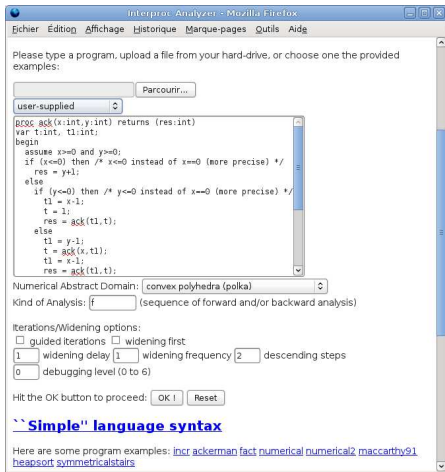
Backward interval analysis

- infer (tight) **necessary conditions** on **inputs** to reach a given point in a given state ($Y = 0$ at the end of the program)
- refine** and **focus** the result of a forward analysis (prove the absence of division by zero) [Bour93b]

Academic implementation: Apron and Interproc

[Apron](#): **library** of numerical abstractions [Jean09]

[Interproc](#): **on-line** analyzer for a **toy** language, based on **Apron**



<http://pop-art.inrialpes.fr/interproc/interprocweb.cgi>

Outline

- Generalities, notations
- Presentation of a few **numerical abstract domains** (non-relational)
 - **sign** domains
 - **constant** domain
 - **interval** domain
 - simple **congruence** domain
- **Reduced products** of domains
- Bibliography

Generalities and notations

Syntax

Expression syntax

Toy language:

- fixed, **finite** set of variables \mathbb{V} ,
- **one datatype**: scalars in \mathbb{I} , with $\mathbb{I} \in \{\mathbb{Z}, \mathbb{Q}, \mathbb{R}\}$
(and later, floating-point numbers \mathbb{F})
- no procedure

arithmetic expressions:

<code>exp</code>	<code>::=</code>	<code>V</code>	variable $V \in \mathbb{V}$
		<code>-exp</code>	negation
		<code>exp \diamond exp</code>	binary operation: $\diamond \in \{+, -, \times, /\}$
		<code>[c, c']</code>	constant range, $c, c' \in \mathbb{I} \cup \{\pm\infty\}$ c is a shorthand for $[c, c]$

Programs (as control-flow graphs)

commands:

$\text{com} ::= V := \text{exp}$ assignment into $V \in \mathbb{V}$
 | $\text{exp} \bowtie 0$ test, $\bowtie \in \{=, <, >, <=, >=, <>\}$

programs: as control-flow graphs

$P \stackrel{\text{def}}{=} (L, e, x, A)$

L	program points (labels)
e	entry point: $e \in L$
x	exit point: $x \in L$
A	arcs: $A \subseteq L \times \text{com} \times L$

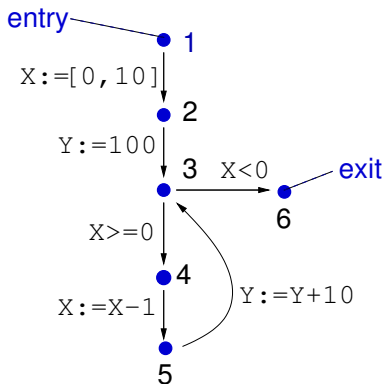
Example

```

1X := [0, 10]; 2
  Y := 100;
  while 3X >= 0 do 4
    X := X - 1; 5
    Y := Y + 10
  done 6

```

structured program



control flow graph

Structured programs can be easily compiled into a CFG.

We use structured program as examples, but present our analysis formally on CFG.

Concrete semantics

Forward concrete semantics

Semantics of expressions: $E[e]: (\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{I})$

The evaluation of e in ρ gives a **set** of values:

$$\begin{aligned}
 E[[c, c']] \rho & \stackrel{\text{def}}{=} \{x \in \mathbb{I} \mid c \leq x \leq c'\} \\
 E[[v]] \rho & \stackrel{\text{def}}{=} \{\rho(v)\} \\
 E[[-e]] \rho & \stackrel{\text{def}}{=} \{-v \mid v \in E[[e]] \rho\} \\
 E[[e_1 + e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 + v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 - e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 - v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 \times e_2]] \rho & \stackrel{\text{def}}{=} \{v_1 \times v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 / e_2]] \rho & \stackrel{\text{def}}{=} \{v_1/v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho, v_2 \neq 0\}
 \end{aligned}$$

Forward concrete semantics (cont.)

Semantics of commands: $C[[c]]: \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

A **transfer function** for c defines a **relation** on environments:

$$\begin{aligned} C[[v := e]] \mathcal{X} &\stackrel{\text{def}}{=} \{ \rho [v \mapsto v] \mid \rho \in \mathcal{X}, v \in E[[e]] \rho \} \\ C[[e \bowtie 0]] \mathcal{X} &\stackrel{\text{def}}{=} \{ \rho \mid \rho \in \mathcal{X}, \exists v \in E[[e]] \rho, v \bowtie 0 \} \end{aligned}$$

It relates the environments after the execution of a command to the environments before.

Complete **join morphism**: $C[[c]] \mathcal{X} = \bigcup_{\rho \in \mathcal{X}} C[[c]] \{ \rho \}$.

Forward concrete semantics (cont.)

Semantics of programs: $P\llbracket(L, e, x, A)\rrbracket : L \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$P\llbracket(L, e, x, A)\rrbracket \ell$ is the **most precise invariant** at $\ell \in L$.

It is the **smallest** solution of a recursive equation system $(\mathcal{X}_\ell)_{\ell \in L}$:

Semantic equation system

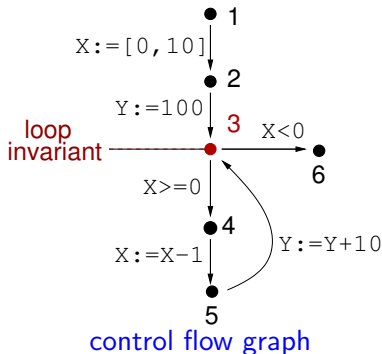
\mathcal{X}_e (given initial state)

$\mathcal{X}_{\ell \neq e} = \bigcup_{(\ell', c, \ell) \in A} C\llbracket c \rrbracket \mathcal{X}_{\ell'}$ (transfer function)

Tarski's Theorem: this smallest solution exists and is unique.

- $\mathcal{D} \stackrel{\text{def}}{=} (\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}), \subseteq, \cup, \cap, \emptyset, (\mathbb{V} \rightarrow \mathbb{I}))$ is a complete lattice,
- each $M_\ell : \mathcal{X}_\ell \rightarrow \bigcup_{(\ell', c, \ell) \in A} C\llbracket c \rrbracket \mathcal{X}_{\ell'}$ is monotonic in \mathcal{D} .
 \Rightarrow the solution is the least fixpoint of $(M_\ell)_{\ell \in L}$.

Forward concrete semantics (example)



$$\left\{ \begin{array}{l} \mathcal{X}_1 = (\{X, Y\} \rightarrow \mathbb{Z}) \\ \mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1 \\ \mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup \\ \quad C[Y := Y + 10] \mathcal{X}_5 \\ \mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3 \\ \mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4 \\ \mathcal{X}_6 = C[X < 0] \mathcal{X}_3 \end{array} \right.$$

equation system

Loop invariant:

$$\mathcal{X}_3 = \{ \rho \mid \rho(X) \in [0, 10], 10\rho(X) + \rho(Y) \in [100, 200] \cap 10\mathbb{Z} \}$$

Resolution

Resolution by increasing iterations:

$$\left\{ \begin{array}{l} \mathcal{X}_e^0 \\ \mathcal{X}_{\ell \neq e}^0 \end{array} \right. \stackrel{\text{def}}{=} \mathcal{X}_e \quad \left\{ \begin{array}{l} \mathcal{X}_e^{n+1} \\ \mathcal{X}_{\ell \neq e}^{n+1} \end{array} \right. \stackrel{\text{def}}{=} \mathcal{X}_e \bigcup_{(\ell', c, \ell) \in A} C[[c]] \mathcal{X}_{\ell'}^n$$

Converges in ω iterations to a least solution,
because each $C[[c]]$ is continuous in the CPO \mathcal{D} .

(Kleene fixpoint theorem)

Resolution (example)

$$\left\{ \begin{array}{ll}
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1 & \emptyset \\
 \mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5 & \emptyset \\
 \mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3 & \emptyset \\
 \mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3 & \emptyset
 \end{array} \right. \quad \text{iteration 0}$$

Resolution (example)

$$\left\{ \begin{array}{ll}
 & \text{iteration 1} \\
 \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\
 \mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\
 \mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5 & \emptyset \\
 \mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3 & \emptyset \\
 \mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4 & \emptyset \\
 \mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3 & \emptyset
 \end{array} \right.$$

Resolution (example)

		iteration 2
$\mathcal{X}_1 = \mathbb{Z}^2$		\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]] \mathcal{X}_1$		$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5$		$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$		\emptyset
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$		\emptyset
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$		\emptyset

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup$ $C[[Y := Y + 10]] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	\emptyset
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	\emptyset

iteration 3

Resolution (example)

		iteration 4
{	$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
	$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
	$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup$ $C[[Y := Y + 10]] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100)\}$
	$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100)\}$
	$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{(-1, 100), \dots, (9, 100)\}$
	$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	\emptyset

Resolution (example)

	iteration 5
$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100), (-1, 110), \dots, (9, 110)\}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100)\}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{(-1, 100), \dots, (9, 100)\}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	\emptyset

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup$ $C[[Y := Y + 10]] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110)\}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110)\}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{(-1, 100), \dots, (9, 100)\}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	$\{(-1, 110)\}$

iteration 6

Resolution (example)

	iteration 7
$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5$	$\{(0, 100), \dots, (10, 100), (-1, 110), \dots, (9, 110)\}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{(0, 100), \dots, (10, 100), (0, 110), \dots, (9, 110)\}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{(-1, 100), \dots, (9, 100), (-1, 110), \dots, (8, 110)\}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	$\{(-1, 110)\}$

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100), (-1, 110), \dots, (9, 110), (-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100), (0, 110), \dots, (9, 110) \}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100), (-1, 110), \dots, (8, 110) \}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	$\{ (-1, 110) \}$

iteration 8

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup C[[Y := Y + 10]] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110),$ $(0, 120), \dots, (8, 120) \}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110) \}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120) \}$

iteration 9

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[[X := [0, 10]]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[[Y := 100]] \mathcal{X}_2 \cup$ $C[[Y := Y + 10]] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100),$ $(-1, 110), \dots, (9, 110),$ $(-1, 120), \dots, (8, 120) \}$
$\mathcal{X}_4 = C[[X \geq 0]] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100),$ $(0, 110), \dots, (9, 110),$ $(0, 120), \dots, (8, 120) \}$
$\mathcal{X}_5 = C[[X := X - 1]] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100),$ $(-1, 110), \dots, (8, 110),$ $(-1, 120), \dots, (7, 120) \}$
$\mathcal{X}_6 = C[[X < 0]] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120) \}$

iteration 10

Resolution (example)

$\mathcal{X}_1 = \mathbb{Z}^2$	\mathbb{Z}^2
$\mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1$	$[0, 10] \times \mathbb{Z}$
$\mathcal{X}_3 = C[Y := 100] \mathcal{X}_2 \cup C[Y := Y + 10] \mathcal{X}_5$	$\{ (0, 100), \dots, (10, 100), (-1, 110), \dots, (9, 110), (-1, 120), \dots, (8, 120), \dots \}$
$\mathcal{X}_4 = C[X \geq 0] \mathcal{X}_3$	$\{ (0, 100), \dots, (10, 100), (0, 110), \dots, (9, 110), (0, 120), \dots, (8, 120), \dots \}$
$\mathcal{X}_5 = C[X := X - 1] \mathcal{X}_4$	$\{ (-1, 100), \dots, (9, 100), (-1, 110), \dots, (8, 110), (-1, 120), \dots, (7, 120), \dots \}$
$\mathcal{X}_6 = C[X < 0] \mathcal{X}_3$	$\{ (-1, 110), (-1, 120), \dots \}$

iteration ...

Backward concrete semantics

Semantics of commands: $\overleftarrow{C}[[c]]: \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$$\overleftarrow{C}[[v := e]] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho \mid \exists v \in E[e] \rho, \rho[v \mapsto v] \in \mathcal{X} \}$$

$$\overleftarrow{C}[[e \bowtie 0]] \mathcal{X} \stackrel{\text{def}}{=} C[[e \bowtie 0]] \mathcal{X}$$

(necessary conditions on ρ to have a successor in \mathcal{X} by c)

Refinement decreasing iterations: given:

- a solution $(\mathcal{X}_\ell)_{\ell \in L}$ of the forward system
- an output criterion \mathcal{Y}_x

compute a least fixpoint by decreasing iterations [Bour93b]

$$\left\{ \begin{array}{l} \mathcal{Y}_x^0 \stackrel{\text{def}}{=} \mathcal{X}_x \cap \mathcal{Y}_x \\ \mathcal{Y}_{\ell \neq x}^0 \stackrel{\text{def}}{=} \mathcal{X}_\ell \\ \mathcal{Y}_x^{n+1} \stackrel{\text{def}}{=} \mathcal{X}_x \cap \mathcal{Y}_x \\ \mathcal{Y}_{\ell \neq x}^{n+1} \stackrel{\text{def}}{=} \mathcal{X}_\ell \cap \left(\bigcup_{(l,c,\ell') \in A} \overleftarrow{C}[[c]] \mathcal{Y}_{\ell'}^n \right) \end{array} \right.$$

Limit to automation

We wish to perform **automatic** numerical invariant discovery.

Theoretical problems

- elements of $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$ are **not computer representable**
- transfer functions $C[[c]]$, $\overleftarrow{C}[[c]]$ are **not computable**
- lattice iterations in $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$ are **transfinite**

Finding the best invariant is an **undecidable problem**

Note:

Even when \mathbb{I} is finite, a concrete analysis is **not tractable**:

- representing elements in $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$ in extension is expensive
- computing $C[[c]]$, $\overleftarrow{C}[[c]]$ explicitly is expensive
- the lattice $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$ has a large height (\Rightarrow many iterations)

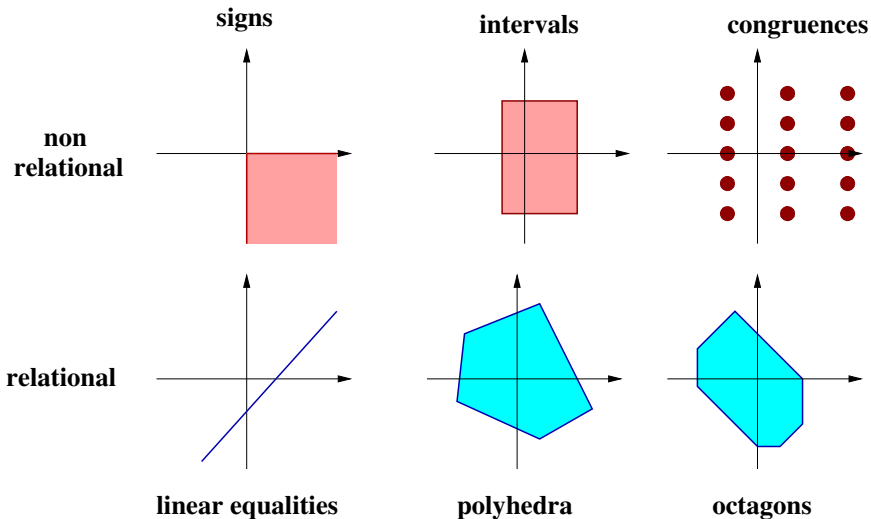
Abstraction

Numerical abstract domains

A **numerical abstract domain** is given by:

- a subset of $\mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$
(a set of environment sets)
together with a machine encoding,
- effective and sound abstract operators,
- an iteration strategy
ensuring convergence in finite time.

Numerical abstract domain examples



Numerical abstract domains (cont.)

Representation: given by

- a set $\mathcal{D}^\#$ of machine-representable abstract values,
- a **partial order** $(\mathcal{D}^\#, \sqsubseteq, \perp^\#, \top^\#)$
relating the amount of information given by abstract values,
- a **concretization** function $\gamma: \mathcal{D}^\# \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$
giving a concrete meaning to each abstract element.

Required algebraic properties:

- γ should be **monotonic** for \sqsubseteq : $\mathcal{X}^\# \sqsubseteq \mathcal{Y}^\# \implies \gamma(\mathcal{X}^\#) \subseteq \gamma(\mathcal{Y}^\#)$,
- $\gamma(\perp^\#) = \emptyset$,
- $\gamma(\top^\#) = \mathbb{V} \rightarrow \mathbb{I}$.

Note: γ need not be one-to-one.

Numerical abstract domains (cont.)

Abstract operators: we require:

- sound, effective, abstract **transfer functions** $C^\# \llbracket c \rrbracket$, $\overleftarrow{C}^\# \llbracket c \rrbracket$ for all commands c ,
- sound, effective, abstract **set operators** $\cup^\#$, $\cap^\#$,
- an algorithm to decide the **ordering** \sqsubseteq .

Soundness criterion:

$F^\#$ is a **sound** abstraction of a n -ary operator F if:

$$\forall x_1^\#, \dots, x_n^\# \in D^\#, F(\gamma(x_1^\#), \dots, \gamma(x_n^\#)) \subseteq \gamma(F^\#(x_1^\#, \dots, x_n^\#))$$

Both **semantic** and **algorithmic** aspects.

Abstract semantics

Abstract semantic equation system

$$\mathcal{X}^\# : L \rightarrow \mathcal{D}^\#$$

$$\mathcal{X}_\ell^\# \sqsupseteq \begin{cases} \mathcal{X}_e^\# & \text{if } \ell = e & \text{(where } \mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^\#)) \\ \bigcup_{(l', c, \ell) \in A} C^\#[c] \mathcal{X}_{l'}^\# & \text{if } \ell \neq e & \text{(abstract transfer function)} \end{cases}$$

Soundness Theorem

Any solution $(\mathcal{X}_\ell^\#)_{\ell \in L}$ is a **sound over-approximation** of the concrete collecting semantics:

$$\forall \ell \in L, \gamma(\mathcal{X}_\ell^\#) \supseteq \mathcal{X}_\ell \quad \left| \quad \begin{array}{l} \text{where } \mathcal{X}_\ell \text{ is the smallest solution of} \\ \left\{ \begin{array}{ll} \mathcal{X}_e & \text{given} \\ \mathcal{X}_\ell = \bigcup_{(l', c, \ell) \in A} C[c] \mathcal{X}_{l'} & \text{if } \ell \neq e \end{array} \right. \end{array} \right.$$

Iteration strategy

Resolution by iterations in \mathcal{D}^\sharp :

To **effectively** solve the abstract system, we require:

- an **iteration ordering** on abstract equations
(which equation(s) are applied at a given iteration)
- a **widening operator** ∇ to speed-up the convergence, if there are infinite strictly increasing chains in \mathcal{D}^\sharp .

$\nabla : (\mathcal{D}^\sharp \times \mathcal{D}^\sharp) \rightarrow \mathcal{D}^\sharp$ is a widening if:

- it is sound: $\gamma(\mathcal{X}^\sharp) \cup \gamma(\mathcal{Y}^\sharp) \subseteq \gamma(\mathcal{X}^\sharp \nabla \mathcal{Y}^\sharp)$

- it enforces termination:

\forall sequence $(\mathcal{Y}_i^\sharp)_{i \in \mathbb{N}}$

the sequence $\mathcal{X}_0^\sharp = \mathcal{Y}_0^\sharp, \mathcal{X}_{i+1}^\sharp = \mathcal{X}_i^\sharp \nabla \mathcal{Y}_{i+1}^\sharp$

stabilizes in finite time: $\exists n < \omega, \mathcal{X}_{n+1}^\sharp = \mathcal{X}_n^\sharp$

(note: $\exists n, \forall m \geq n, \mathcal{X}_{m+1}^\sharp = \mathcal{X}_m^\sharp$ is **not** required)

Abstract analysis

$\mathcal{W} \subseteq L$ is a set of **widening points** if every CFG cycle has a point in \mathcal{W} .

Forward analysis:

$$\mathcal{X}_e^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_e^{\#} \quad \text{given, such that } \mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^{\#})$$

$$\mathcal{X}_{l \neq e}^{\#0} \stackrel{\text{def}}{=} \perp^{\#}$$

$$\mathcal{X}_l^{\#n+1} \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}_e^{\#} & \text{if } l = e \\ \bigcup_{(l',c,l) \in A} C^{\#}[[c]] \mathcal{X}_{l'}^{\#n} & \text{if } l \notin \mathcal{W}, l \neq e \\ \mathcal{X}_l^{\#n} \nabla \bigcup_{(l',c,l) \in A} C^{\#}[[c]] \mathcal{X}_{l'}^{\#n} & \text{if } l \in \mathcal{W}, l \neq e \end{cases}$$

- **termination:** for some δ , $\forall l, \mathcal{X}_l^{\#\delta+1} = \mathcal{X}_l^{\#\delta}$
- **soundness:** $\forall l \in L, \mathcal{X}_l \subseteq \gamma(\mathcal{X}_l^{\#\delta})$
- can be refined by decreasing iterations with narrowing Δ (presented later)
- here, apply every equation at each step, but other iteration scheme are possible (worklist, chaotic iterations, see [Bour93a])

Abstract analysis (proof)

Proof of soundness:

Suppose that $\forall \ell, \mathcal{X}_\ell^{\#\delta+1} = \mathcal{X}_\ell^{\#\delta}$.

If $\ell = e$, by definition: $\mathcal{X}_e^{\#\delta} = \mathcal{X}_e^\#$ and $\mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^{\#\delta})$.

If $\ell \neq e, \ell \notin \mathcal{W}$, then $\mathcal{X}_\ell^{\#\delta} = \mathcal{X}_\ell^{\#\delta+1} = \bigcup_{(\ell', c, \ell) \in A}^\# \mathbf{C}^\#[[c]] \mathcal{X}_{\ell'}^{\#\delta}$.

By soundness of $\bigcup^\#$ and $\mathbf{C}^\#[[c]]$, $\gamma(\mathcal{X}_\ell^{\#\delta}) \supseteq \bigcup_{(\ell', c, \ell) \in A} \mathbf{C}[[c]] \gamma(\mathcal{X}_{\ell'}^{\#\delta})$.

If $\ell \neq e, \ell \in \mathcal{W}$, then $\mathcal{X}_\ell^{\#\delta} = \mathcal{X}_\ell^{\#\delta+1} = \mathcal{X}_\ell^{\#\delta} \nabla \bigcup_{(\ell', c, \ell) \in A}^\# \mathbf{C}^\#[[c]] \mathcal{X}_{\ell'}^{\#\delta}$.

By soundness of ∇ , $\gamma(\mathcal{X}_\ell^{\#\delta}) \supseteq \gamma(\bigcup_{(\ell', c, \ell) \in A}^\# \mathbf{C}^\#[[c]] \mathcal{X}_{\ell'}^{\#\delta})$,

and so we also have $\gamma(\mathcal{X}_\ell^{\#\delta}) \supseteq \bigcup_{(\ell', c, \ell) \in A} \mathbf{C}[[c]] \gamma(\mathcal{X}_{\ell'}^{\#\delta})$.

We have proved that $\lambda \ell. \gamma(\mathcal{X}_\ell^{\#\delta})$ is a postfixpoint of the concrete equation system. Hence, it is greater than its least solution.

Abstract analysis (proof)

Proof of termination:

Suppose that the iteration does not terminate in finite time.

Given a label $\ell \in L$, we denote by $i_\ell^1, \dots, i_\ell^k, \dots$ the increasing sequence of unstable indices, i.e., such that $\forall k, \mathcal{X}_\ell^{\#i_\ell^{k+1}} \neq \mathcal{X}_\ell^{\#i_\ell^k}$.

As the iteration is not stable, $\forall n, \exists \ell, \mathcal{X}_\ell^{\#n} \neq \mathcal{X}_\ell^{\#n+1}$.

Hence, the sequence $(i_\ell^k)_k$ is infinite for at least one $\ell \in L$.

We argue that $\exists \ell \in \mathcal{W}$ such that $(i_\ell^k)_k$ is infinite as, otherwise,

$N = \max \{ i_\ell^k \mid \ell \in \mathcal{W} \} + |L|$ is finite and satisfies: $\forall n \geq N, \forall \ell \in L, \mathcal{X}_\ell^{\#n} = \mathcal{X}_\ell^{\#n+1}$, contradicting our assumption.

For such a $\ell \in \mathcal{W}$, consider the subsequence $\mathcal{Y}_k^\# = \mathcal{X}_\ell^{\#i_\ell^k}$ comprised of the unstable iterates of $\mathcal{X}_\ell^\#$.

Then $\mathcal{Y}^{\#k+1} = \mathcal{Y}^{\#k} \nabla \mathcal{Z}^{\#k}$ for some sequence $\mathcal{Z}^{\#k}$.

The subsequence is infinite and $\forall k, \mathcal{Y}^{\#k+1} \neq \mathcal{Y}^{\#k}$, which contradicts the definition of ∇ .

Hence, the iteration must terminate in finite time.

Abstract analysis (cont.)

Backward refinement:

Given a forward analysis result $\mathcal{X}^\#$ and an abstract output $\mathcal{Y}_x^\#$.

$$\mathcal{Y}_x^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_x^\# \cap^\# \mathcal{Y}_x^\#$$

$$\mathcal{Y}_{l \neq x}^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_l^\#$$

$$\mathcal{Y}_l^{\#n+1} \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}_x^\# \cap^\# \mathcal{Y}_x^\# & \text{if } l = x \\ \mathcal{X}_l^\# \cap^\# \bigcup_{(l,c,l') \in A} \overleftarrow{C}^\#[[c]] \mathcal{Y}_{l'}^{\#n} & \text{if } l \notin \mathcal{W}, l \neq x \\ \mathcal{Y}_l^{\#n} \Delta (\mathcal{X}_l^\# \cap^\# \bigcup_{(l,c,l') \in A} \overleftarrow{C}^\#[[c]] \mathcal{Y}_{l'}^{\#n}) & \text{if } l \in \mathcal{W}, l \neq x \end{cases}$$

Δ overapproximates \cap while enforcing the convergence of **decreasing** iterations (the definition will be given later, on intervals)

Forward-backward analyses can be iterated [Bour93b].

Exact and best abstractions: Reminders

Galois connection: $(\mathcal{D}, \sqsubseteq) \xrightleftharpoons[\alpha]{\gamma} (\mathcal{D}^\#, \sqsubseteq)$

- α, γ monotonic and $\forall \mathcal{X}, \mathcal{Y}^\#, \alpha(\mathcal{X}) \sqsubseteq \mathcal{Y}^\# \iff \mathcal{X} \sqsubseteq \gamma(\mathcal{Y}^\#)$
- \Rightarrow elements \mathcal{X} have a **best** abstraction: $\alpha(\mathcal{X})$
- \Rightarrow operators F have a **best** abstraction: $F^\# = \alpha \circ F \circ \gamma$

Sometimes, no α exists:

- $\{\gamma(\mathcal{Y}^\#) \mid \mathcal{X} \sqsubseteq \gamma(\mathcal{Y}^\#)\}$ has no greatest lower bound
- abstract elements with the same γ have no best representation

$\alpha \circ F \circ \gamma$ may still be defined for some F (partial α)

Concretization-based optimality:

- **sound** abstraction: $\gamma \circ F^\# \supseteq F \circ \gamma$
- **exact** abstraction: $\gamma \circ F^\# = F \circ \gamma$
- **optimal** abstraction: $\gamma(\mathcal{X}^\#)$ minimal in $\{\gamma(\mathcal{Y}^\#) \mid \mathcal{X} \sqsubseteq \gamma(\mathcal{Y}^\#)\}$

Non-relational domains

Value abstract domain

Idea: start from an abstraction of **values** $\mathcal{P}(\mathbb{I})$

Numerical value abstract domain:

$\mathcal{B}^\#$	abstract values, machine-representable
$\gamma_b: \mathcal{B}^\# \rightarrow \mathcal{P}(\mathbb{I})$	concretization
\sqsubseteq_b	partial order
$\perp_b^\#, \top_b^\#$	represent \emptyset and \mathbb{I}
$\cup_b^\#, \cap_b^\#$	abstractions of \cup and \cap
∇_b	extrapolation operator
$\alpha_b: \mathcal{P}(\mathbb{I}) \rightarrow \mathcal{B}^\#$	abstraction (optional)

Derived abstract domain

$$\mathcal{D}^\# \stackrel{\text{def}}{=} (\mathbb{V} \rightarrow (\mathcal{B}^\# \setminus \{\perp_b^\#\})) \cup \{\perp^\#\}$$

- point-wise extension: $\mathcal{X}^\# \in \mathcal{D}^\#$ is a vector of elements in $\mathcal{B}^\#$ (e.g. using arrays of size $|\mathbb{V}|$)
- smashed $\perp^\#$ (avoids redundant representations of \emptyset)

Definitions on $\mathcal{D}^\#$ derived from $\mathcal{B}^\#$:

$$\gamma(\mathcal{X}^\#) \stackrel{\text{def}}{=} \begin{cases} \emptyset & \text{if } \mathcal{X}^\# = \perp^\# \\ \{\rho \mid \forall v, \rho(v) \in \gamma_b(\mathcal{X}^\#(v))\} & \text{otherwise} \end{cases}$$

$$\alpha(\mathcal{X}) \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X} = \emptyset \\ \lambda v. \alpha_b(\{\rho(v) \mid \rho \in \mathcal{X}\}) & \text{otherwise} \end{cases}$$

$$\top^\# \stackrel{\text{def}}{=} \lambda v. \top_b^\#$$

Derived abstract domain (cont.)

$$\mathcal{X}^\# \sqsubseteq \mathcal{Y}^\# \stackrel{\text{def}}{\iff} \mathcal{X}^\# = \perp^\# \vee (\mathcal{X}^\#, \mathcal{Y}^\# \neq \perp^\# \wedge \forall v, \mathcal{X}^\#(v) \sqsubseteq_b \mathcal{Y}^\#(v))$$

$$\mathcal{X}^\# \cup^\# \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{Y}^\# & \text{if } \mathcal{X}^\# = \perp^\# \\ \mathcal{X}^\# & \text{if } \mathcal{Y}^\# = \perp^\# \\ \lambda v. \mathcal{X}^\#(v) \cup_b^\# \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^\# \nabla \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{Y}^\# & \text{if } \mathcal{X}^\# = \perp^\# \\ \mathcal{X}^\# & \text{if } \mathcal{Y}^\# = \perp^\# \\ \lambda v. \mathcal{X}^\#(v) \nabla_b \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^\# \cap^\# \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X}^\# = \perp^\# \text{ or } \mathcal{Y}^\# = \perp^\# \\ \perp^\# & \text{if } \exists v, \mathcal{X}^\#(v) \cap_b^\# \mathcal{Y}^\#(v) = \perp_b^\# \\ \lambda v. \mathcal{X}^\#(v) \cap_b^\# \mathcal{Y}^\#(v) & \text{otherwise} \end{cases}$$

We will see later how to derive $C^\#[[c]]$, $\overleftarrow{C}^\#[[c]]$ using:

- abstract operators $+_b^\#, \dots$ for $C^\#[[V := e]]$
- backward abstract operators $\overleftarrow{+}_b^\#, \dots$
for $\overleftarrow{C}^\#[[V := e]]$ and $C^\#[[e \bowtie 0]]^\#$

Cartesian abstraction

Non-relational domains “forget” all relationships between variables.

Cartesian abstraction:

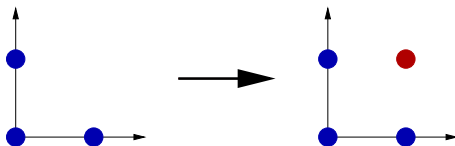
Upper closure operator $\rho_c : \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{V} \rightarrow \mathbb{I})$

$$\rho_c(\mathcal{X}) \stackrel{\text{def}}{=} \{ \rho \in \mathbb{V} \rightarrow \mathbb{I} \mid \forall \mathbf{v} \in \mathbb{V}, \exists \rho' \in \mathcal{X}, \rho(\mathbf{v}) = \rho'(\mathbf{v}) \}$$

A domain is non relational if $\rho \circ \gamma = \gamma$,

i.e. it cannot distinguish between \mathcal{X} and \mathcal{X}' if $\rho_c(\mathcal{X}) = \rho_c(\mathcal{X}')$.

Example: $\rho_c(\{(X, Y) \mid X \in \{0, 2\}, Y \in \{0, 2\}, X + Y \leq 2\}) = \{0, 2\} \times \{0, 2\}$.



Generic non-relational abstract assignments

Given: **sound** abstract versions in $\mathcal{B}^\#$ of all arithmetic operators:

$$\begin{array}{lcl}
 [c, c']_b^\# : & \{x \mid c \leq x \leq c'\} & \sqsubseteq \gamma_b([c, c']_b^\#) \\
 -_b^\# : & \{-x \mid x \in \gamma_b(\mathcal{X}_b^\#)\} & \sqsubseteq \gamma_b(-_b^\# \mathcal{X}_b^\#) \\
 +_b^\# : & \{x+y \mid x \in \gamma_b(\mathcal{X}_b^\#), y \in \gamma_b(\mathcal{Y}_b^\#)\} & \sqsubseteq \gamma_b(\mathcal{X}_b^\# +_b^\# \mathcal{Y}_b^\#) \\
 \vdots & &
 \end{array}$$

We can define:

- an abstract semantics of expressions: $E^\# \llbracket e \rrbracket : D^\# \rightarrow \mathcal{B}^\#$

$$E^\# \llbracket e \rrbracket \perp^\# \stackrel{\text{def}}{=} \perp_b^\#$$

if $\mathcal{X}^\# \neq \perp^\#$:

$$E^\# \llbracket [c, c'] \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} [c, c']_b^\#$$

$$E^\# \llbracket v \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#(v)$$

$$E^\# \llbracket -e \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} -_b^\# E^\# \llbracket e \rrbracket \mathcal{X}^\#$$

$$E^\# \llbracket e_1 + e_2 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} E^\# \llbracket e_1 \rrbracket \mathcal{X}^\# +_b^\# E^\# \llbracket e_2 \rrbracket \mathcal{X}^\#$$

⋮

Generic non-relational abstract assignments (cont.)

We can then define:

- an abstract assignment:

$$C^\# \llbracket v := e \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{V}_b^\# = \perp_b^\# \\ \mathcal{X}^\# [v \mapsto \mathcal{V}_b^\#] & \text{otherwise} \end{cases}$$

where $\mathcal{V}_b^\# = E^\# \llbracket e \rrbracket \mathcal{X}^\#$.

Using a Galois connection (α_b, γ_b) :

We can define **best** abstract arithmetic operators:

$$\begin{aligned} [c, c']_b^\# &\stackrel{\text{def}}{=} \alpha_b(\{x \mid c \leq x \leq c'\}) \\ -_b^\# \mathcal{X}_b^\# &\stackrel{\text{def}}{=} \alpha_b(\{-x \mid x \in \gamma(\mathcal{X}_b^\#)\}) \\ \mathcal{X}_b^\# +_b^\# \mathcal{Y}_b^\# &\stackrel{\text{def}}{=} \alpha_b(\{x+y \mid x \in \gamma(\mathcal{X}_b^\#), y \in \gamma(\mathcal{Y}_b^\#)\}) \\ &\vdots \end{aligned}$$

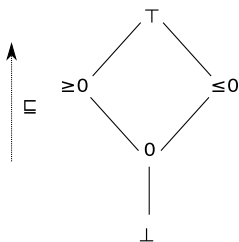
Note: in general, $E^\# \llbracket e \rrbracket$ is less precise than $\alpha_b \circ E \llbracket e \rrbracket \circ \gamma$

e.g. $e = V - V$ and $\gamma_b(\mathcal{X}^\#(V)) = [0, 1]$

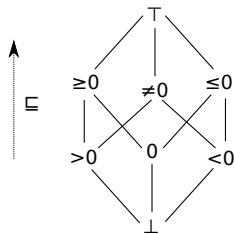
The sign domain

The sign lattices

Hasse diagram: for the lattice $(\mathcal{B}^\#, \sqsubseteq_b, \perp_b, \top_b)$



simple signs



extended signs

The extended sign domain is a refinement of the simple sign domain.

The diagram implicitly defines $\cup^\#$ and $\cap^\#$ as the least upper bound and greatest lower bound for \sqsubseteq .

Operations on simple signs

Abstraction α : there is a **Galois connection** between $\mathcal{B}^\#$ and $\mathcal{P}(\mathbb{I})$:

$$\alpha_b(S) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } S = \emptyset \\ 0 & \text{if } S = \{0\} \\ \geq 0 & \text{else if } \forall s \in S, s \geq 0 \\ \leq 0 & \text{else if } \forall s \in S, s \leq 0 \\ \top_b^\# & \text{otherwise} \end{cases}$$

Derived abstract arithmetic operators:

$$c_b^\# \stackrel{\text{def}}{=} \alpha_b(\{c\}) = \begin{cases} 0 & \text{if } c = 0 \\ \leq 0 & \text{if } c < 0 \\ \geq 0 & \text{if } c > 0 \end{cases}$$

$$X^\# +_b^\# Y^\# \stackrel{\text{def}}{=} \alpha_b(\{x + y \mid x \in \gamma_b(X^\#), y \in \gamma_b(Y^\#)\})$$

$$= \begin{cases} \perp_b^\# & \text{if } X \text{ or } Y^\# = \perp_b^\# \\ 0 & \text{if } X^\# = Y^\# = 0 \\ \leq 0 & \text{else if } X^\# \text{ and } Y^\# \in \{0, \leq 0\} \\ \geq 0 & \text{else if } X^\# \text{ and } Y^\# \in \{0, \geq 0\} \\ \top_b^\# & \text{otherwise} \end{cases}$$

Operations on simple signs (cont.)

Abstract test examples:

$$C^\# \llbracket X \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left(\begin{array}{ll} \mathcal{X}^\# [X \mapsto 0] & \text{if } \mathcal{X}^\#(X) \in \{0, \geq 0\} \\ \mathcal{X}^\# [X \mapsto \leq 0] & \text{if } \mathcal{X}^\#(X) \in \{\top_b^\#, \leq 0\} \\ \perp^\# & \text{otherwise} \end{array} \right)$$

$$C^\# \llbracket X - c \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left(\begin{array}{ll} C^\# \llbracket X \leq 0 \rrbracket \mathcal{X}^\# & \text{if } c \leq 0 \\ \mathcal{X}^\# & \text{otherwise} \end{array} \right)$$

$$C^\# \llbracket X - Y \leq 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left\{ \begin{array}{ll} C^\# \llbracket X \leq 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(Y) \in \{0, \leq 0\} \\ \mathcal{X}^\# & \text{otherwise} \end{array} \right. \cap^\# \left\{ \begin{array}{ll} C^\# \llbracket Y \geq 0 \rrbracket \mathcal{X}^\# & \text{if } \mathcal{X}^\#(X) \in \{0, \geq 0\} \\ \mathcal{X}^\# & \text{otherwise} \end{array} \right.$$

Other cases: $C^\# \llbracket expr \bowtie 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$ is always a sound abstraction.

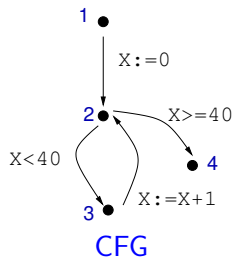
Simple sign analysis example

Example analysis using the simple sign domain:

```

X:=0;
while X<40 do
  X:=X+1
done
  
```

Program



$$\begin{cases}
 \mathcal{X}_2^{\#i+1} &= C^\# \llbracket X := 0 \rrbracket \mathcal{X}_1^{\#i} \cup \\
 & C^\# \llbracket X := X + 1 \rrbracket \mathcal{X}_3^{\#i} \\
 \mathcal{X}_3^{\#i+1} &= C^\# \llbracket X < 40 \rrbracket \mathcal{X}_2^{\#i} \\
 \mathcal{X}_4^{\#i+1} &= C^\# \llbracket X \geq 40 \rrbracket \mathcal{X}_2^{\#i}
 \end{cases}$$

Iteration system

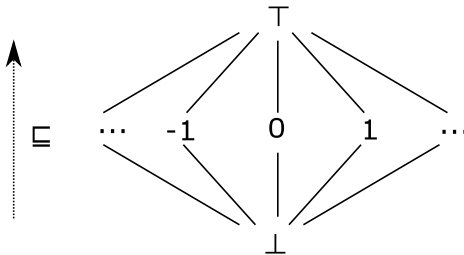
l	$\mathcal{X}_l^{\#0}$	$\mathcal{X}_l^{\#1}$	$\mathcal{X}_l^{\#2}$	$\mathcal{X}_l^{\#3}$	$\mathcal{X}_l^{\#4}$	$\mathcal{X}_l^{\#5}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$	$X \geq 0$
3	$\perp^\#$	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$
4	$\perp^\#$	$\perp^\#$	$X = 0$	$X = 0$	$X \geq 0$	$X \geq 0$

Iterations

The constant domain

The constant lattice

Hasse diagram:



$$\mathcal{B}^\# = \perp \cup \{T_b^\#, \perp_b^\#\}$$

The lattice is **flat** but **infinite**.

Operations on constants

Abstraction α : there is a Galois connection:

$$\alpha_b(S) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } S = \emptyset \\ c & \text{if } S = \{c\} \\ \top_b^\# & \text{otherwise} \end{cases}$$

Derived abstract arithmetic operators:

$$c_b^\# \stackrel{\text{def}}{=} c$$

$$(X^\#) +_b^\# (Y^\#) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } X^\# \text{ or } Y^\# = \perp_b^\# \\ \top_b^\# & \text{else if } X^\# \text{ or } Y^\# = \top_b^\# \\ X^\# + Y^\# & \text{otherwise} \end{cases}$$

$$(X^\#) \times_b^\# (Y^\#) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } X^\# \text{ or } Y^\# = \perp_b^\# \\ 0 & \text{else if } X^\# \text{ or } Y^\# = 0 \\ \top_b^\# & \text{else if } X^\# \text{ or } Y^\# = \top_b^\# \\ X^\# \times Y^\# & \text{otherwise} \end{cases}$$

Operations on constants (cont.)

Abstract test examples:

$$C^\# \llbracket X - c = 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X}^\#(X) \notin \{c, \top_b^\#\} \\ \mathcal{X}^\# \llbracket X \mapsto c \rrbracket & \text{otherwise} \end{cases}$$

$$C^\# \llbracket X - Y - c = 0 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \left(\begin{array}{l} \left(\begin{array}{l} C^\# \llbracket X - (\mathcal{X}^\#(Y) + c) = 0 \rrbracket \mathcal{X}^\# \\ \mathcal{X}^\# \end{array} \right. \begin{array}{l} \text{if } \mathcal{X}^\#(Y) \notin \{\perp_b^\#, \top_b^\#\} \\ \text{otherwise} \end{array} \end{array} \right) \cap^\# \\ \left(\begin{array}{l} \left(\begin{array}{l} C^\# \llbracket Y - (\mathcal{X}^\#(X) - c) = 0 \rrbracket \mathcal{X}^\# \\ \mathcal{X}^\# \end{array} \right. \begin{array}{l} \text{if } \mathcal{X}^\#(X) \notin \{\perp_b^\#, \top_b^\#\} \\ \text{otherwise} \end{array} \end{array} \right) \end{array}$$

Constant analysis example

\mathcal{B}^\sharp has **finite height**, the $(\mathcal{X}_\ell^{\sharp i})$ **converge in finite time**.
(even though \mathcal{B}^\sharp is infinite...)

Analysis example:

```

X:=0; Y:=10;
while X<100 do
  Y:=Y-3;
  X:=X+Y; ●
  Y:=Y+3
done
```

The constant analysis finds, at ●, the invariant: $\begin{cases} X = 7 \\ Y = 7 \end{cases}$

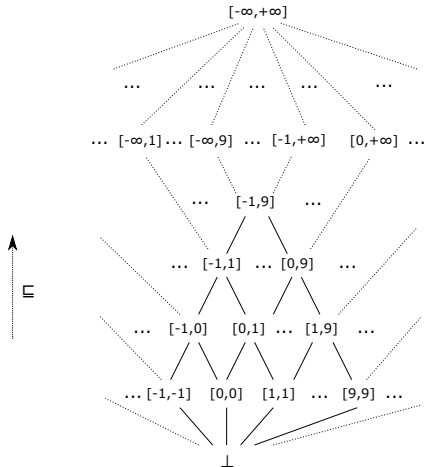
Note: the analysis can find constants **that do not appear syntactically** in the program.

The interval domain

The interval lattice

Introduced by [Cous76].

$$\mathcal{B}^\# \stackrel{\text{def}}{=} \{ [a, b] \mid a \in \mathbb{I} \cup \{-\infty\}, b \in \mathbb{I} \cup \{+\infty\}, a \leq b \} \cup \{\perp^\#\}$$



Note: intervals are open at infinite bounds $+\infty$, $-\infty$.

The interval lattice (cont.)

Galois connection (α_b, γ_b):

$$\gamma_b([a, b]) \stackrel{\text{def}}{=} \{x \in \mathbb{I} \mid a \leq x \leq b\}$$

$$\alpha_b(\mathcal{X}) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } \mathcal{X} = \emptyset \\ [\min \mathcal{X}, \max \mathcal{X}] & \text{otherwise} \end{cases}$$

If $\mathbb{I} = \mathbb{Q}$, α_b is not always defined...

Partial order:

$$[a, b] \sqsubseteq_b [c, d] \stackrel{\text{def}}{\iff} a \geq c \text{ and } b \leq d$$

$$\top_b^\# \stackrel{\text{def}}{=}] - \infty, +\infty[$$

$$[a, b] \cup_b^\# [c, d] \stackrel{\text{def}}{=} [\min(a, c), \max(b, d)]$$

$$[a, b] \cap_b^\# [c, d] \stackrel{\text{def}}{=} \begin{cases} [\max(a, c), \min(b, d)] & \text{if } \max \leq \min \\ \perp_b^\# & \text{otherwise} \end{cases}$$

If $\mathbb{I} \neq \mathbb{Q}$, it is a **complete lattice**.

Interval abstract arithmetic operators

$$[c, c'] \#_b \stackrel{\text{def}}{=} [c, c']$$

$$-\#_b [a, b] \stackrel{\text{def}}{=} [-b, -a]$$

$$[a, b] +\#_b [c, d] \stackrel{\text{def}}{=} [a + c, b + d]$$

$$[a, b] -\#_b [c, d] \stackrel{\text{def}}{=} [a - d, b - c]$$

$$[a, b] \times\#_b [c, d] \stackrel{\text{def}}{=} [\min(ac, ad, bc, bd), \max(ac, ad, bc, bd)]$$

$$[a, b] /\#_b [c, d] \stackrel{\text{def}}{=} \begin{cases} \perp\#_b & \text{if } c = d = 0 \\ [\min(a/c, a/d, b/c, b/d), \max(a/c, a/d, b/c, b/d)] & \text{else if } 0 \leq c \\ [-b, -a] /\#_b [-d, -c] & \text{else if } d \leq 0 \\ ([a, b] /\#_b [c, 0]) \cup\#_b ([a, b] /\#_b [0, d]) & \text{otherwise} \end{cases}$$

$$\text{where } \left| \begin{array}{l} \pm\infty \times 0 = 0, \quad 0/0 = 0, \quad \forall x, x/\pm\infty = 0 \\ \forall x > 0, x/0 = +\infty, \quad \forall x < 0, x/0 = -\infty \end{array} \right.$$

Operators are **strict**: $-\#_b \perp\#_b = \perp\#_b$, $[a, b] +\#_b \perp\#_b = \perp\#_b$, etc.

Exactness and optimality: Example proofs

Proof: **exactness** of $+_b^\sharp$

$$\begin{aligned}
 & \{x + y \mid x \in \gamma_b([a, b]), y \in \gamma_b([c, d])\} \\
 = & \{x + y \mid a \leq x \leq b \wedge c \leq y \leq d\} \\
 = & \{z \mid a + c \leq z \leq b + d\} \\
 = & \gamma_b([a + c, b + d]) \\
 = & \gamma_b([a, b] +_b^\sharp [c, d])
 \end{aligned}$$

Proof **optimality** of \cup_b^\sharp

$$\begin{aligned}
 & \alpha_b(\gamma_b([a, b]) \cup \gamma_b([c, d])) \\
 = & \alpha_b(\{x \mid a \leq x \leq b\} \cup \{x \mid c \leq x \leq d\}) \\
 = & \alpha_b(\{x \mid a \leq x \leq b \vee c \leq x \leq d\}) \\
 = & [\min \{x \mid a \leq x \leq b \vee c \leq x \leq d\}, \max \{x \mid a \leq x \leq b \vee c \leq x \leq d\}] \\
 = & [\min(a, c), \max(b, d)] \\
 = & [a, b] \cup_b^\sharp [c, d]
 \end{aligned}$$

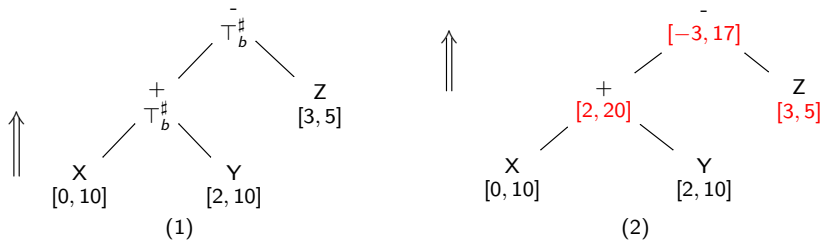
but \cup_b^\sharp is not exact

...

Generic interval abstract tests, step 1

Example: $C^\# \llbracket X + Y - Z \leq 0 \rrbracket \mathcal{X}^\#$
 with $\mathcal{X}^\# = \{ X \mapsto [0, 10], Y \mapsto [2, 10], Z \mapsto [3, 5] \}$

First step: **annotate** the expression tree with intervals

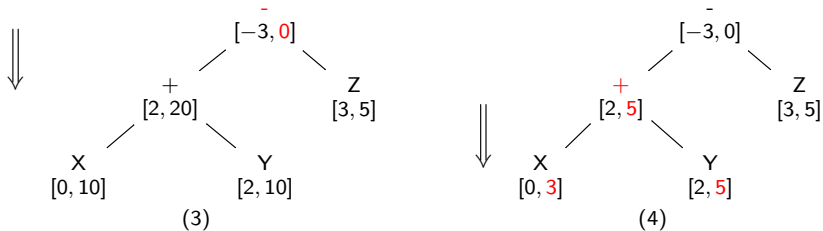


Bottom-up evaluation similar to interval expression evaluation using $+^\#$, $-^\#$, etc. but storing intervals at each node.

Generic interval abstract tests, step 2

Example: $C^\# \llbracket X + Y - Z \leq 0 \rrbracket \mathcal{X}^\#$
 with $\mathcal{X}^\# = \{ X \mapsto [0, 10], Y \mapsto [2, 10], Z \mapsto [3, 5] \}$

Second step: top-down expression refinement.



- refine the **root** interval, knowing that the result should be negative;
- **propagate** refined intervals **downwards**;
- intervals at **leaf variables** provide new information to store into $\mathcal{X}^\#$.
 $\{ X \mapsto [0, 3], Y \mapsto [2, 5], Z \mapsto [3, 5] \}$

Backward arithmetic and comparison operators

In general, we need **sound backward** arithmetic and comparison operators that **refine** their arguments given a result.

Soundness condition: for $\overleftarrow{\leq}_b^\sharp$, $\overleftarrow{+}_b^\sharp$, $\overleftarrow{-}_b^\sharp$, \dots

$$\mathcal{X}_b^{\sharp'} = \overleftarrow{\leq}_b^\sharp(\mathcal{X}_b^\sharp) \implies \{x \in \gamma_b(\mathcal{X}_b^\sharp) \mid x \leq 0\} \subseteq \gamma_b(\mathcal{X}_b^{\sharp'}) \subseteq \gamma_b(\mathcal{X}_b^\sharp)$$

$$\mathcal{X}_b^{\sharp'} = \overleftarrow{-}_b^\sharp(\mathcal{X}_b^\sharp, \mathcal{R}_b^\sharp) \implies \{x \mid x \in \gamma_b(\mathcal{X}_b^\sharp), -x \in \gamma_b(\mathcal{R}_b^\sharp)\} \subseteq \gamma_b(\mathcal{X}_b^{\sharp'}) \subseteq \gamma_b(\mathcal{X}_b^\sharp)$$

$$\begin{aligned} (\mathcal{X}_b^{\sharp'}, \mathcal{Y}_b^{\sharp'}) &= \overleftarrow{+}_b^\sharp(\mathcal{X}_b^\sharp, \mathcal{Y}_b^\sharp, \mathcal{R}_b^\sharp) \implies \\ &\{x \in \gamma_b(\mathcal{X}_b^\sharp) \mid \exists y \in \gamma_b(\mathcal{Y}_b^\sharp), x + y \in \gamma_b(\mathcal{R}_b^\sharp)\} \subseteq \gamma_b(\mathcal{X}_b^{\sharp'}) \subseteq \gamma_b(\mathcal{X}_b^\sharp) \\ &\{y \in \gamma_b(\mathcal{Y}_b^\sharp) \mid \exists x \in \gamma_b(\mathcal{X}_b^\sharp), x + y \in \gamma_b(\mathcal{R}_b^\sharp)\} \subseteq \gamma_b(\mathcal{Y}_b^{\sharp'}) \subseteq \gamma_b(\mathcal{Y}_b^\sharp) \\ &\vdots \end{aligned}$$

Note: **best** backward operators can be designed with α_b :

e.g. for $\overleftarrow{+}_b^\sharp$: $\mathcal{X}_b^{\sharp'} = \alpha_b(\{x \in \gamma_b(\mathcal{X}_b^\sharp) \mid \exists y \in \gamma_b(\mathcal{Y}_b^\sharp), x + y \in \gamma_b(\mathcal{R}_b^\sharp)\})$

Generic backward operator construction

Synthesizing (non optimal) backward arithmetic operators from forward arithmetic operators.

$$\overleftarrow{0}_b^\#(x_b^\#) \stackrel{\text{def}}{=} x_b^\# \cap_b^\#]-\infty, 0]_b^\#$$

$$\overleftarrow{_}{}_b^\#(x_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} x_b^\# \cap_b^\# (-_{}_b^\# \mathcal{R}_b^\#)$$

$$\overleftarrow{+}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# -_{}_b^\# y_b^\#), y_b^\# \cap_b^\# (\mathcal{R}_b^\# -_{}_b^\# x_b^\#))$$

$$\overleftarrow{-}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# +_{}_b^\# y_b^\#), y_b^\# \cap_b^\# (x_b^\# -_{}_b^\# \mathcal{R}_b^\#))$$

$$\overleftarrow{/}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (\mathcal{R}_b^\# /_{}_b^\# y_b^\#), y_b^\# \cap_b^\# (\mathcal{R}_b^\# /_{}_b^\# x_b^\#))$$

$$\overleftarrow{\setminus}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) \stackrel{\text{def}}{=} (x_b^\# \cap_b^\# (S_b^\# \times_{}_b^\# y_b^\#), y_b^\# \cap_b^\# ((x_b^\# /_{}_b^\# S_b^\#) \cup_b^\# [0, 0]_b^\#))$$

where $S_b^\# = \begin{cases} \mathcal{R}_b^\# & \text{if } \mathbb{I} \neq \mathbb{Z} \\ \mathcal{R}_b^\# +_{}_b^\# [-1, 1]_b^\# & \text{if } \mathbb{I} = \mathbb{Z} \text{ (as } / \text{ rounds)} \end{cases}$

Note: $\overleftarrow{\diamond}_b^\#(x_b^\#, y_b^\#, \mathcal{R}_b^\#) = (x_b^\#, y_b^\#)$ is always sound (no refinement).

Interval backward operators

Applying the generic construction to the interval domain:

$$\overleftarrow{0}_b^\#([a, b]) \stackrel{\text{def}}{=} \begin{cases} [a, \min(b, 0)] & \text{if } a \geq 0 \\ \perp_b^\# & \text{otherwise} \end{cases}$$

$$\overleftarrow{-}_b^\#([a, b], [r, s]) \stackrel{\text{def}}{=} [a, b] \cap_b^\# [-s, -r]$$

$$\overleftarrow{+}_b^\#([a, b], [c, d], [r, s]) \stackrel{\text{def}}{=} ([a, b] \cap_b^\# [r - d, s - c], [c, d] \cap_b^\# [r - b, s - a])$$

...

Generic non-relational backward assignment

Abstract function: $\overleftarrow{C}^\# \llbracket v := e \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#)$

over-approximates $\gamma(\mathcal{X}^\#) \cap \overleftarrow{C} \llbracket v := e \rrbracket \gamma(\mathcal{R}^\#)$ given:

- an abstract pre-condition $\mathcal{X}^\#$ to refine,
- according to a given abstract post-condition $\mathcal{R}^\#$.

Algorithm: similar to the abstract test

- annotate **variable leaves** based on $\mathcal{X}^\# \cap^\# (\mathcal{R}^\# [v \mapsto T_b^\#])$;
- **evaluate** bottom-up using forward operators $\diamond_b^\#$;
- **intersect** the root with $\mathcal{R}^\#(v)$;
- **refine** top-down using backward operators $\overleftarrow{\diamond}_b^\#$;
- **return** $\mathcal{X}^\#$ **intersected** with values at variable leaves.

Note:

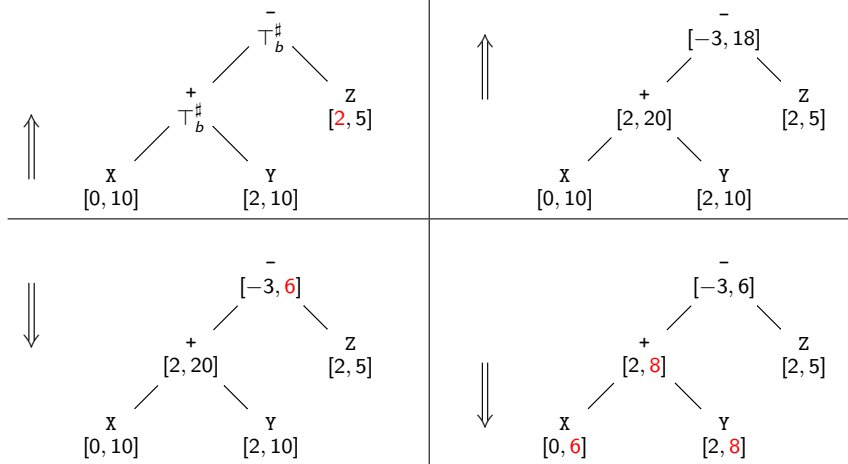
- local iterations can also be used
- fallback: $\overleftarrow{C}^\# \llbracket v := e \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#) = \mathcal{X}^\# \cap^\# (\mathcal{R}^\# [v \mapsto T_b^\#])$

Interval backward assignment example

Example: $\overleftarrow{C}^\# \llbracket X := X + Y - Z \rrbracket (\mathcal{X}^\#, \mathcal{R}^\#)$

with $\mathcal{X}^\# = \{ X \mapsto [0, 10], Y \mapsto [2, 10], Z \mapsto [1, 5] \}$

and $\mathcal{R}^\# = \{ X \mapsto [-6, 6], Y \mapsto [2, 10], Z \mapsto [2, 6] \}$



Interval widening

Widening on non-relational domains:

Given a value widening $\nabla_b: \mathcal{B}^\# \times \mathcal{B}^\# \rightarrow \mathcal{B}^\#$,

we extend it point-wisely into a widening $\nabla: \mathcal{D}^\# \times \mathcal{D}^\# \rightarrow \mathcal{D}^\#$:

$$\mathcal{X}^\# \nabla \mathcal{Y}^\# \stackrel{\text{def}}{=} \lambda v. (\mathcal{X}^\#(v) \nabla_b \mathcal{Y}^\#(v))$$

Interval widening example:

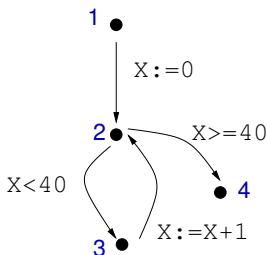
$$\perp^\# \quad \nabla_b \quad \mathcal{X}^\# \quad \stackrel{\text{def}}{=} \quad \mathcal{X}^\#$$

$$[a, b] \quad \nabla_b \quad [c, d] \quad \stackrel{\text{def}}{=} \quad \left[\left\{ \begin{array}{ll} a & \text{if } a \leq c \\ -\infty & \text{otherwise} \end{array} \right\}, \left\{ \begin{array}{ll} b & \text{if } b \geq d \\ +\infty & \text{otherwise} \end{array} \right\} \right]$$

Unstable bounds are set to $\pm\infty$.

Analysis with widening example

Analysis example with $\mathcal{W} = \{2\}$



ℓ	$\mathcal{X}_\ell^{\#0}$	$\mathcal{X}_\ell^{\#1}$	$\mathcal{X}_\ell^{\#2}$	$\mathcal{X}_\ell^{\#3}$	$\mathcal{X}_\ell^{\#4}$	$\mathcal{X}_\ell^{\#5}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2 ∇	$\perp^\#$	$= 0$	$= 0$	≥ 0	≥ 0	≥ 0
3	$\perp^\#$	$\perp^\#$	$= 0$	$= 0$	$\in [0, 39]$	$\in [0, 39]$
4	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	≥ 40	≥ 40

More precisely, at the widening point:

$$\begin{aligned}
 \mathcal{X}_2^{\#1} &= \perp^\# \quad \nabla_b ([0, 0] \cup_b \perp^\#) &= \perp^\# \quad \nabla_b [0, 0] &= [0, 0] \\
 \mathcal{X}_2^{\#2} &= [0, 0] \quad \nabla_b ([0, 0] \cup_b \perp^\#) &= [0, 0] \quad \nabla_b [0, 0] &= [0, 0] \\
 \mathcal{X}_2^{\#3} &= [0, 0] \quad \nabla_b ([0, 0] \cup_b [1, 1]) &= [0, 0] \quad \nabla_b [0, 1] &= [0, +\infty[\\
 \mathcal{X}_2^{\#4} &= [0, +\infty[\quad \nabla_b ([0, 0] \cup_b [1, 40]) &= [0, +\infty[\quad \nabla_b [0, 40] &= [0, +\infty[
 \end{aligned}$$

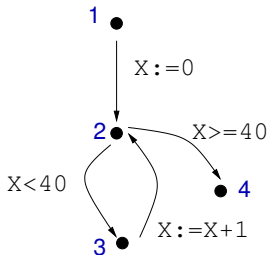
Note that the most precise interval abstraction would be

$X \in [0, 40]$ at 2, and $X = 40$ at 4.

Influence of the widening point and iteration strategy

Changing \mathcal{W} changes the analysis result

Example: The analysis is less precise for $\mathcal{W} = \{3\}$.



ℓ	$\mathcal{X}_\ell^{\#1}$	$\mathcal{X}_\ell^{\#2}$	$\mathcal{X}_\ell^{\#3}$	$\mathcal{X}_\ell^{\#4}$	$\mathcal{X}_\ell^{\#5}$	$\mathcal{X}_\ell^{\#6}$
1	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$	$\top^\#$
2	$= 0$	$= 0$	$\in [0, 1]$	$\in [0, 1]$	≥ 0	≥ 0
3 ∇	$\perp^\#$	$= 0$	$= 0$	≥ 0	≥ 0	≥ 0
4	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	$\perp^\#$	≥ 40

Intuition: extrapolation to $+\infty$ is no longer contained by the tests.

Chaotic iterations

Changing the iteration order changes the analysis result in the presence of a widening.

Narrowing

Using a widening makes the analysis less precise.

Some precision can be retrieved by using a **narrowing** Δ .

Definition: narrowing Δ

Binary operator $\mathcal{D}^\# \times \mathcal{D}^\# \rightarrow \mathcal{D}^\#$ such that:

- $(\mathcal{X}^\# \cap^\# \mathcal{Y}^\#) \sqsubseteq (\mathcal{X}^\# \Delta \mathcal{Y}^\#) \sqsubseteq \mathcal{X}^\#$,
- for all sequences $(\mathcal{X}_i^\#)$, the decreasing sequence $(\mathcal{Y}_i^\#)$

$$\text{defined by } \begin{cases} \mathcal{Y}_0^\# & \stackrel{\text{def}}{=} & \mathcal{X}_0^\# \\ \mathcal{Y}_{i+1}^\# & \stackrel{\text{def}}{=} & \mathcal{Y}_i^\# \Delta \mathcal{X}_{i+1}^\# \end{cases}$$

is **stationary**.

This is not the dual of a widening!

Narrowing examples

Trivial narrowing:

$\mathcal{X}^\# \Delta \mathcal{Y}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$ is a correct narrowing.

Finite-time intersection narrowing:

$$\mathcal{X}^{\#i} \Delta \mathcal{Y}^\# \stackrel{\text{def}}{=} \begin{cases} \mathcal{X}^{\#i} \cap^\# \mathcal{Y}^\# & \text{if } i \leq N \\ \mathcal{X}^{\#i} & \text{if } i > N \end{cases}$$

Interval narrowing:

$$[a, b] \Delta_b [c, d] \stackrel{\text{def}}{=} \left[\begin{cases} c & \text{if } a = -\infty \\ a & \text{otherwise} \end{cases}, \begin{cases} d & \text{if } b = +\infty \\ b & \text{otherwise} \end{cases} \right]$$

(refine only infinite bounds)

Point-wise extension to $\mathcal{D}^\#$: $\mathcal{X}^\# \Delta \mathcal{Y}^\# \stackrel{\text{def}}{=} \lambda v. (\mathcal{X}^\#(v) \Delta_b \mathcal{Y}^\#(v))$

Iterations with narrowing

Let $\mathcal{X}_\ell^{\#\delta}$ be the result after widening stabilisation, *i.e.*:

$$\mathcal{X}_\ell^{\#\delta} \sqsupseteq \begin{cases} \top^\# & \text{if } \ell = e \\ \bigcup_{(l',c,\ell) \in A} C^\#[c] \mathcal{X}_{l'}^{\#\delta} & \text{if } \ell \neq e \end{cases}$$

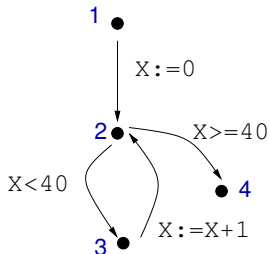
The following sequence is computed:

$$\mathcal{Y}_\ell^{\#0} \stackrel{\text{def}}{=} \mathcal{X}_\ell^{\#\delta} \quad \mathcal{Y}_\ell^{\#i+1} \stackrel{\text{def}}{=} \begin{cases} \top^\# & \text{if } \ell = e \\ \bigcup_{(l',c,\ell) \in A} C^\#[c] \mathcal{Y}_{l'}^{\#i} & \text{if } \ell \notin \mathcal{W} \\ \mathcal{Y}_\ell^{\#i} \triangle \bigcup_{(l',c,\ell) \in A} C^\#[c] \mathcal{Y}_{l'}^{\#i} & \text{if } \ell \in \mathcal{W} \end{cases}$$

- the sequence $(\mathcal{Y}_\ell^{\#i})$ is **decreasing** and **converges in finite time**,
- all $(\mathcal{Y}_\ell^{\#i})$ are **solutions of the abstract semantic system**.

Analysis with narrowing example

Example with $\mathcal{W} = \{2\}$



l	$\mathcal{Y}_l^{\#0}$	$\mathcal{Y}_l^{\#1}$	$\mathcal{Y}_l^{\#2}$	$\mathcal{Y}_l^{\#3}$
1	$\top^{\#}$	$\top^{\#}$	$\top^{\#}$	$\top^{\#}$
2 Δ	≥ 0	$\in [0, 40]$	$\in [0, 40]$	$\in [0, 40]$
3	$\in [0, 39]$	$\in [0, 39]$	$\in [0, 39]$	$\in [0, 39]$
4	≥ 40	≥ 40	$= 40$	$= 40$

Narrowing at 2 gives:

$$\mathcal{Y}_2^{\#1} = [0, +\infty[\Delta_b ([0, 0] \cup_b^{\#} [1, 40]) = [0, +\infty[\Delta_b [0, 40] = [0, 40]$$

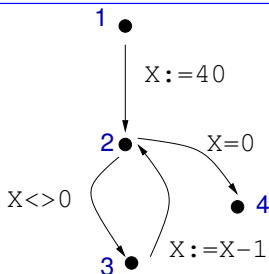
$$\mathcal{Y}_2^{\#2} = [0, 40] \Delta_b ([0, 0] \cup_b^{\#} [1, 40]) = [0, 40] \Delta_b [0, 40] = [0, 40]$$

Then $\mathcal{Y}_2^{\#2} : X \in [0, 40]$ gives $\mathcal{Y}_4^{\#3} : X = 40$.

We found the most precise invariants!

Improving the widening

Example of imprecise analysis



ℓ	intervals with ∇_b	extended signs	intervals with ∇'_b
1	$\top^\#$	$\top^\#$	$\top^\#$
2 ∇	$X \leq 40$	$X \geq 0$	$X \in [0, 40]$
3	$X \leq 40$	$X > 0$	$X \in [0, 40]$
4	$X = 0$	$X = 0$	$X = 0$

The interval domain cannot prove that $X \geq 0$ at 2, while the (less powerful) sign domain can!

Solution: improve the interval widening

$$[a, b] \nabla'_b [c, d] \stackrel{\text{def}}{=} \left[\begin{cases} a & \text{if } a \leq c \\ 0 & \text{if } 0 \leq c < a \\ -\infty & \text{otherwise} \end{cases}, \begin{cases} b & \text{if } b \geq d \\ 0 & \text{if } 0 \geq b > d \\ +\infty & \text{otherwise} \end{cases} \right]$$

(∇'_b checks the stability of 0)

Widening with thresholds

Analysis problem:

```

X:=0;
while • 1=1 do
  if [0,1]=0 then
    X:=X+1;
    if X>40 then X:=0 fi
  fi
done

```

We wish to prove that $X \in [0, 40]$ at \bullet .

- Widening at \bullet finds the loop invariant $X \in [0, +\infty[$.

$$\mathcal{X}_{\bullet}^{\sharp} = [0, 0] \nabla_b ([0, 0] \cup^{\sharp} [0, 1]) = [0, 0] \nabla_b [0, 1] = [0, +\infty[$$

- Narrowing is unable to refine the invariant:

$$\mathcal{Y}_{\bullet}^{\sharp} = [0, +\infty[\Delta_b([0, 0] \cup^{\sharp} [0, +\infty[) = [0, +\infty[$$

(the code that limits X is not executed at every loop iteration)

Widening with thresholds (cont.)

Solution:

Choose a **finite set T of thresholds** containing $+\infty$ and $-\infty$.

Definition: widening with thresholds ∇_b^T

$$[a, b] \nabla_b^T [c, d] \stackrel{\text{def}}{=} \left[\begin{array}{ll} \left\{ \begin{array}{ll} a & \text{if } a \leq c \\ \max \{x \in T \mid x \leq c\} & \text{otherwise} \end{array} \right. & , \\ \left. \begin{array}{ll} \left\{ \begin{array}{ll} b & \text{if } b \geq d \\ \min \{x \in T \mid x \geq d\} & \text{otherwise} \end{array} \right. & \end{array} \right]$$

The widening tests and stops at the first stable bound in T .

Widening with thresholds (cont.)

Applications:

- On the previous example, we find:
 $X \in [0, \min \{x \in T \mid x \geq 40\}]$.
- Useful when it is **easy to find a 'good' set T** .
Example: array bound-checking
- Useful if an **over-approximation of the bound is sufficient**.
Example: arithmetic overflow checking

Limitations: only works if some non- ∞ bound in T is stable.

Example: with $T = \{ 5, 15 \}$

<pre>while 1=1 do X:=X+1; if X>10 then X=0 fi done</pre>	<pre>while 1=1 do X:=X+1; if X<>10 then X=0 fi done</pre>
-----------------------------------------------------------------	---------------------------------------------------------------------

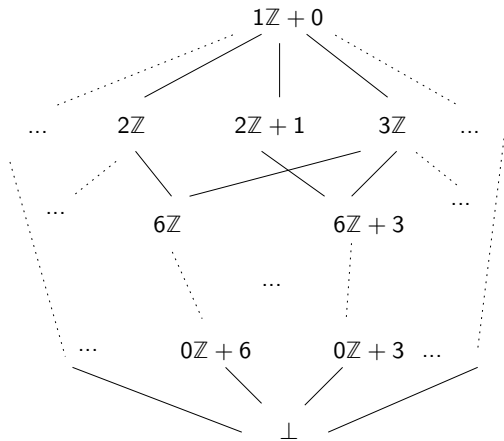
15 is stable

no stable bound

The congruence domain

The congruence lattice

$$\mathcal{B}^\# \stackrel{\text{def}}{=} \{(a\mathbb{Z} + b) \mid a \in \mathbb{N}, b \in \mathbb{Z}\} \cup \{\perp^\#\}$$



Introduced by Granger [Gran89].

We take $\mathbb{I} = \mathbb{Z}$.

The congruence lattice (cont.)

Concretization:

$$\gamma_b(\mathcal{X}_b^\#) \stackrel{\text{def}}{=} \begin{cases} \{ak + b \mid k \in \mathbb{Z}\} & \text{if } \mathcal{X}_b^\# = (a\mathbb{Z} + b) \\ \emptyset & \text{if } \mathcal{X}_b^\# = \perp_b^\# \end{cases}$$

Note that $\gamma(0\mathbb{Z} + b) = \{b\}$.

γ_b is **not injective**: $\gamma_b(2\mathbb{Z} + 1) = \gamma_b(2\mathbb{Z} + 3)$.

Definitions:

Given $x, x' \in \mathbb{Z}$, $y, y' \in \mathbb{N}$, we define:

- $y/y' \stackrel{\text{def}}{\iff} y$ divides y' ($\exists k \in \mathbb{N}, y' = ky$) (note that $\forall y: y/0$)
- $x \equiv x' [y] \stackrel{\text{def}}{\iff} y \mid |x - x'|$ (in particular, $x \equiv x' [0] \iff x = x'$)
- \vee is the LCM, extended with $y \vee 0 \stackrel{\text{def}}{=} 0 \vee y \stackrel{\text{def}}{=} 0$
- \wedge is the GCD, extended with $y \wedge 0 \stackrel{\text{def}}{=} 0 \wedge y \stackrel{\text{def}}{=} y$

$(\mathbb{N}, /, \vee, \wedge, 1, 0)$ is a **complete distributive lattice**.

Abstract congruence operators

Complete lattice structure on \mathcal{B}^\sharp :

- $(a\mathbb{Z} + b) \sqsubseteq_b (a'\mathbb{Z} + b') \stackrel{\text{def}}{\iff} a' / a \text{ and } b \equiv b' [a']$
- $\top_b \stackrel{\text{def}}{=} (1\mathbb{Z} + 0)$
- $(a\mathbb{Z} + b) \cup_b^\sharp (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a' \wedge |b - b'|)\mathbb{Z} + b$
- $(a\mathbb{Z} + b) \cap_b^\sharp (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} (a \vee a')\mathbb{Z} + b'' & \text{if } b \equiv b' [a \wedge a'] \\ \perp_b^\sharp & \text{otherwise} \end{cases}$
 b'' such that $b'' \equiv b [a \vee a'] \equiv b' [a \vee a']$ is given by Bezout's Theorem.

Galois connection: $\alpha_b(\mathcal{X}) = \bigcup_{c \in \mathcal{X}}^\sharp (0\mathbb{Z} + c)$

(up to equivalence $a\mathbb{Z} + b \equiv a'\mathbb{Z} + b' \stackrel{\text{def}}{\iff} a = a' \wedge b \equiv b' [a]$)

Abstract congruence operators (cont.)

Arithmetic operators:

$$[c, c']_b^{\#} \stackrel{\text{def}}{=} \begin{cases} 0\mathbb{Z} + c & \text{if } c = c' \\ \top_b^{\#} & \text{otherwise} \end{cases}$$

$$-_b^{\#} (a\mathbb{Z} + b) \stackrel{\text{def}}{=} a\mathbb{Z} + (-b)$$

$$(a\mathbb{Z} + b) +_b^{\#} (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a')\mathbb{Z} + (b + b')$$

$$(a\mathbb{Z} + b) -_b^{\#} (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (a \wedge a')\mathbb{Z} + (b - b')$$

$$(a\mathbb{Z} + b) \times_b^{\#} (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} (aa' \wedge ab' \wedge a'b)\mathbb{Z} + bb'$$

$$(a\mathbb{Z} + b) /_b^{\#} (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} \perp_b^{\#} & \text{if } a'\mathbb{Z} + b' = 0\mathbb{Z} + 0 \\ (a/|b'|)\mathbb{Z} + (b/b') & \text{if } a' = 0, b' \neq 0, b'|a, \text{ and } b'|b \\ \top_b^{\#} & \text{otherwise (not optimal)} \end{cases}$$

Abstract congruence operators (cont.)

Test operators:

$$\overset{\leftarrow}{\leq}_b^\# (a\mathbb{Z} + b) \stackrel{\text{def}}{=} \begin{cases} \perp_b^\# & \text{if } a = 0, b > 0 \\ a\mathbb{Z} + b & \text{otherwise} \end{cases}$$

⋮

Note: better than the generic $\overset{\leftarrow}{\leq}_b^\# (\mathcal{X}_b^\#) \stackrel{\text{def}}{=} \mathcal{X}_b^\# \cap_b^\#]-\infty, 0]_b^\# = \mathcal{X}_b^\#$

Extrapolation operators:

- no infinite increasing chain \implies no need for ∇
- infinite decreasing chains $\implies \Delta$ needed

$$(a\mathbb{Z} + b) \Delta_b (a'\mathbb{Z} + b') \stackrel{\text{def}}{=} \begin{cases} a'\mathbb{Z} + b' & \text{if } a = 1 \\ a\mathbb{Z} + b & \text{otherwise} \end{cases}$$

Note: $\mathcal{X}^\# \Delta \mathcal{Y}^\# \stackrel{\text{def}}{=} \mathcal{X}^\#$ is always a narrowing.

Reduced products of domains

Non-reduced product of domains

Product representation:

Cartesian product $\mathcal{D}_{1 \times 2}^\sharp$ of \mathcal{D}_1^\sharp and \mathcal{D}_2^\sharp :

- $\mathcal{D}_{1 \times 2}^\sharp \stackrel{\text{def}}{=} \mathcal{D}_1^\sharp \times \mathcal{D}_2^\sharp$
- $\gamma_{1 \times 2}(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \stackrel{\text{def}}{=} \gamma_1(\mathcal{X}_1^\sharp) \cap \gamma_2(\mathcal{X}_2^\sharp)$
- $\alpha_{1 \times 2}(\mathcal{X}) \stackrel{\text{def}}{=} (\alpha_1(\mathcal{X}), \alpha_2(\mathcal{X}))$
- $(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \sqsubseteq_{1 \times 2} (\mathcal{Y}_1^\sharp, \mathcal{Y}_2^\sharp) \iff \mathcal{X}_1^\sharp \sqsubseteq_1 \mathcal{Y}_1^\sharp \text{ and } \mathcal{X}_2^\sharp \sqsubseteq_2 \mathcal{Y}_2^\sharp$

Abstract operators: performed in parallel on both components:

- $(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \cup_{1 \times 2}^\sharp (\mathcal{Y}_1^\sharp, \mathcal{Y}_2^\sharp) \stackrel{\text{def}}{=} (\mathcal{X}_1^\sharp \cup_1^\sharp \mathcal{Y}_1^\sharp, \mathcal{X}_2^\sharp \cup_2^\sharp \mathcal{Y}_2^\sharp)$
- $(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \nabla_{1 \times 2} (\mathcal{Y}_1^\sharp, \mathcal{Y}_2^\sharp) \stackrel{\text{def}}{=} (\mathcal{X}_1^\sharp \nabla_1 \mathcal{Y}_1^\sharp, \mathcal{X}_2^\sharp \nabla_2 \mathcal{Y}_2^\sharp)$
- $\mathbf{C}^\sharp[\![c]\!]_{1 \times 2}(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \stackrel{\text{def}}{=} (\mathbf{C}^\sharp[\![c]\!]_1(\mathcal{X}_1^\sharp), \mathbf{C}^\sharp[\![c]\!]_2(\mathcal{X}_2^\sharp))$

Non-reduced product example

The product analysis is no more precise than two separate analyses.

Example: interval-congruence product:

```

X:=1;
while X-10<=0 do
  X:=X+2
done;
•if X-12>=0 then ♦ X:=0★ fi
  
```

	interval	congruence	product
•	$X \in [11, 12]$	$X \equiv 1 [2]$	$X = 11$
♦	$X = 12$	$X \equiv 1 [2]$	\emptyset
★	$X = 0$	$X = 0$	$X = 0$

We **cannot** prove that the if branch is never taken!

Fully-reduced product

Definition:

Given the Galois connections (α_1, γ_1) and (α_2, γ_2) on \mathcal{D}_1^\sharp and \mathcal{D}_2^\sharp we define the **reduction operator** ρ as:

$$\rho : \mathcal{D}_{1 \times 2}^\sharp \rightarrow \mathcal{D}_{1 \times 2}^\sharp$$

$$\rho(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \stackrel{\text{def}}{=} (\alpha_1(\gamma_1(\mathcal{X}_1^\sharp) \cap \gamma_2(\mathcal{X}_2^\sharp)), \alpha_2(\gamma_1(\mathcal{X}_1^\sharp) \cap \gamma_2(\mathcal{X}_2^\sharp)))$$

ρ propagates information between domains.

Application:

We can reduce the result of each abstract operator, except ∇ :

- $(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \cup_{1 \times 2}^\sharp (\mathcal{Y}_1^\sharp, \mathcal{Y}_2^\sharp) \stackrel{\text{def}}{=} \rho(\mathcal{X}_1^\sharp \cup_1^\sharp \mathcal{Y}_1^\sharp, \mathcal{X}_2^\sharp \cup_2^\sharp \mathcal{Y}_2^\sharp),$
- $\mathbf{C}^\sharp \llbracket c \rrbracket_{1 \times 2}(\mathcal{X}_1^\sharp, \mathcal{X}_2^\sharp) \stackrel{\text{def}}{=} \rho(\mathbf{C}^\sharp \llbracket c \rrbracket_1(\mathcal{X}_1^\sharp), \mathbf{C}^\sharp \llbracket c \rrbracket_2(\mathcal{X}_2^\sharp)).$

We refrain from reducing after a widening ∇ , this may jeopardize the convergence (octagon domain example).

Fully-reduced product example

Reduction example: between the **interval** and **congruence** domains:

$$\text{Noting: } a' \stackrel{\text{def}}{=} \min \{ x \geq a \mid x \equiv d [c] \}$$

$$b' \stackrel{\text{def}}{=} \max \{ x \leq b \mid x \equiv d [c] \}$$

We get:

$$\rho_b([a, b], c\mathbb{Z} + d) \stackrel{\text{def}}{=} \begin{cases} (\perp_b^\#, \perp_b^\#) & \text{if } a' > b' \\ ([a', a'], 0\mathbb{Z} + a') & \text{if } a' = b' \\ ([a', b'], c\mathbb{Z} + d) & \text{if } a' < b' \end{cases}$$

extended point-wisely to ρ on $\mathcal{D}^\#$.

Application:

- $\rho_b([10, 11], 2\mathbb{Z} + 1) = ([11, 11], 0\mathbb{Z} + 11)$
(proves that the branch is never taken on our example)
- $\rho_b([1, 3], 4\mathbb{Z}) = (\perp_b^\#, \perp_b^\#)$

Partially-reduced product

Definition: of a **partial** reduction:

any function $\rho : \mathcal{D}_{1 \times 2}^\# \rightarrow \mathcal{D}_{1 \times 2}^\#$ such that:

$$(\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) = \rho(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \implies \begin{cases} \gamma_{1 \times 2}(\mathcal{Y}_1^\#, \mathcal{Y}_2^\#) = \gamma_{1 \times 2}(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \\ \gamma_1(\mathcal{Y}_1^\#) \subseteq \gamma_1(\mathcal{X}_1^\#) \\ \gamma_2(\mathcal{Y}_2^\#) \subseteq \gamma_2(\mathcal{X}_2^\#) \end{cases}$$

Useful when:

- there is no Galois connection, or
- a full reduction exists but is expensive to compute.

Partial reduction example:

$$\rho(\mathcal{X}_1^\#, \mathcal{X}_2^\#) \stackrel{\text{def}}{=} \begin{cases} (\perp^\#, \perp^\#) & \text{if } \mathcal{X}_1^\# = \perp^\# \text{ or } \mathcal{X}_2^\# = \perp^\# \\ (\mathcal{X}_1^\#, \mathcal{X}_2^\#) & \text{otherwise} \end{cases}$$

(works on all domains)

For more complex examples, see [Blan03].

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